What is claimed is:

1. A control system, applied to a behavioral control device of a home service robot, comprising:

a collection device configured on a preset position of the home service robot to collect operation instructions input by a user, and to form an output of collection data;

a communication module including a first communication unit and a second communication unit, the first communication unit being connected to the collection device to receive the collection data, and transforming the collection data to an output of collection data matched to the first communication unit;

a first processing unit connected to the first communication unit and the second communication unit respectively, to receive the collection data, and to analyse and process the collection data, to form a control command output by the second communication unit;

a second processing unit connected to the second communication unit to receive the control command output by the second communication unit, and to form an output of control instruction according to the control command output;

an execution unit connected to the second processing unit to execute one of more actions under effect of the control instruction;

a detecting unit connected to the second processing unit, to detect status information of the home service robot at a present physical environment, and to form a detection information and output to the second processing unit;

wherein the second processing unit comprises a memory unit, the memory unit comprising a plurality of preset scene modes and is configured to match a relationship between the preset scene modes and the status information of the home service robot at the present physical environment;

wherein the second processing unit sends the status information of the home service robot at the present physical environment, the control command output and the control instruction to the first processing unit by the second communication unit, the first processing unit analyzes the received data to form an analysis result to return to the second processing unit, wherein the first processing unit updates the relationship between the status information of the home service robot at the present physical environment in the memory unit and the preset scene modes according to the analysis result.

2. The control system as claimed in Claim 1, wherein the collection device comprises:

a sound capture module connected to the first communication unit to capture voice message, and to form an output of voice collection data matched to first communication unit format;

an image capture module connected to the first communication unit to capture image message, and to form an output of image collection data matched to the first communication unit format.

3. The control system as claimed in Claim 2, wherein the first processing unit comprises:

a voice recognition unit connected to the sound capture module to recognize voice control command according to the voice collection data;

an image recognition unit connected to the image capture module to recognize image control command according to the image collection data.

4. The control system as claimed in Claim 1, wherein the detecting unit comprises:

a temperature sensor connected to the second processing unit, to acquire temperature information of the present physical environment, and to form a temperature signal and output to the second processing unit;

a light sensor connected to the second processing unit, to acquire light information of the present physical environment, and to form a light signal and output to the second processing unit;

a displacement sensor connected to the second processing unit, to acquire position information of the present physical environment, and to form a position signal and output to the second processing unit.

5. The control system as claimed in Claim 1, wherein the execution unit comprises:

an audio play unit connected to the second processing unit to execute an action of audio play under an effect of the control instruction which is output by the second processing unit and which is relevant to the audio play unit;

a light regulation unit connected to the second processing unit to execute an action of light regulation under an effect of the control instruction which is output by the second processing unit and which is relevant to the light regulation unit;

a drive unit connected to the second processing unit to execute an action of position movement under an effect of the control instruction which is output by the second processing unit and which is relevant to the drive unit.

6. The control system as claimed in Claim 5, wherein the audio play unit is an audio play device inside the home service robot or an audio play device in the present physical environment where the home service robot is located, whose control end is connected to a corresponding output end of the second processing unit.

7. The control system as claimed in Claim 5, wherein the light regulation unit is a lighting system in the present physical environment where the home service robot is located, whose control end is connected to a corresponding output end of the second processing unit, which is configured to regulate light intensity of the present physical environment.