

Abstract

Method and system for operating an automatically guided transport vehicle for containers

The invention relates to a method for operating an automatically guided transport vehicle (1) for containers (12), which can be automatically guided during forward driving and during rearward driving, and comprises a towing vehicle (1a) and a trailer (1b) with a loading surface (11) for at least one container (12). The transport vehicle (1), particularly the towing vehicle (1a), has a vehicle control system (13) for controlling a steering system and a travel drive of the transport vehicle (1) in such a way that the transport vehicle (1) follows a nominal route. The aim of the invention is to improve such a method. To this end the nominal route is automatically pre-defined taking into account a trajectory of the transport vehicle. The invention also relates to a system for operating an automatically guided transport vehicle (1) operating according to such a method.

Fig. 2