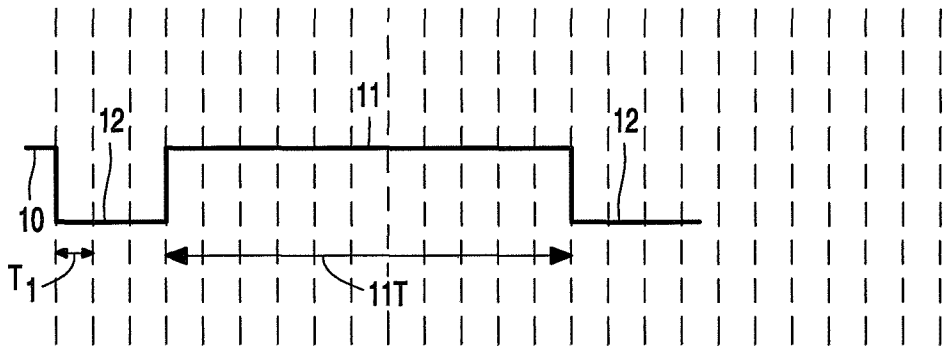


FIG. 1a

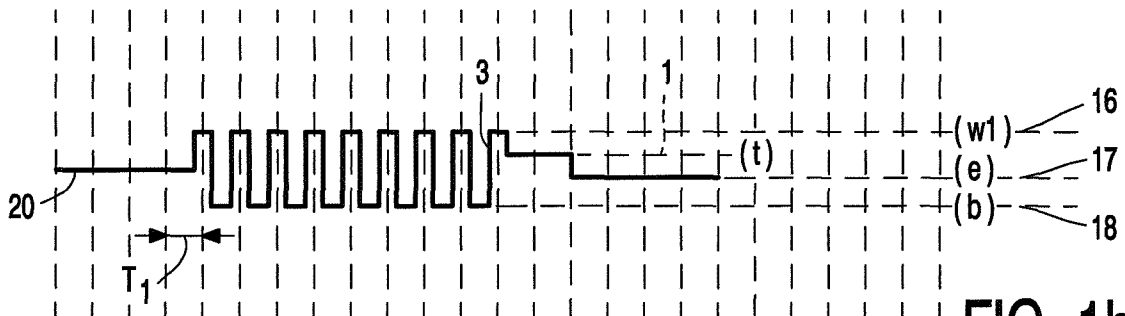


FIG. 1b

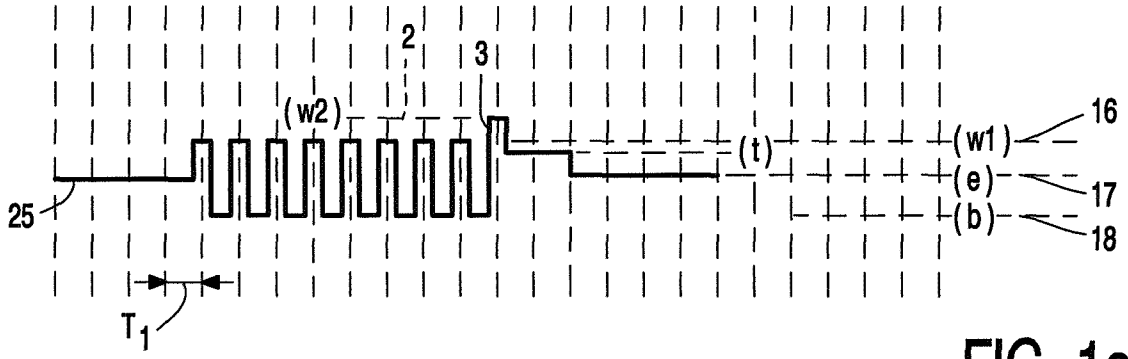


FIG. 1c

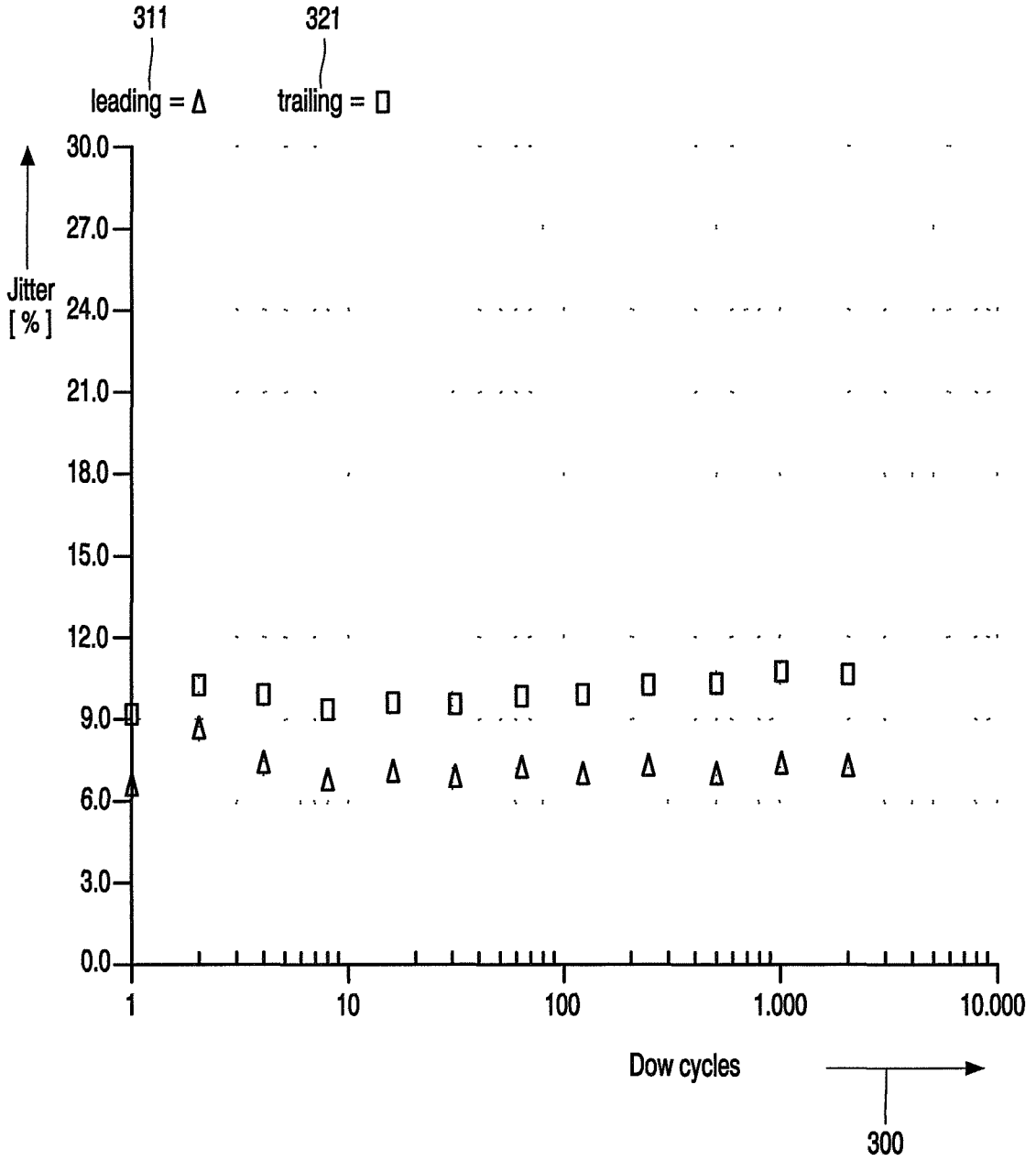

311
321
leading = Δ
trailing = □
Jitter [%]
30.0
27.0
24.0
21.0
18.0
15.0
12.0
9.0
6.0
3.0
0.0
1
10
100
1.000
10.000
Dow cycles
300

FIG. 2a

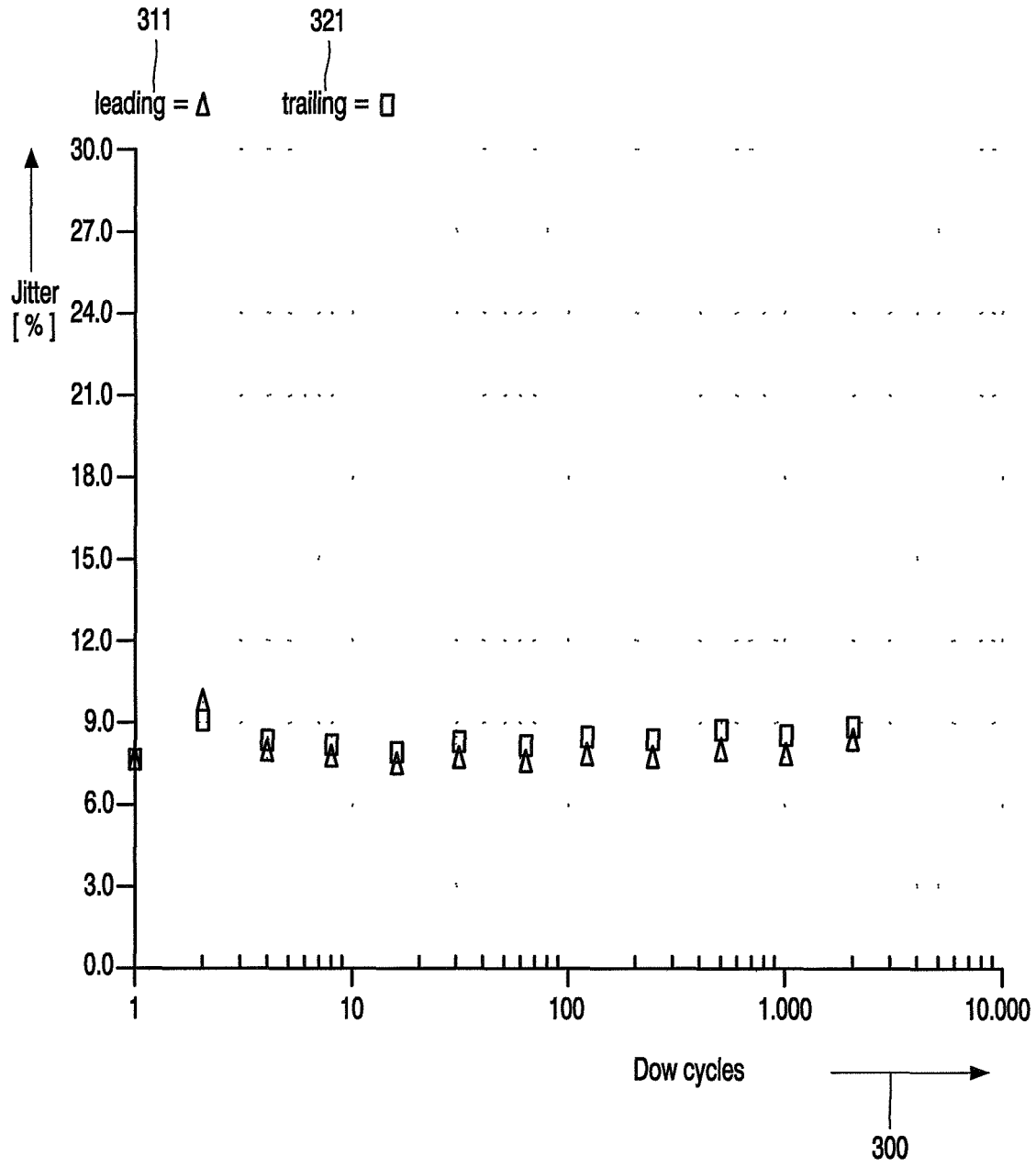

311
321
leading = Δ
trailing = □
Jitter
[%]
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27.0
24.0
21.0
18.0
15.0
12.0
9.0
6.0
3.0
0.0
1
10
100
1.000
10.000
Dow cycles
300

FIG. 2b

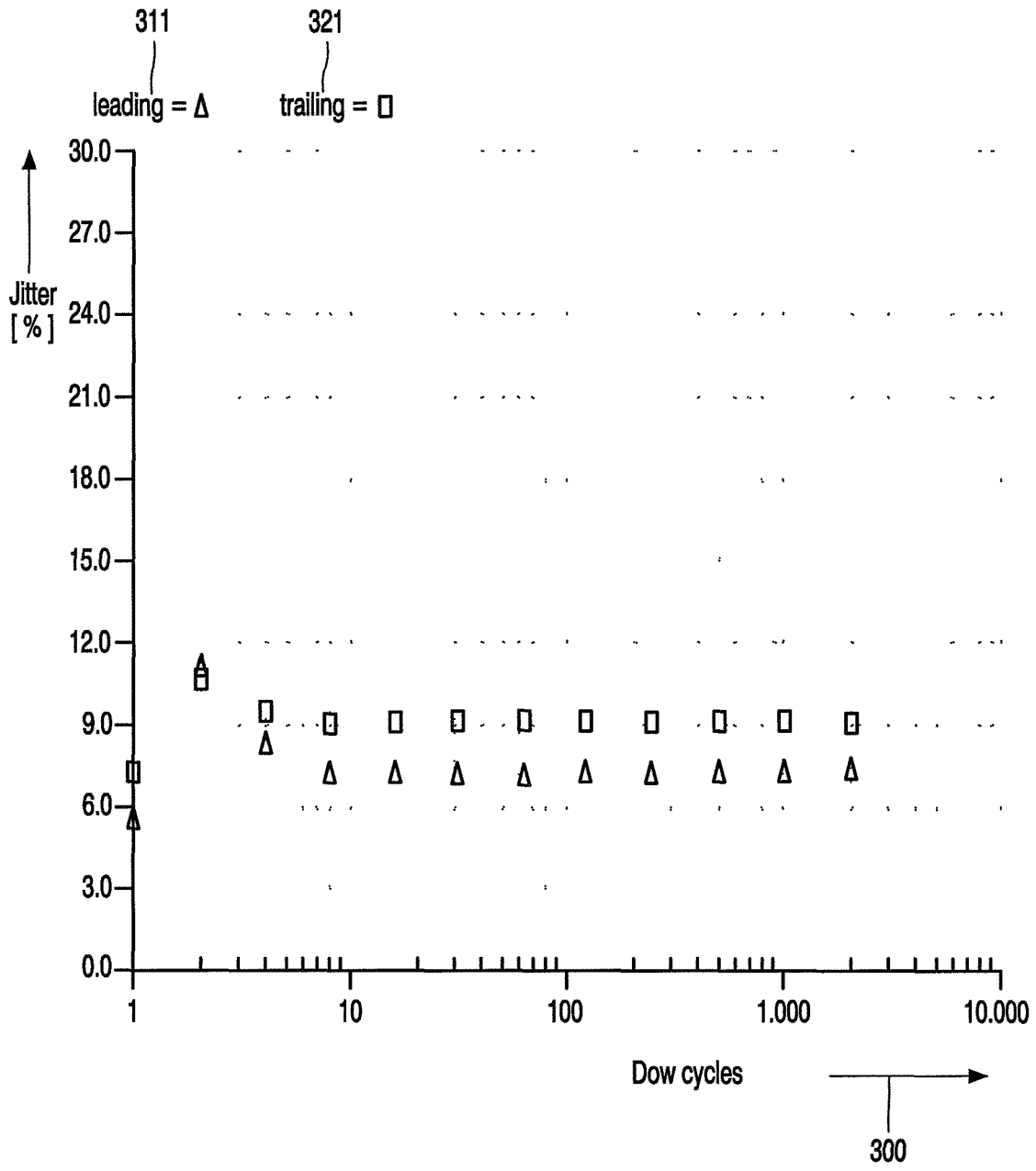

311
321
leading = Δ
trailing = □
Jitter [%]
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27.0
24.0
21.0
18.0
15.0
12.0
9.0
6.0
3.0
0.0
1
10
100
1.000
10.000
Dow cycles
300

FIG. 3a

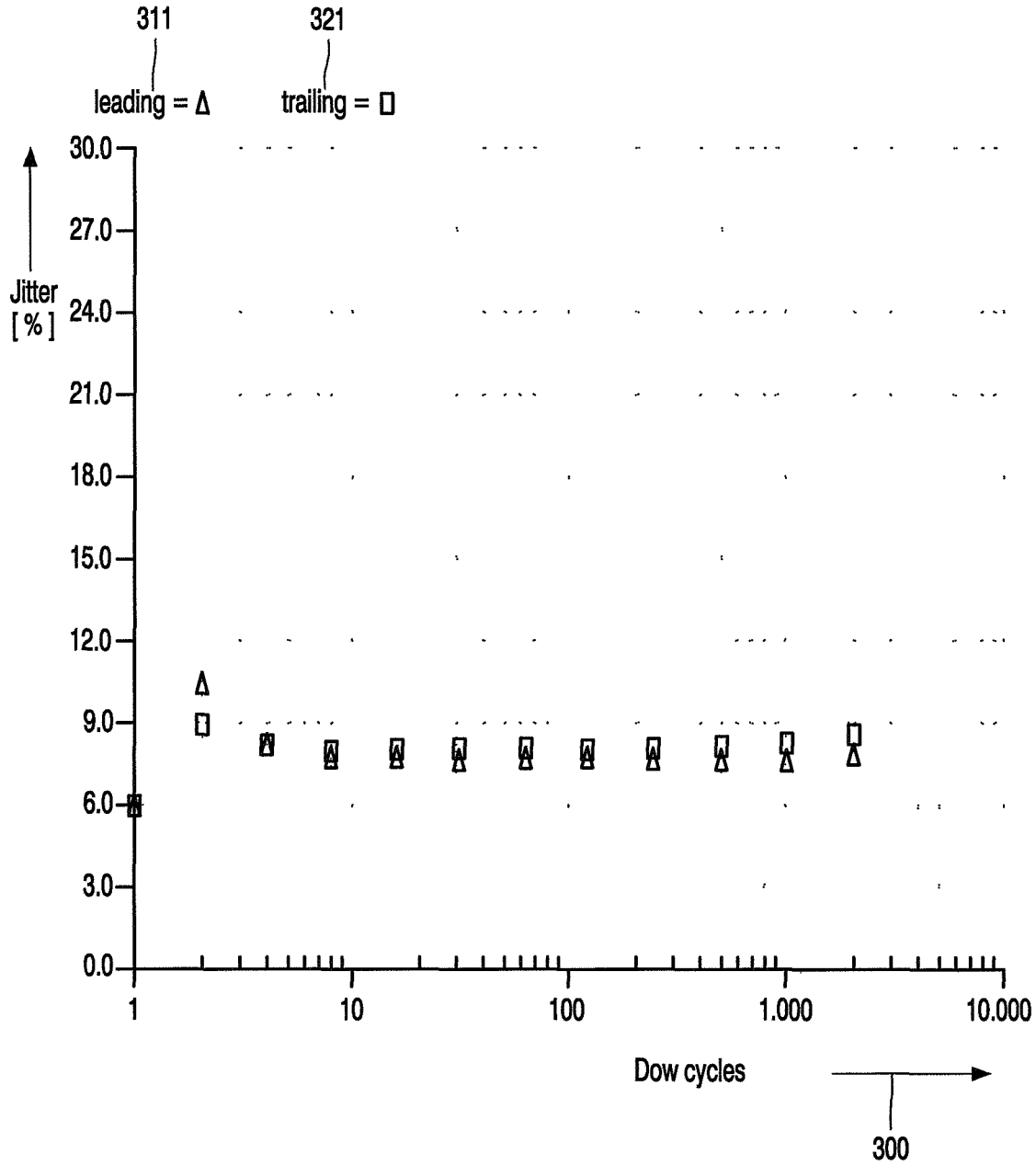

311
321
leading = Δ
trailing = □
Jitter [%]
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24.0
21.0
18.0
15.0
12.0
9.0
6.0
3.0
0.0
1
10
100
1.000
10.000
Dow cycles
300

FIG. 3b

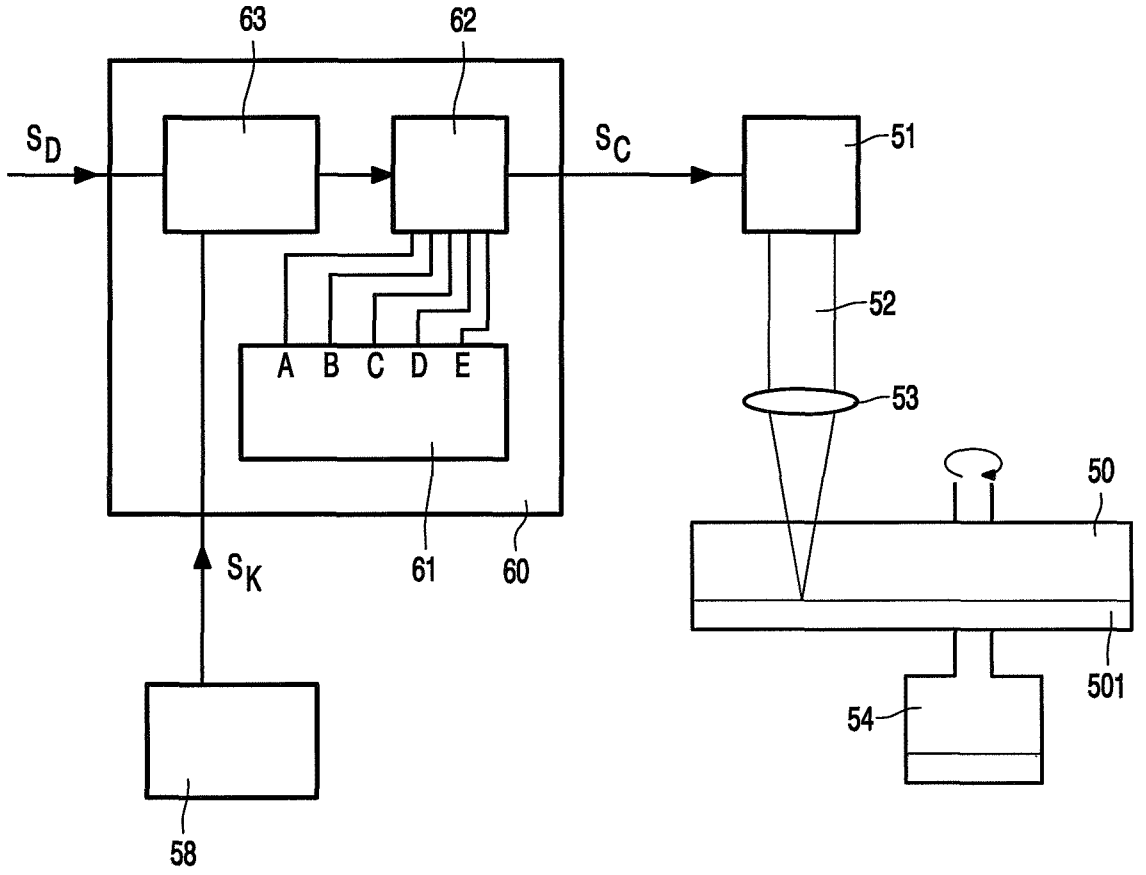


FIG. 4