CLAIMS

1. A method comprising:

receiving, at a computing system, an image of an interior of a vehicle, wherein the image is received from a camera positioned inside the vehicle, and wherein the computing system is positioned remotely from the vehicle and accessible by an operator to provide assistance to a plurality of vehicles;

displaying, by the computing system on a graphical user interface, the image with a request to determine whether the interior of the vehicle includes an object left behind by a passenger;

receiving, by the computing system, confirmation that the interior of the vehicle lacks the object; and

providing, by the computing system to a vehicle computing system of the vehicle, the confirmation that the interior of the vehicle lacks the object, wherein the vehicle computing system is configured to execute an autonomous operation in response to receiving the confirmation, and

wherein displaying the image with the request to determine whether the interior of the vehicle includes the object comprises:

displaying the image with text conveying a natural language question that requests for confirmation or denial that the interior includes the object left behind by the passenger.

2. The method of claim 1, wherein providing the confirmation that interior of the vehicle lacks the object further comprises:

providing instructions to proceed with navigation.

3. The method of claim 1, further comprising:

receiving an indication that the interior of the vehicle includes one or more objects; and

providing the indication that the interior of the vehicle includes the one or more objects to the vehicle computing system of the vehicle.

4. The method of claim 3, wherein receiving the indication that the interior of the vehicle includes one or more objects comprising:

receiving an input that identifies a given object located in the interior of the vehicle; and

wherein providing the indication comprises:

providing instructions based on the identification of the given object.

5. The method of claim 1, further comprising providing instructions

that cause the vehicle to remain stationary until an indication that the vehicle has reached a desired occupancy is received.

6. The method of claim 1, wherein receiving the image of the interior of the vehicle comprises:

receiving a set of images of the interior of the vehicle.

7. The method of claim 1, further comprising:

receiving audio via a microphone positioned in the interior of the vehicle.

8. The method of claim 1, further comprising:

obtaining sensor data indicating the passenger exited the vehicle via a tactile sensor, wherein the tactile sensor is coupled to a seatbelt inside the vehicle.

9. The method of claim 1, further comprising:

displaying profile information for the passenger.

10. A system comprising:

a vehicle having a vehicle computing system;

a computing device positioned remotely from the vehicle and accessible by an operator to provide assistance to a plurality of vehicles, wherein the computing device is configured to:

receive an image of an interior of the vehicle, wherein the image is received from a camera positioned inside the vehicle;

display, on a graphical user interface, the image with a request to determine whether the interior of the vehicle includes an object left behind by a passenger wherein the image is displayed with text conveying a natural language question that requests for confirmation or denial that the interior includes the object left behind by the passenger:

receive confirmation that the interior of the vehicle lacks the object; and

provide, to a vehicle computing system of the vehicle, the confirmation that the interior of the vehicle lacks the object, wherein the vehicle computing system is configured to execute an autonomous operation in response to receiving the confirmation.

11. The system of claim 10, wherein the computing device is further configured to:

provide, to the vehicle computing system of the vehicle, instructions to proceed with navigation to a subsequent passenger.

12. The system of claim 10, wherein the computing device is further configured to:

receive an indication that the passenger exited the vehicle in addition to the image of the interior of the vehicle.

13. The system of claim 10, wherein the computing device is further configured to:

provide instructions that cause the vehicle to remain stationary until the computing device receives an indication that the vehicle has reached a desired occupancy.

14. A non-transitory computer readable medium having stored therein instructions executable by one or more processors to cause a computing system to perform functions comprising:

receiving an image of an interior of a vehicle, wherein the image is received from a camera positioned inside the vehicle, wherein the computing system is positioned remotely from the vehicle and accessible by an operator to provide assistance to a plurality of vehicles;

displaying, on a graphical user interface, the image with a request to determine whether the interior of the vehicle includes an object left behind by a passenger;

receiving confirmation that the interior of the vehicle lacks the object; and

providing, to a vehicle computing system of the vehicle, the confirmation that the interior of the vehicle lacks the object, wherein the vehicle computing system is configured to execute an autonomous operation in response to receiving the confirmation, and

wherein displaying the image with the request to determine whether the interior of the vehicle includes the object comprises:

displaying the image with text conveying a natural language question that requests

for confirmation or denial that the interior includes the object left behind by the passenger.

15. The method of claim 1, wherein receiving confirmation that the interior of the vehicle lacks the object comprises:

receiving an operator input that confirms the interior of the vehicle lacks the object.

16. The non-transitory computer readable medium of claim 14, wherein receiving conformation that the interior of the vehicle lacks the object comprises:

receiving an operator input that confirms the interior of the vehicle lacks the object.