

ABSTRACT

A spraying robot, a control method, and a computer readable storage medium. The spraying robot (100) comprises a frame body (1), a first lifting mechanism (2), a lifting motor (3), and a spraying gun (4); a lifting channel (12) is provided inside the frame body (1); the first lifting mechanism (2) is provided inside the lifting channel (12); a first portion of the first lifting mechanism (2) is fixedly connected to the frame body (1); the lifting motor (3) is connected to the first lifting mechanism (2) in a transmission manner, so that under the driving of the lifting motor (3), the first lifting mechanism (2) moves in the lifting channel (12); the spraying gun (4) is provided in a second portion of the first lifting mechanism (2); wherein the first portion and the second portion are provided on both sides of the first lifting mechanism (2).