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ABSTRACT

A micro robot having a size of about 1cm^3 and capable of wireless control. This robot includes at least two sensors (12, 14) having detection regions thereof overlapping partially with each other, at least a pair of independently operated driving units (30, 28) having driving points spaced apart in a direction perpendicular to a moving direction, control units (40, 58, 60, 62) for controlling the driving units on the basis of the outputs of the sensors, and a rechargeable power supply portion (16) for supplying a power supply voltage to the sensors, the driving units and the control units. The control units and the power supply units are disposed between the driving units.

This Sheet Has Been Replaced

