

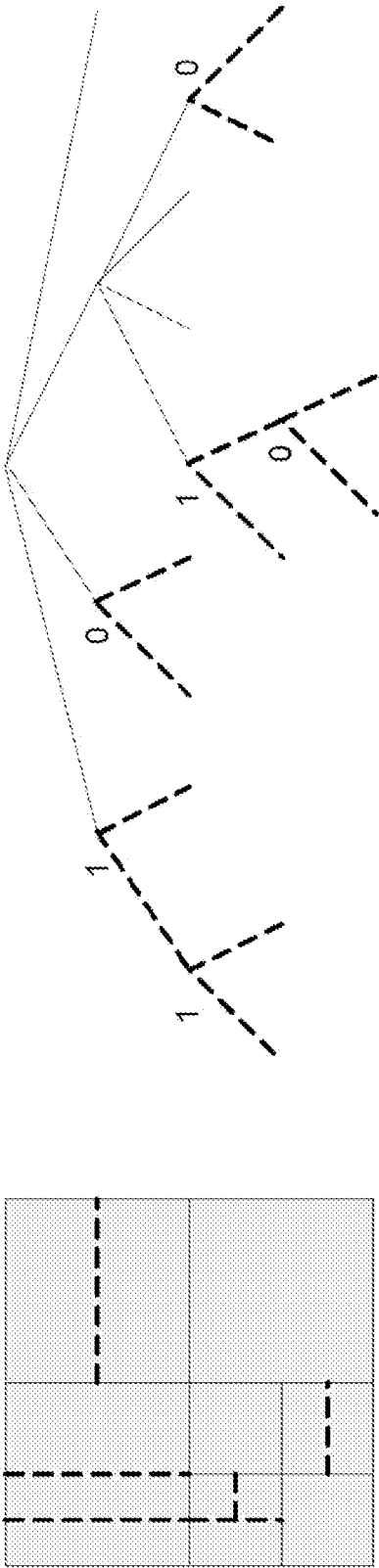
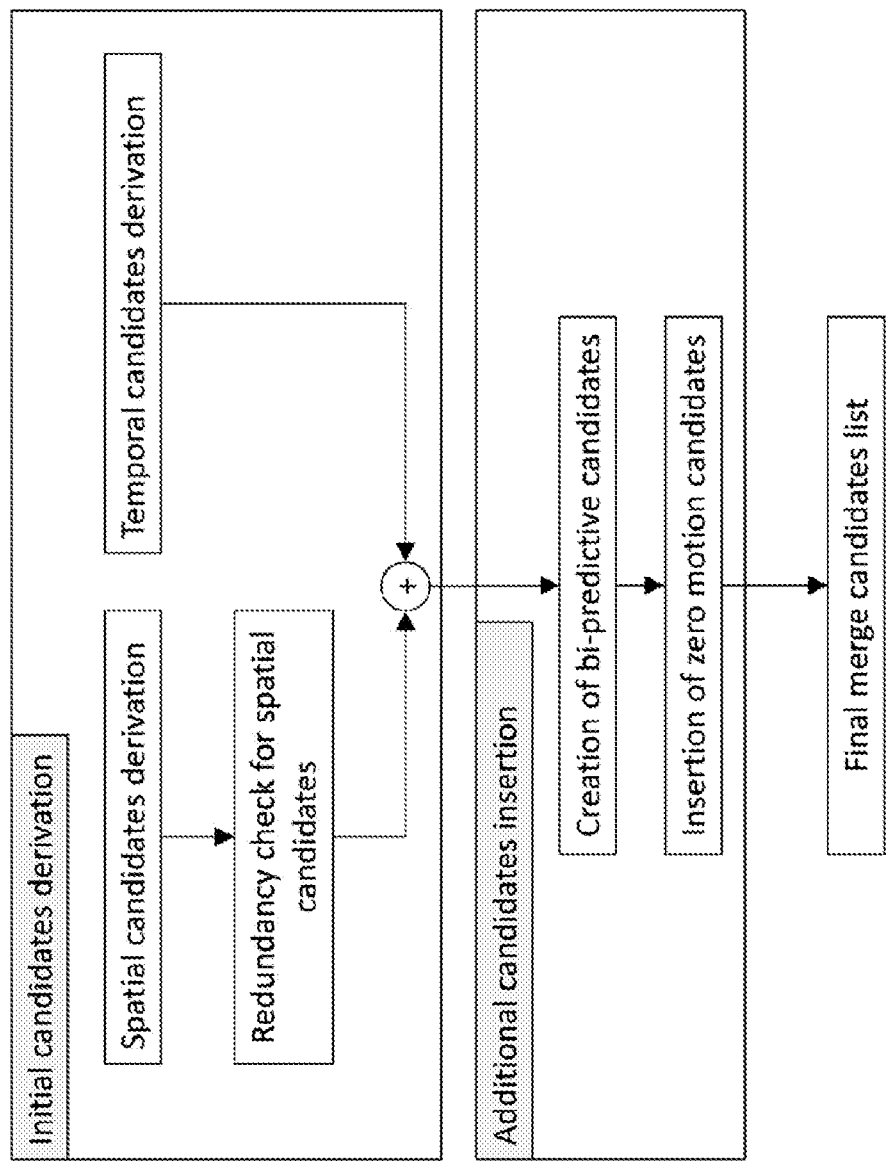


FIG. 1B

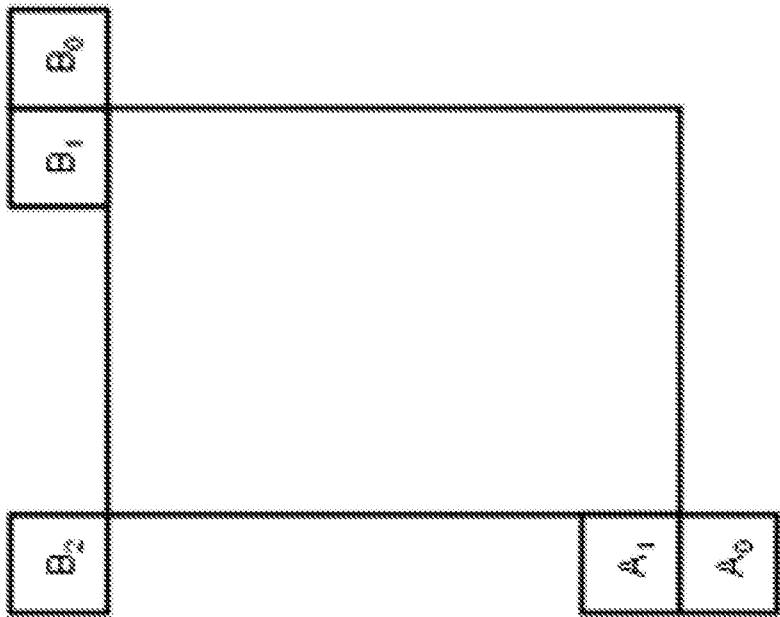
Illustration of a QTT structure

FIG. 1A



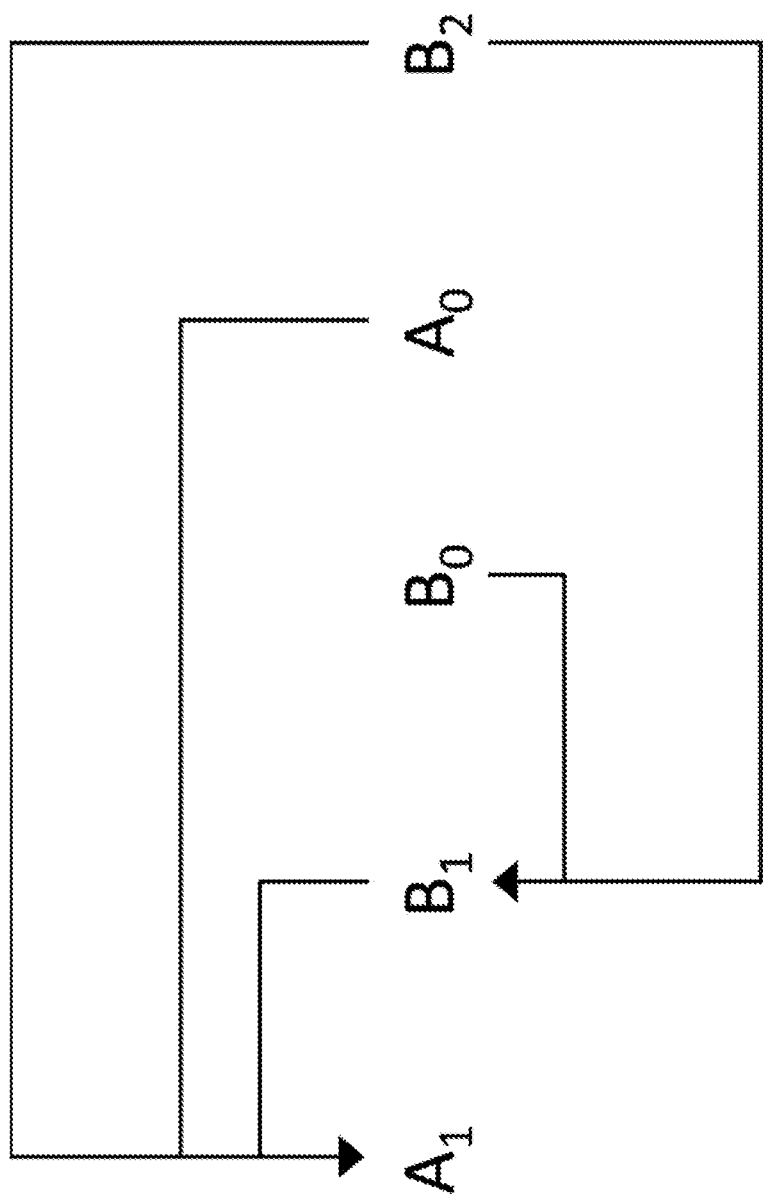
Derivation process for merge candidates list construction.

FIG. 2



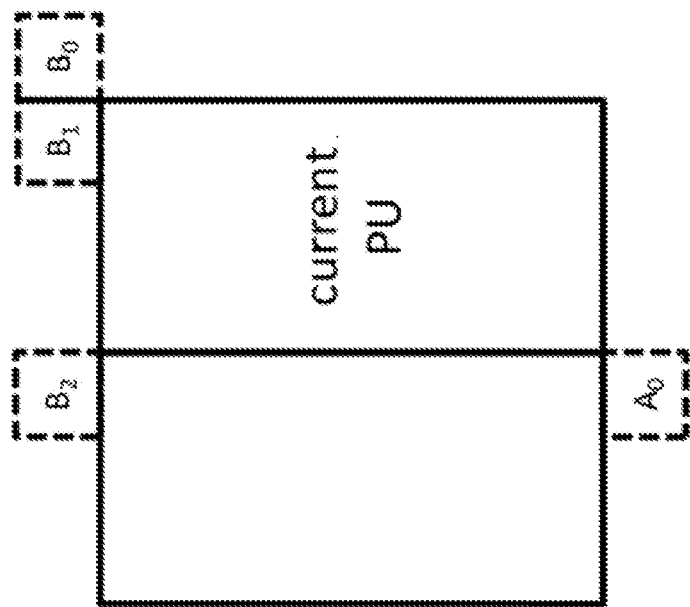
Positions of spatial merge candidates

FIG. 3



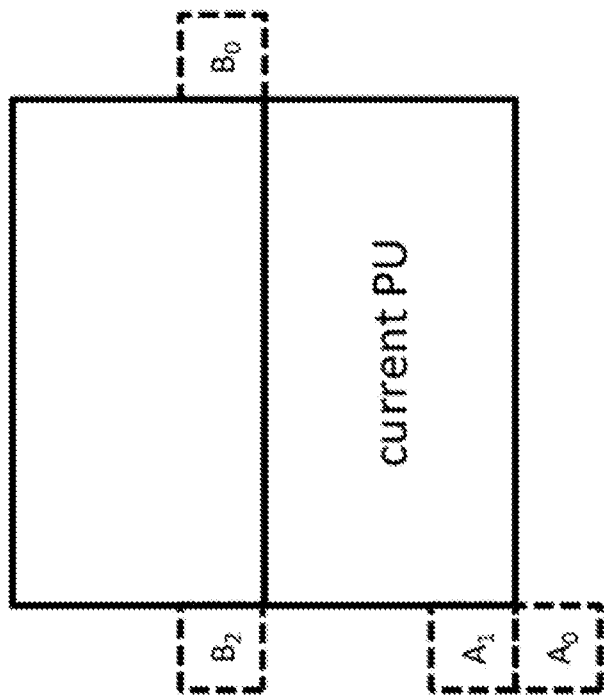
Candidate pairs considered for redundancy check of spatial merge candidates

FIG. 4



second PU of Nx2N

FIG. 5A



second PU of 2NxN

FIG. 5B

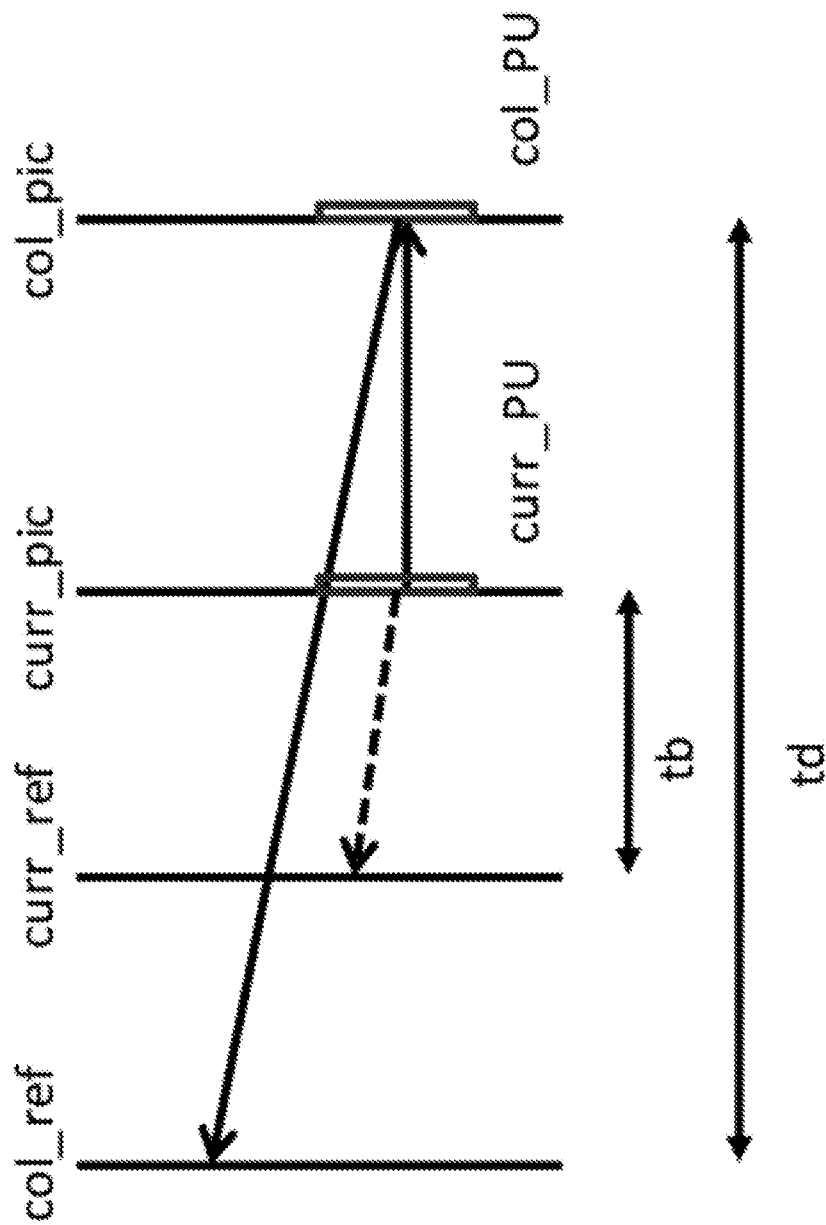
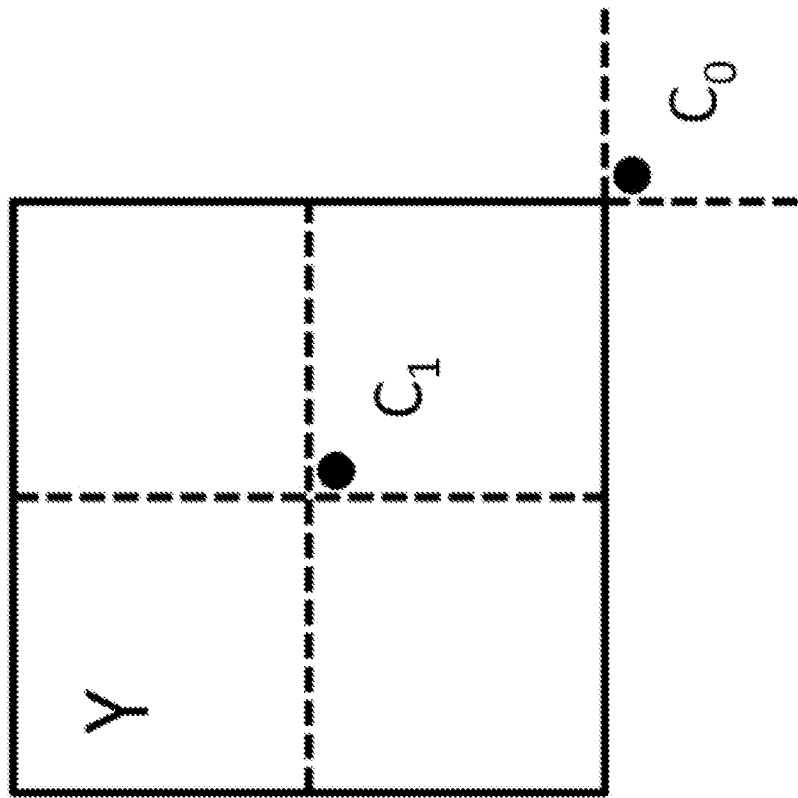


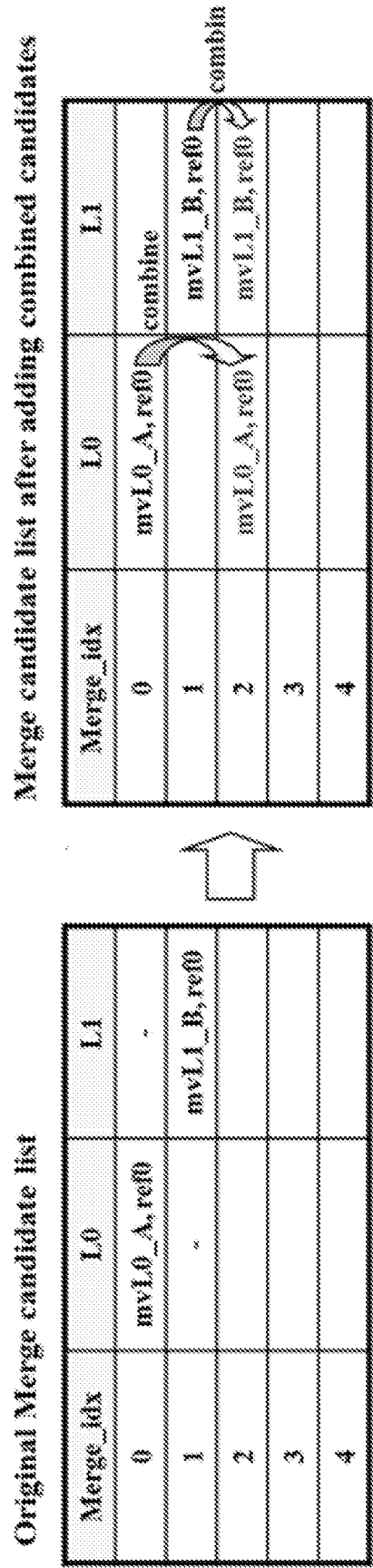
Illustration of motion vector scaling for temporal merge candidate

FIG. 6



Candidate positions for temporal merge candidate, C0 and C1

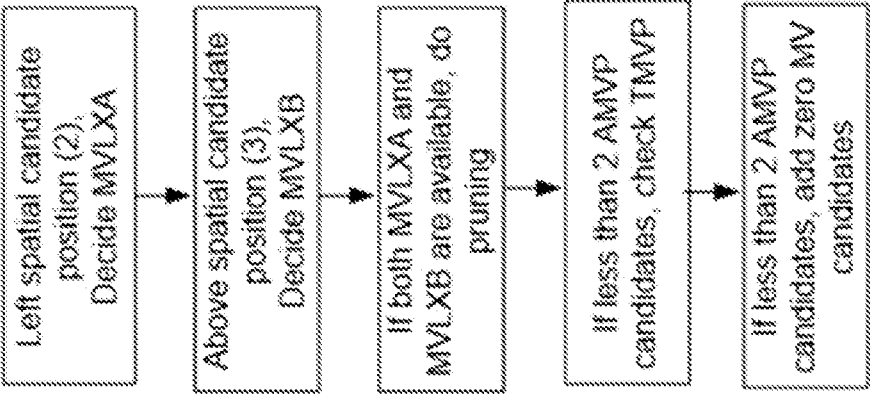
FIG. 7



Example of combined bi-predictive merge candidate

FIG. 8

For each reference picture list with refidx as an input



Derivation process for motion vector prediction candidates

FIG. 9

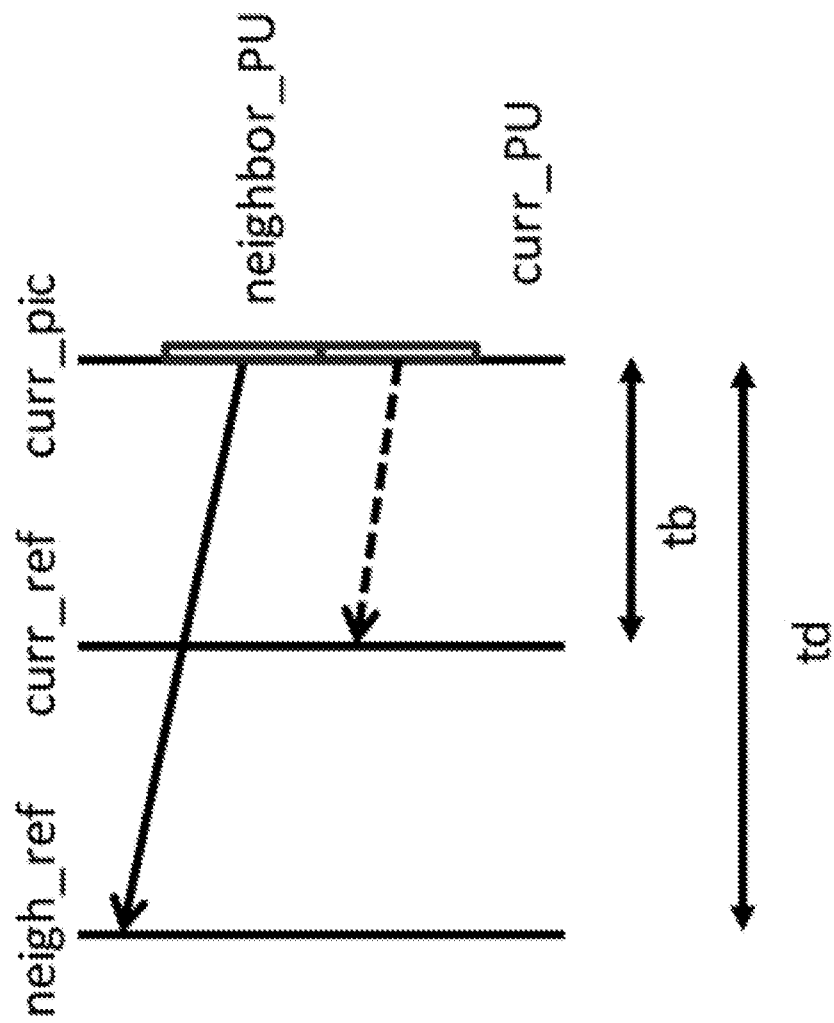


Illustration of motion vector scaling for spatial motion vector candidate

FIG. 10

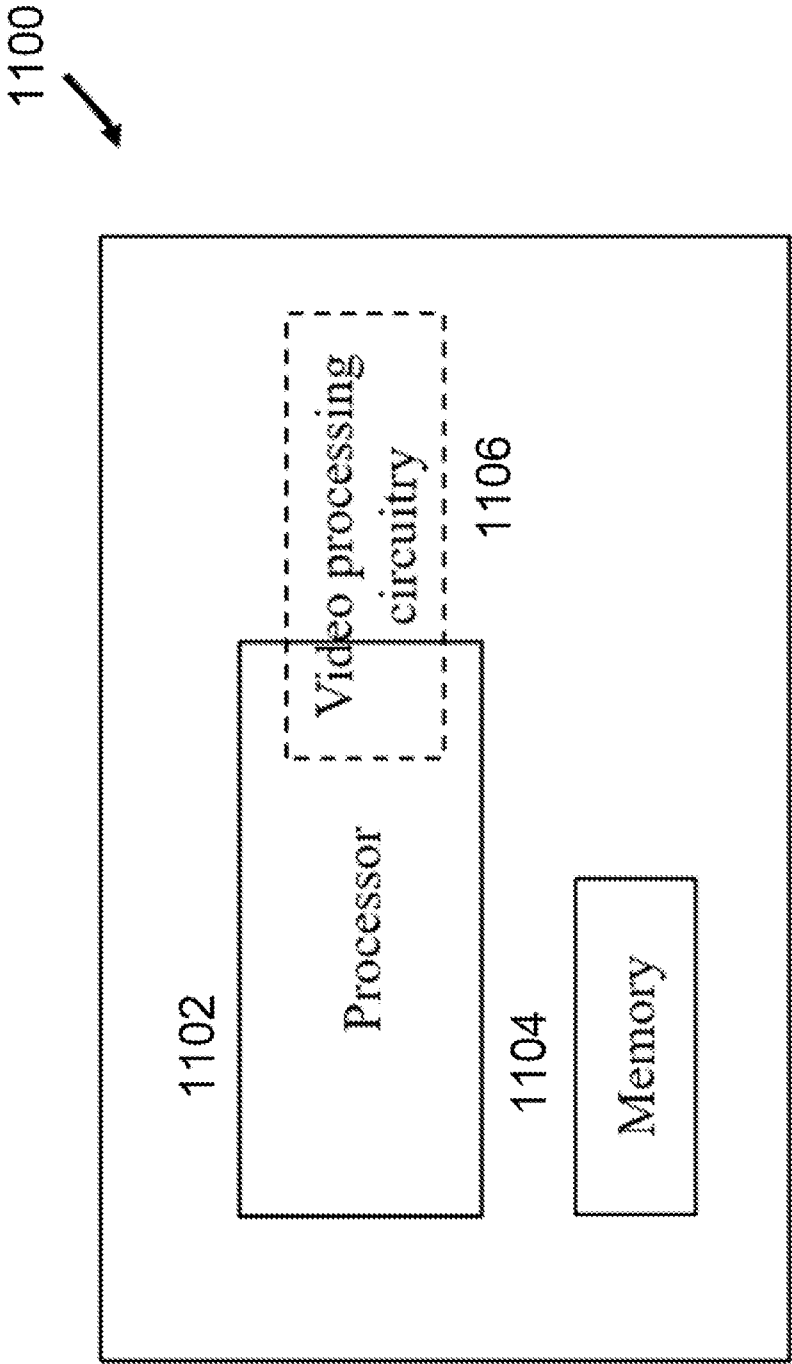


FIG. 11A

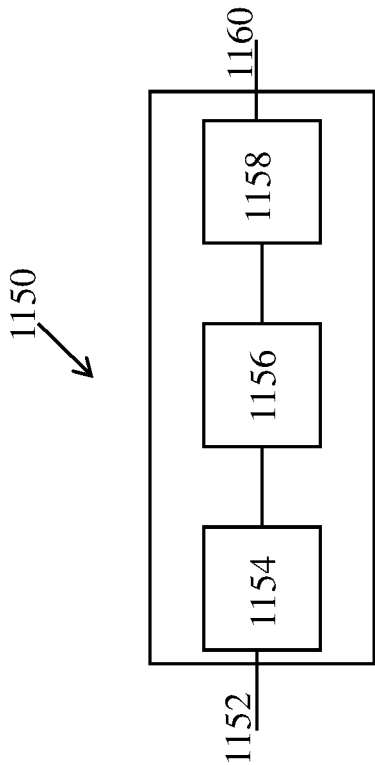
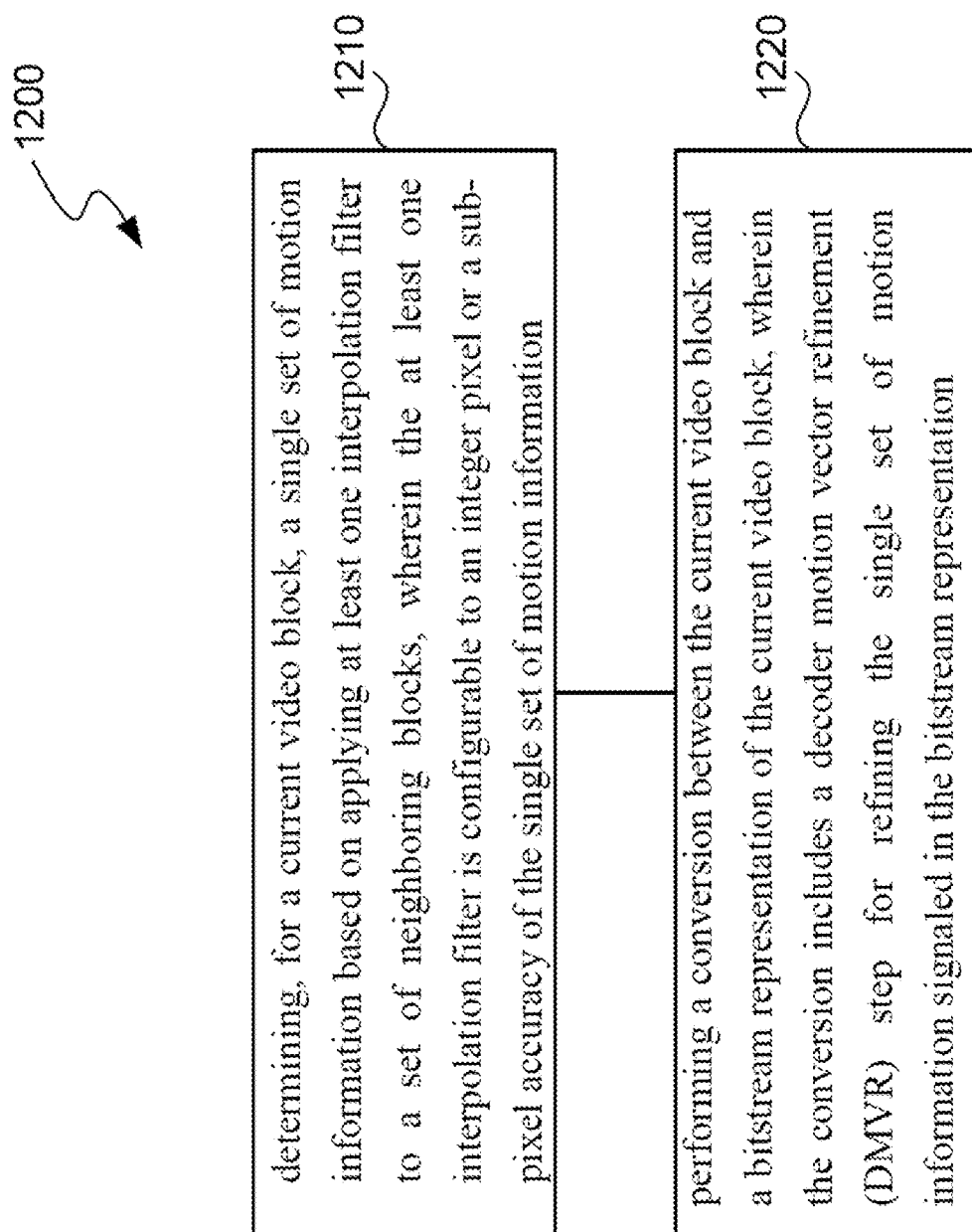


FIG. 11B

**FIG. 12**

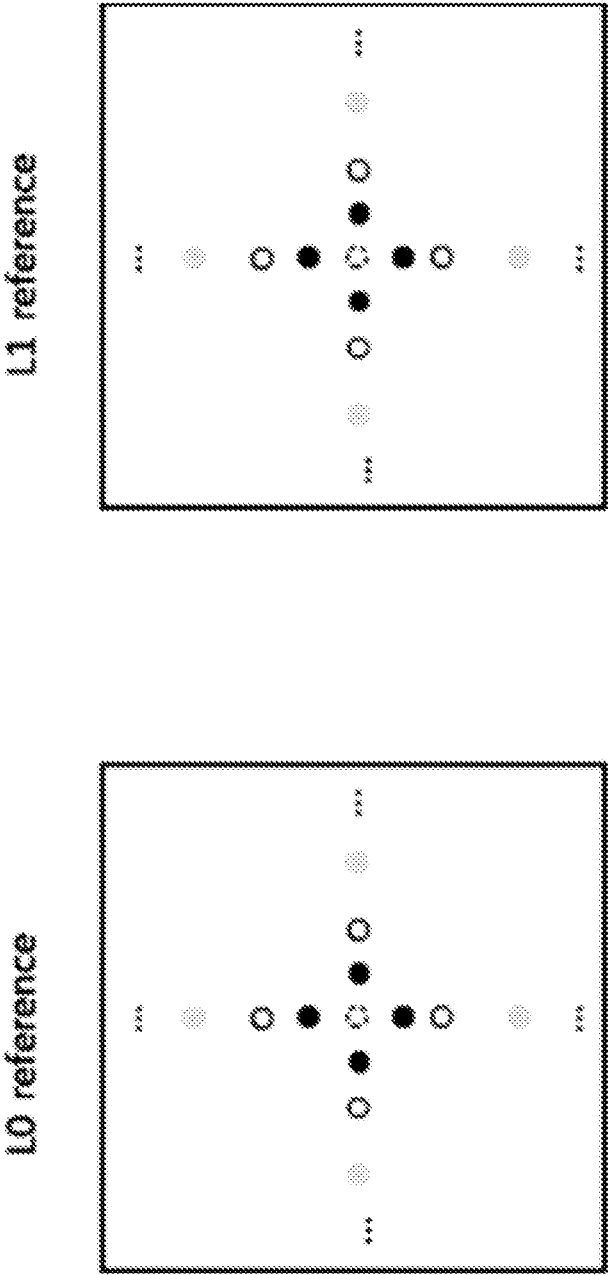


FIG. 13

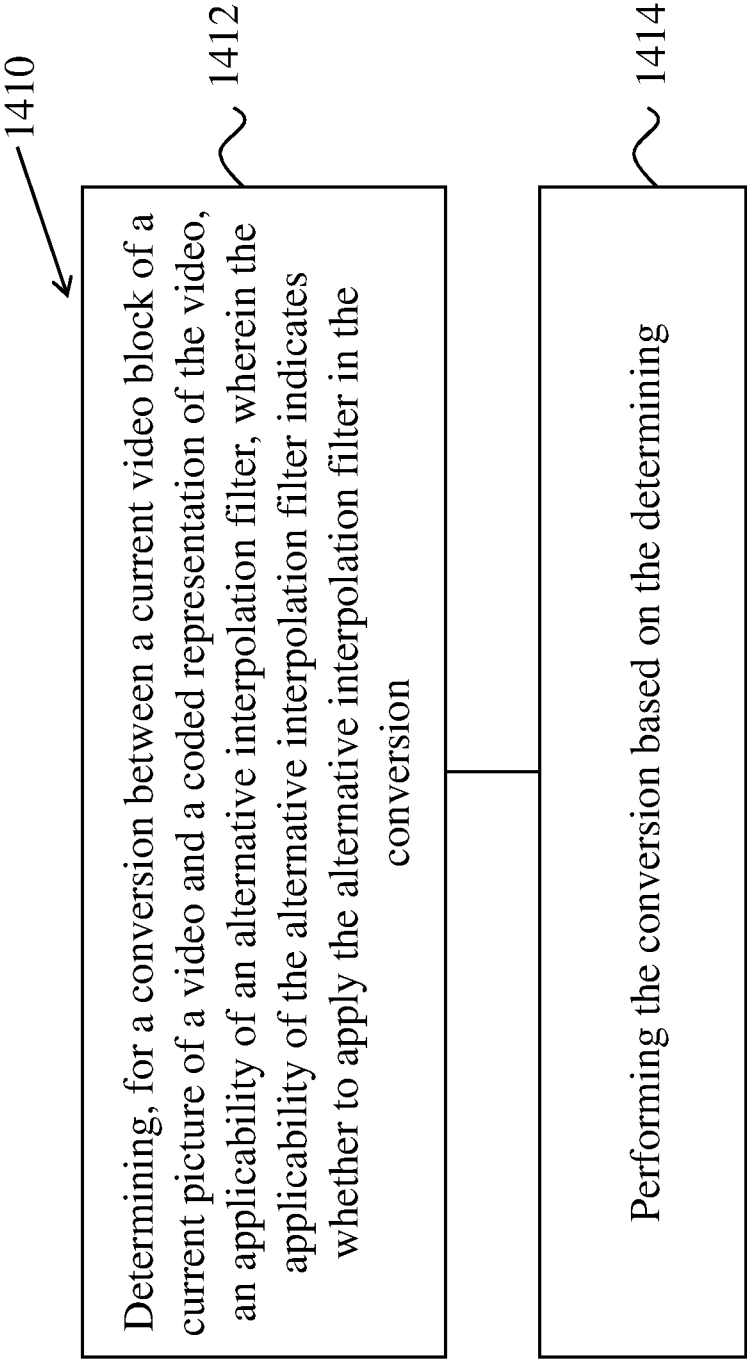


FIG. 14A

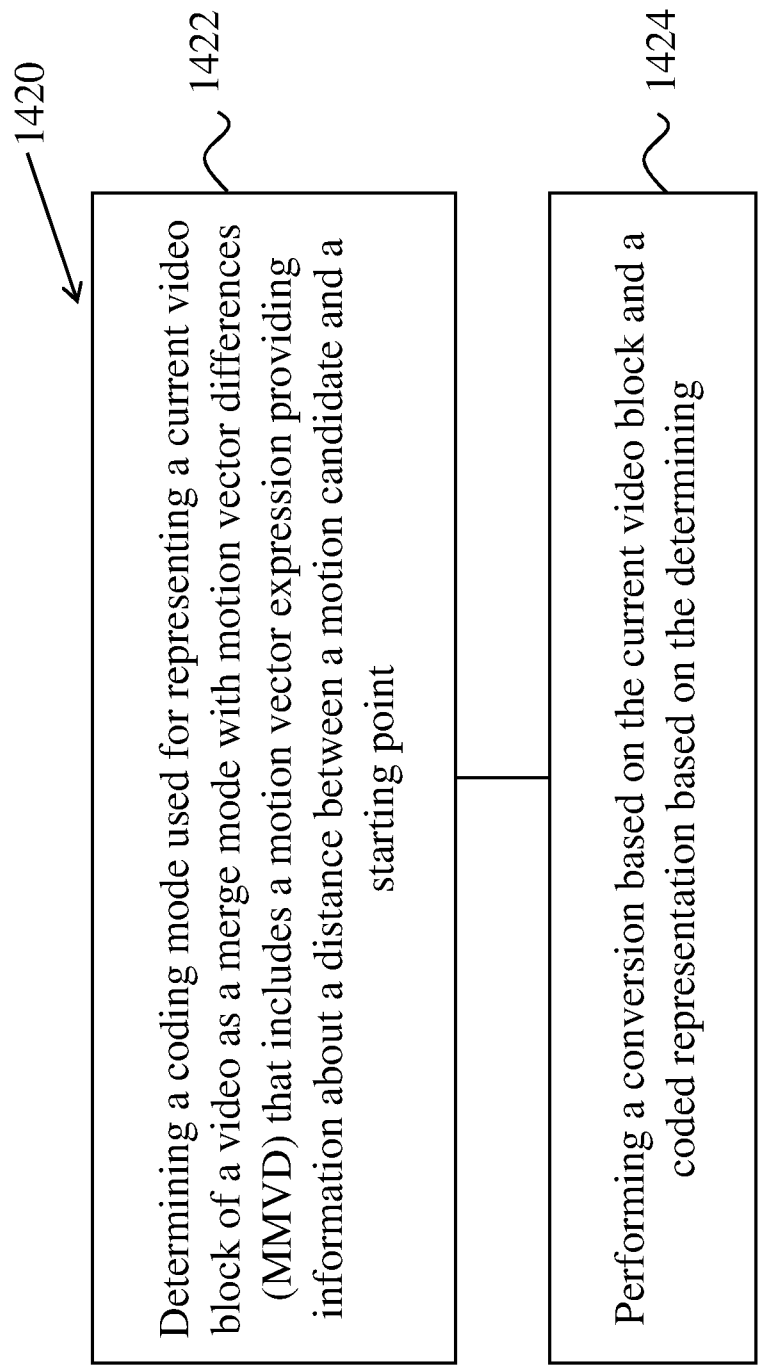


FIG. 14B

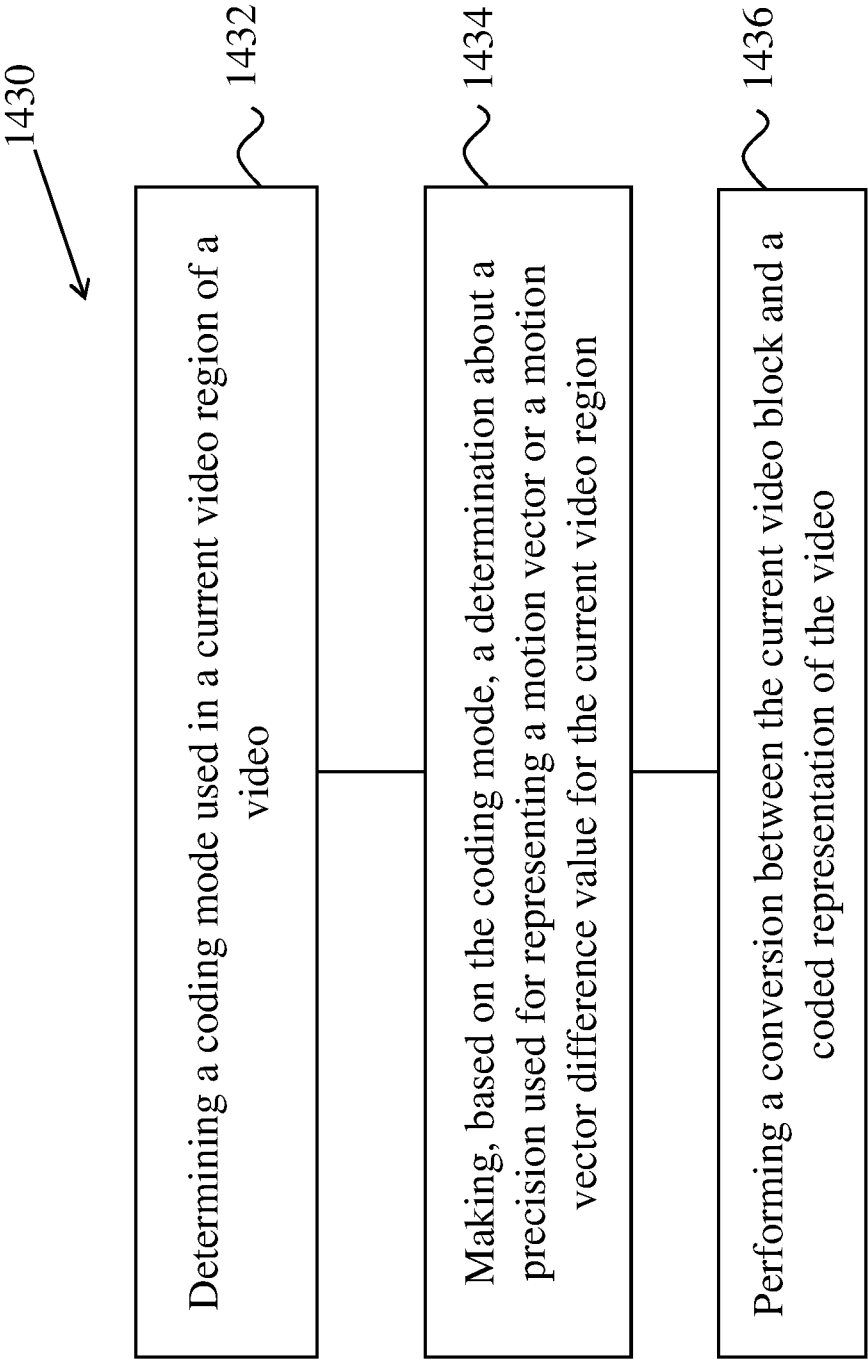
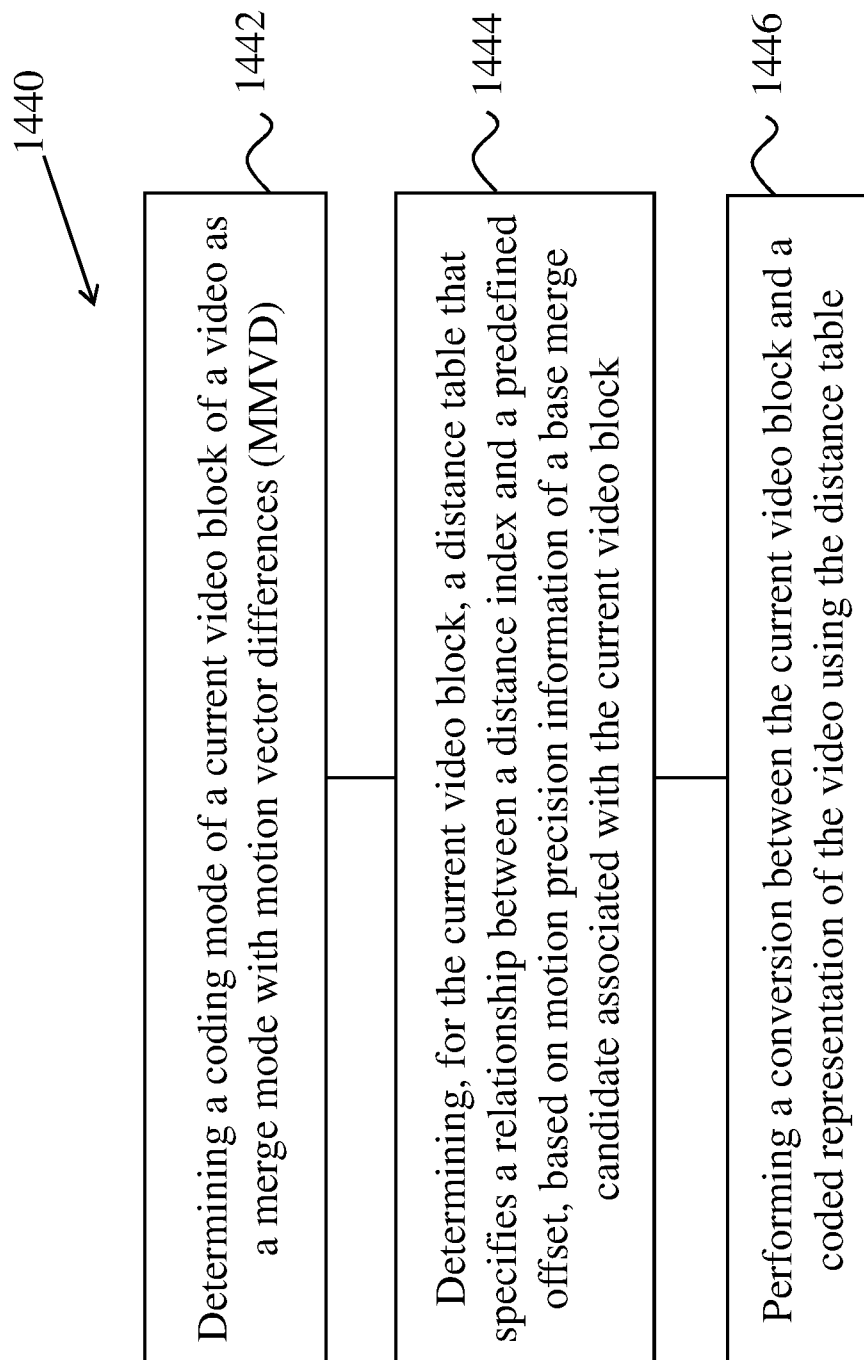
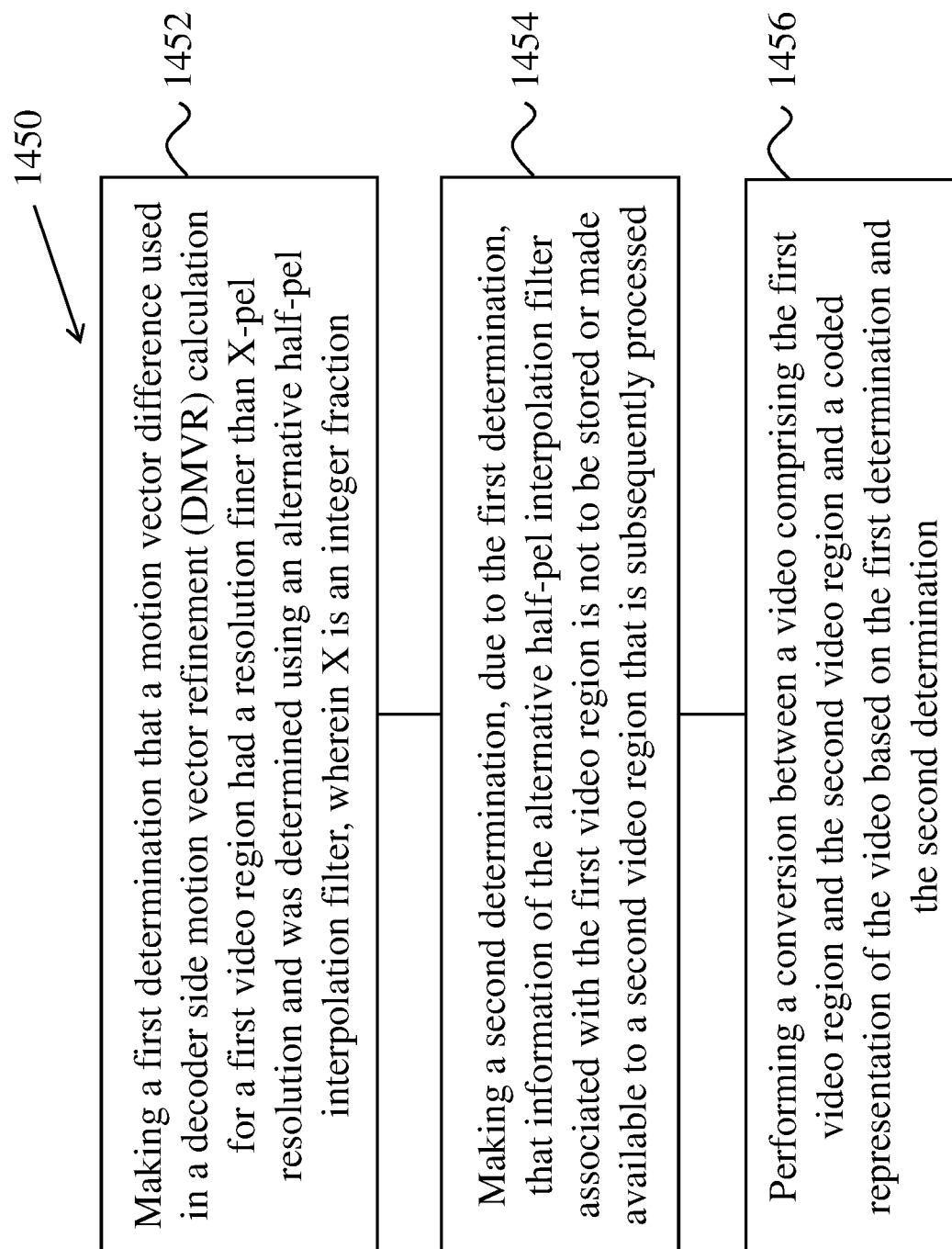
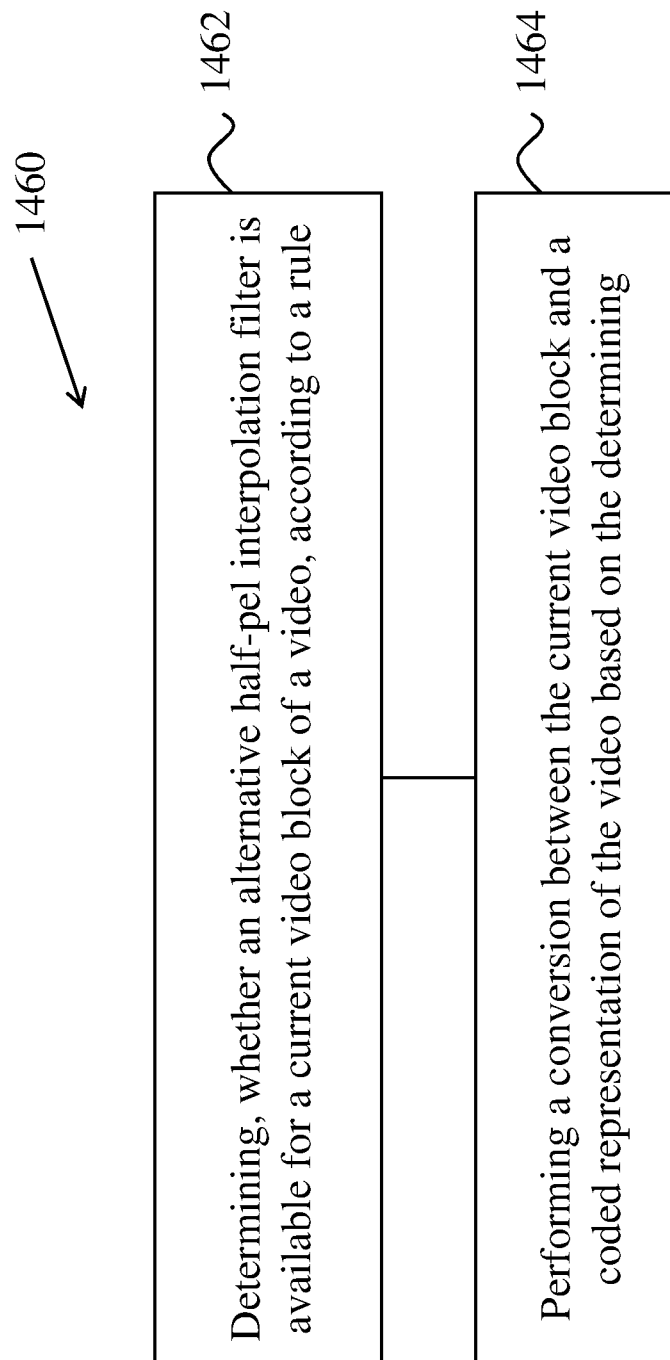


FIG. 14C

**FIG. 14D**

**FIG. 14E**

**FIG. 14F**

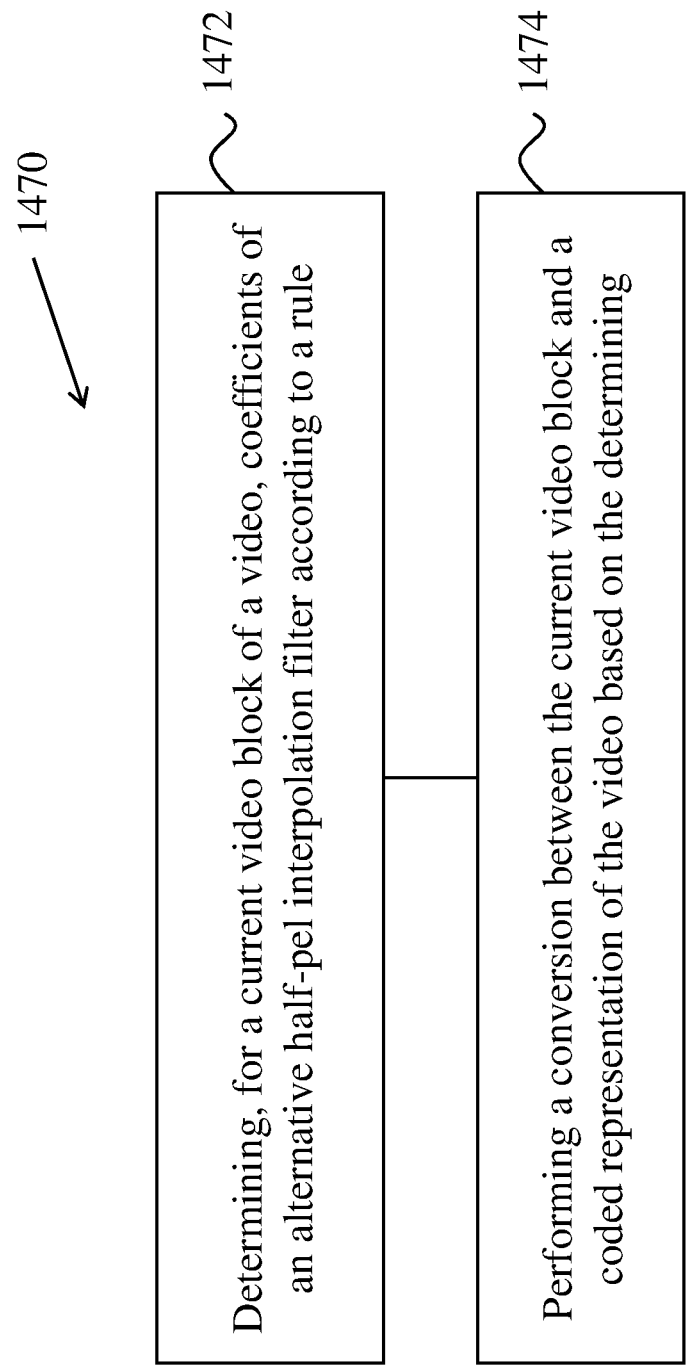


FIG. 14G

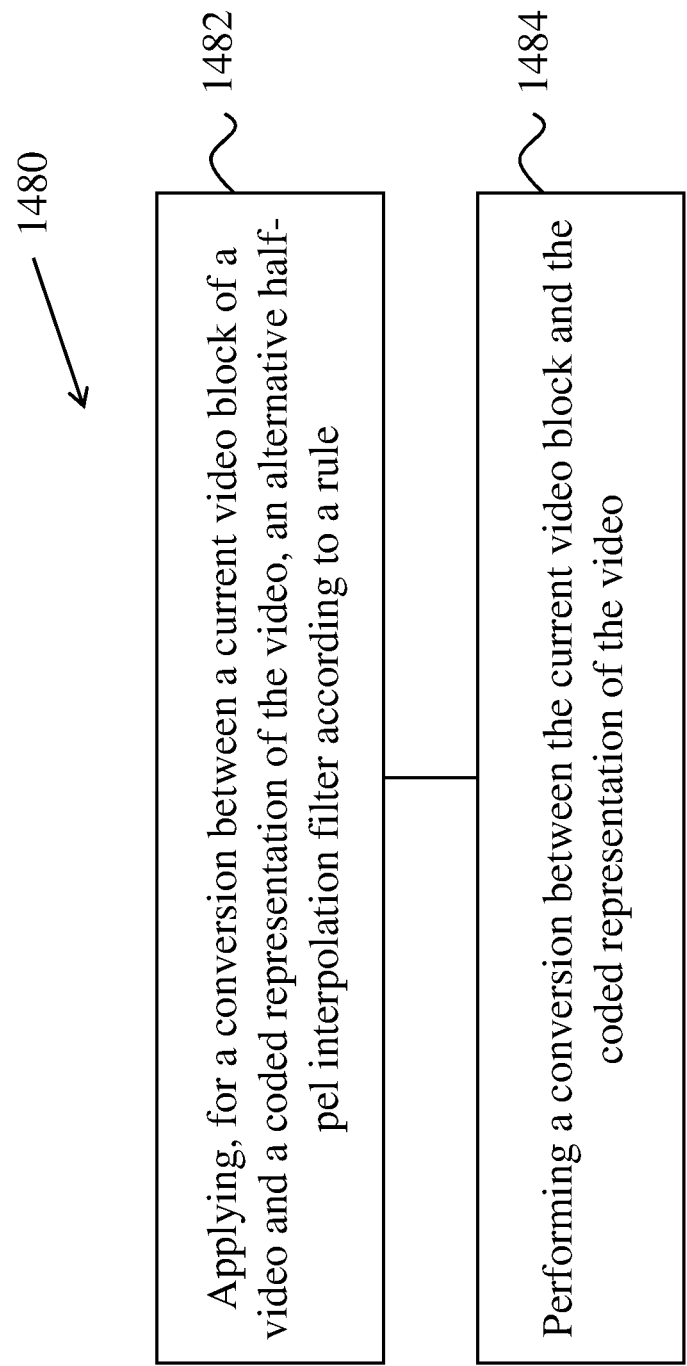
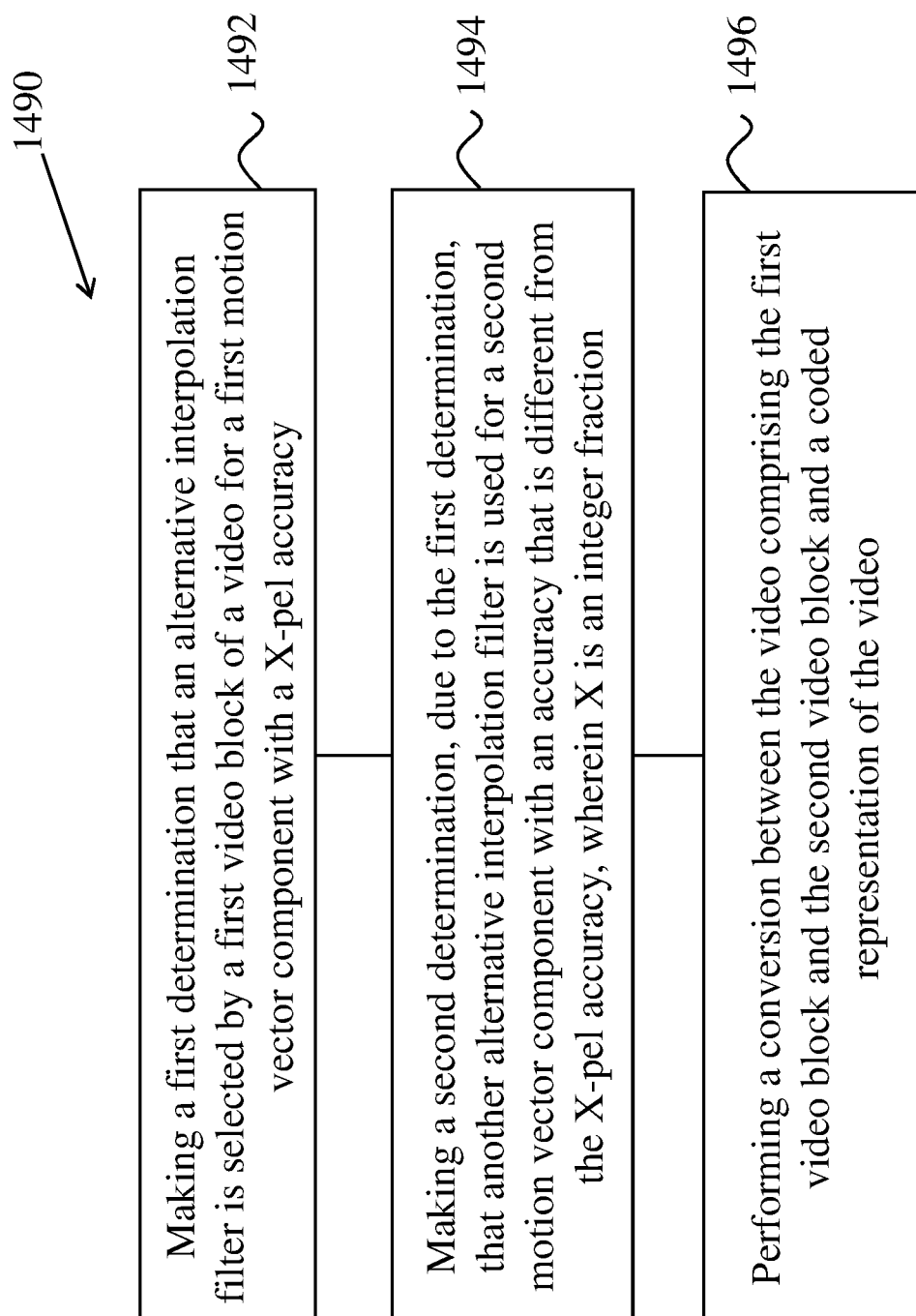


FIG. 14H

**FIG. 14I**