

Description

The invention relates to a vibration damper as defined in the precharacterizing part of claim 1 and as disclosed in DE-A-3334649. In this prior art vibration damper the plate elements are rigid covers that are able to distribute loads over a continuous intermediate elastomeric layer from which elastomeric bodies protrude towards both the plate elements. The intermediate layer is connected to the plate elements by clamping along the edges.

There are also known vibration dampers in the form of a laminate of, for example, felt, rubber, cork, nylon, polyurethane foam, hard foam and similar materials, in different combinations. The object of such laminates is to make use of the self-damping properties of the different materials and by combining these obtain optimum damping characteristics for a particular application.

A disadvantage of laminates is that their manufacture is complicated because a good bond between the component layers is required. Another disadvantage of laminates is that, in order to change their characteristics, for example for adaptation to a change in occurring vibrations, the entire laminate must be replaced by another laminate.

There are also known vibration dampers which are formed at least partly by a vibration damping plate of self damping material which on both sides has projecting studs with flat support faces parallel to the plate surfaces. Such self-damping plate material is known from Dutch patent No. 128,238.

In this known material, marketed under the name of RUBLOC®, the studs are arranged in groups, each group comprising a series of studs with different heights and/or different diameters. Equal studs on opposite sides of the plate are off-set relative to one another.

The working principle of the RUBLOC® material is that as the strength of the vibrations generated by an apparatus which is supported by a layer of such damping material increases, more studs become involved in the vibration damping, thus achieving a progressive damping. By means of the off-set position of equal studs on opposite sides of the plate it is achieved that vibrations are not transferred perpendicularly to the plate from one stud to an opposite stud, but are forced to follow a longer, sloping or bent path, which extends partly horizontally through the web of the plate. Since the studs carrying an object can also deflect laterally, an object supported by a RUBLOC® plate is prevented from slipping laterally.

A general observation with regard to the RUBLOC® vibration damper is that interengaging parts of successive plates, or parts of the RUBLOC® vibration damper engaging objects to be insulated, which are supported by the vibration damper, interengage through flat surfaces, such as the end faces of the

studs.

The present invention relates to a vibration damper, exclusively comprising elastomeric parts without metal elements, in which the disadvantages of laminates mentioned above are avoided, and in which the self-damping properties of rubber or like elastomeric material can be used in the same way as in the RUBLOC® material, i.e., that with increasing vibratory load more self-damping material becomes involved in the vibration damping.

The vibration damper according to the invention comprises the features cited in claim 1.

In this way layers of preferably interconnected elastomeric bodies can be exchangeably sandwiched between plate elements, and the assembly of these internal bodies and the two plate elements forms a layered, plate-shaped vibration damper, comparable to a laminate, of which the components, however, are easily exchangeable. Elastomeric bodies can be replaced by elastomeric bodies with a different shape and/or a different hardness to adapt to vibrations with a changed intensity and/or frequency. To facilitate handling the elastomeric bodies they may be interconnected to form a mat by means of a thin layer of material or thin strips which do not influence the deforming behaviour of the separate elements.

Apart from the exchangeability of the layer of internal elastomeric bodies the energy-absorbing capacity of the elastomeric bodies is utilized more effectively than with known laminates and also more effectively than with RUBLOC® material. The invention is based on the insight that the energy-absorbing capacity of an elastomeric body can be increased by reducing the contact of the elastomeric body with other objects to a minimum.

Because the facing sides of the layer or layers of elastomeric bodies and of the elastomeric plate elements are geared to one another in such a way that the contact between them in unloaded state is limited to theoretically point-shaped places of contact and for the rest the elastomeric bodies are substantially freely deformable, maximum use is made of the resiliently deforming capacity of an elastomer for absorbing vibratory energy.

While in a known laminate in particular the middle layer cannot be deformed independently of the other or others at all, and in the RUBLOC® plates the studs support an object through their flat end faces and are thus slightly hindered in their deformation, in principle this is not or hardly the case in the elastomeric internal bodies according to the invention. The vibration damper according to the invention really makes maximum use of the resiliently deforming capacity of the elastomeric material and, indeed, experiments have shown that higher vertical damping is possible than in comparable vibration dampers in which the material deforming through a periodically exerted load is more enclosed, in which latter case

the lateral stability will be higher.

In the simplest embodiment of the invention the plate elements may be designed with smooth, facing surfaces and with peripheral flanges which, when the elastomeric elements are between them, are at a distance from one another. These flanges prevent the lateral egress of the elastomeric bodies and prevent these, softer, bodies from becoming loaded too heavily by reducing the mutual approach of the covers. The flanges also form a protection against the ingress of dust which may have a negative effect on the operation of the damper.

When under an exclusively vertical load, at least a load perpendicular to the plane of the vibration damper, each of the elastomeric bodies will be freely deformable. For example, spherical elastomeric bodies can be flattened perpendicularly to the direction of the compression into ellipsoid solids of revolution, whereby the contact point at the top and bottom ends of the vertical axis changes into a small surface-to-surface contact. Except for these contacting surfaces with small dimensions the spherical elastomeric bodies are freely deformable.

If the load has a component in the plane of the vibration damper, each spherical elastomeric element, in addition to the symmetrical deformation described above, will also undergo a lopsided deformation, but the latter deformation also has a high degree of freedom owing to the presence of the free spaces with a volume increasing from the places of contact mentioned above. A vibration component in the plane of the damper can also be damped virtually exclusively by the deformation of the elastomeric bodies. Only when the lateral component becomes excessive will the further lateral movements be progressively checked through the contact between the elastomeric bodies and the walls of the recesses.

According to the invention the free spaces of which the volume increases from each place of contact can be formed, in the case where at least at the places of contact the recesses in the elastomeric plate elements and the elastomeric bodies each have the shape of parts of solids of revolution, through the generatrices of the respective solids of revolution enclosing different angles with a plane parallel to the layer of elastomeric elements at the places of contact. The generatrix of each recess is an ellipsoid and the generatrix of each elastomeric body is a circle.

In all these embodiments it is achieved that the elastomeric bodies can freely undergo their maximum lateral deformation when under a vertical load, before completely filling the recesses in the plate elements, which implies that the maximum damping capacity of the elastomeric bodies is utilized.

It is possible, through an effective selection of the shape of the cooperating surfaces of the elastomeric bodies and of the elastomeric plate elements, to obtain damping characteristics which are the most

suitable for a certain use. These damping characteristics can almost fully be determined by the shape and the size and by the material of the elastomeric bodies, while the elastomeric plate elements may be dishes or covers made of an elastomer having a higher hardness than the elastomeric elements.

In a further elaboration of the invention, the elastomeric plate elements may be provided on the sides away from the elastomeric bodies, with projections which themselves can deform and bend under vibratory loads.

The projections may be parts of spheres or cylindrical or prismatic studs with flat end faces, which are arranged in groups, each group having projections of different heights and diameters. In other words, the plate elements may be modified RUB-LOC® plates in the sense that, instead of both plates being provided with projections, the projections are only present on one of the surfaces and the other surface is designed with recesses for receiving elastomeric bodies. In such a vibration damper the softer elastomeric bodies will first receive the lower amplitude vibrations, while the harder dishes will damp the higher amplitude vibrations after the softer bodies have been maximally compressed. Thus the damping is switched from the softer elastomeric bodies to the harder dishes, in particular the studs thereof.

A particularly advantageous embodiment is one in which the stud pattern is positioned in relation to the subjacent recesses in such a way that the higher studs are laterally off-set relative to the elastomeric bodies, so that the vibrations acting on said higher studs are forced to travel along a curved path through the elastomeric bodies into the vibration damper (see arrows 19 in Figs. 6 and 8).

When elastomeric bodies are combined to form mats it is also easier to sandwich between elastomeric plate elements a plurality of layers of elastomeric bodies positioned one on top of the other or others, thereby to realise different spring characteristics. It is observed that with spherical elastomeric bodies these layers should be off-set in such a way that the interengaging spheres in the resulting stack of spheres only make point contact.

In illustration of the invention, some embodiments of the vibration damper will be described, by way of example, with reference to the accompanying drawings.

Figs. 1-8 are cross-sectional views of different vibration dampers comprising at least three layers, wherein the embodiments of fig. 2 to 5 and 7 do not fall within the scope of the invention;

Fig. 1A shows a detail of the vibration damper illustrated in Fig. 1, when subjected to a load;

Fig. 9 shows a vibration damper not falling within the scope of the invention, comprising at least two elements;

Fig. 10 shows another variant embodiment of the

vibration damper shown in Figs. 1-8;

Figs. 11 and 12 show different uses of vibration dampers according to the invention.

According to the drawings, in particular Fig. 1, a vibration damper according to the invention comprises a layer of elastomeric bodies 1, with elastomeric plate elements 2 on both sides, said plate elements in general having a higher hardness than the elastomer of bodies 1. In the embodiment of Fig. 1 the elastomeric bodies are substantially spherical and they are received in recesses 4 in the plate elements, which will be referred to hereinafter as dishes or covers 2, said recesses 4 in this embodiment having the shape of a part of an ellipsoid solid of revolution.

The mutual contact between elastomeric bodies 1 and recesses 4 is in unloaded position reduced to two basically point-shaped places of contact 3, which with a vertical load on covers 2 will be slightly increased to small surfaces of contact 3', as shown in Fig. 1A. The spherical elastomeric bodies are allowed to deform substantially freely into ellipsoid solids of revolution (flattened spheres) in the space between opposite recesses 4, through the presence of free spaces 5 surrounding places of contact 3, 3'. When the vertical load is released the flattened spheres can spring back, again freely, to the spherical shapes. The spheres 1 will then not be hindered by the thin bands or strips of material 6 shown in Fig. 1, which connect adjoining spheres into a mat, which facilitates the manipulation of the spheres in assembling a vibration damper.

The recesses 4 here also provide for the limitation of the relative lateral movements of the covers 2, thus preventing the lateral slipping of the interposed elastomeric bodies 1.

The embodiment according to Fig. 2 differs from that in Fig. 1 in that recesses 4a have a conical shape, in general the shape of a surface of revolution of which the generatrix shows a bend. In this embodiment the contact between each of the spherical elastomeric bodies 1 and the recesses 4a is along a circle 3". Although it is true that there is more contact here, namely linear contact 3", than with the point contact 3' in the embodiment according to Fig. 1, there are still free spaces adjoining the places of contact, having an increasing volume from the places of contact 3".

For that matter Fig. 2 can also represent recesses in the shape of a polyhedron, in particular a pyramid, so that the contact between elastomeric bodies 1 and recesses 4a is limited to spaced points of contact 3".

In the embodiment shown in Fig. 3, the elastomeric bodies 1 are shown in somewhat loaded form. In the left-hand part of this figure the covers 2b are formed with a flat bottom 4', and in the right-hand part partitions 4" define recesses 4 with flat bottoms 4b.

According to Fig. 4 the bottoms of the recesses

4c in the dishes 2c can have the shape of pyramids or cones, with the apex being directed towards elastomeric bodies 1. This embodiment best shows the presence of free spaces around the places of contact 3, which free spaces 5 have a volume which increases from the places of contact 3.

Fig. 5 shows elastomeric bodies 1 in the shape of cubes. If the recesses 4d in the dishes 2d are bounded by a conical plane with an apical angle β , the contact is limited to points 3''' at the corners of each cube 1.

Figs. 6-8 show embodiments of the vibration damper in which covers 2e are provided with projections 9 on their outer sides away from elastomeric bodies 1.

Fig. 6 additionally shows dish flanges 7 and grooves 8 mating therewith which limit the mutual approach of the dishes 2e and form a dust seal at the edges of the vibration damper. In the embodiment shown the walls of flanges 7 and grooves 8 have different slopes. These may be parallel, however.

Fig. 7 shows an alternative to the boundaries formed by the flanges of covers 2e, namely in the shape of strips 7a and receiving grooves 8a.

Projections 9 in the embodiments of Figs. 6 and 7 have the shape of studs with flat end faces (see also the left-hand part of Fig. 6). They can be arranged according to the RUBLOC® system. This means that the vibration damper is an improvement of the RUBLOC® vibration damper in that weak vibrations are first received by the softer spherical elastomeric bodies and at an increasing intensity of the vibrations the plate bodies start to function as a RUBLOC® vibration damper. In that configuration, as shown in Figs. 6 and 8, vibrations are not transferred perpendicularly through the damper, but along a longer, bent path 19.

Fig. 8 shows an embodiment in which projections 9a have the shape of spherical caps. When this vibration damper is placed on a flat base, the projections 9a will show a fair amount of free deformability.

Fig. 9 is a slightly deviant embodiment, in which the principle of the invention, namely minimum contact and free spaces adjoining the places of contact with increasing volume, is embodied in a two-part vibration damper. Instead of a separate layer of elastomeric bodies being enclosed between two elastomeric plate elements, the elastomeric bodies 11 in this embodiment are connected to an elastomeric plate 12. Plate 12 has conical or pyramidal projections 11 and can cooperate with a second plate 13 with recesses 14, in which projections 11 and recesses 14 have different apical angles 20. Also, a plate 12 can cooperate with a similar plate 12, which has projections 11 on one side and recesses 14' on the other. When the two plates 12 (and 13) are stacked, the projections and the recesses cooperate in the same way as in the embodiments described above, although no

distinction can be made here between the hardness of the projections and that of the plates. Through their shape the projections 11 will deform sooner than the plates 12, thereby receiving the weaker vibrations. The elastomeric plates 12 and 13 can be selected so as to have different hardnesses, thereby to vary the damping capacity.

Fig. 10 shows an embodiment with a plurality of layers of elastomeric bodies 1 between two dishes 2.

The vibration damper according to the invention can excellently be adapted to a large diversity of uses. Not only can the hardnesses of the elastomeric covers 2 and of the elastomeric bodies 1 be geared to each other, but the shapes of the covers, the recesses and the elastomeric bodies can be adapted to suit virtually any purpose. For passive damping (protecting an object against vibrations generated elsewhere) of high-frequency vibrations, for example, soft elastomeric bodies can be used with a pointed configuration, such as a pyramid or a cone with a relatively small apical angle 20. On the other hand spheres of hard material are better suited for active damping (receiving vibrations at the object where the vibrations are generated) of stronger vibrations.

In order to dissipate the heat released when the elastomeric bodies are deformed, the plate elements can be provided with vent openings 15 (see Fig. 3), which need only have small dimensions, since the pumping effect caused by the recurrent mutual approach of the plate elements causes a forced air displacement.

Fig. 11 shows a typical application of the vibration dampers according to the invention, namely under the feet of a machine 16.

Fig. 12 shows a special use of the vibration damper, namely with a clamped machine part 17. Vibrations generated by this machine part are introduced into the softer elastomeric bodies 1 which through plate elements or covers 2 are clamped in a frame 18. The clamping force can be adjusted, so that by providing a pre-stress an adjustment of the natural frequency of the spheres is possible within certain limits.

Claims

1. A vibration damper without metal elements and made of exclusively elastomeric parts comprising at least one layer of elastomeric bodies (1) longitudinally and transversally spaced within the layer (1), said layer being sandwiched between two elastomeric plate elements (2), the facing sides of the layer or layers of the elastomeric bodies (1) and of the elastomeric plate elements (2) are geared to one another in such a way that the contact between them in unloaded state is limited to small places of contact and for the area

of the elastomeric bodies (1) not in contact with the plate elements (2) the said bodies (1) are substantially freely deformable, thereby each of the bodies (1) when subjected to a load can be deformed substantially independently from the others and the internal elastomeric bodies (1) can more easily be deformed than the elastomeric plate elements (2), characterized by the said elastomeric plate elements (2) comprising recesses (4, 4e) for each of the elastomeric bodies (1) in order to prevent lateral movement of the internal layer or layers (1) between the plate elements (2), at least at the places of contact (3, 3') the recesses (4, 4e) in the plate elements (2) and the elastomeric bodies (1) each have the shape of parts of solids of revolution with the generatrices of the respective solids of revolution enclosing different angles (β) with a plane parallel to the layer of elastomeric bodies (1) at the places of contact, the generatrix of each recess (4, 4e) being an ellipsoid and the generatrix of each elastomeric body (1) being a circle, thereby the contact between the elastomeric plate elements (2) and the elastomeric bodies (1) in unloaded state is limited to theoretically point-shaped places of contact.

2. A vibration damper according to claim 1, characterized in that the elastomeric bodies (1) are interconnected by means of thin strips (6) to form a mat.
3. A vibration damper according to claim 1 or 2, characterized in that the recesses (4) in the elastomeric plate elements (2, 2a-2e) are designed with smooth, facing surfaces (4b) and peripheral flanges (4') which, when the elastomeric bodies (1) are between them, are at a distance from one another.
4. A vibration damper according to any of the preceding claims, characterized in that the plate elements (2, 2a-2e) are dishes or covers made of an elastomer having a higher hardness than the elastomeric bodies (1).
5. A vibration damper according to any of the preceding claims, characterized in that the elastomeric plate elements (2e) are provided on the sides away from the elastomeric bodies (1) with projections (9) which themselves can deform and bend under vibratory loads.
6. A vibration damper according to claim 5, characterized in that the projections (9a) are parts of spheres.
7. A vibration damper according to claim 5, charac-



distinction can be made here between the hardness of the projections and that of the plates. Through their shape the projections 11 will deform sooner than the plates 12, thereby receiving the weaker vibrations. The elastomeric plates 12 and 13 can be selected so as to have different hardnesses, thereby to vary the damping capacity.

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Claims

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of the elastomeric bodies (1) not in contact with the plate elements (2) the said bodies (1) are substantially freely deformable, thereby each of the bodies (1) when subjected to a load can be deformed substantially independently from the others and the internal elastomeric bodies (1) can more easily be deformed than the elastomeric plate elements (2), characterized by the said elastomeric plate elements (2) comprising recesses (4, 4e) for each of the elastomeric bodies (1) in order to prevent lateral movement of the internal layer or layers (1) between the plate elements (2), at least at the places of contact (3, 3') the recesses (4, 4e) in the plate elements (2) and the elastomeric bodies (1) each have the shape of parts of solids of revolution with the generatrices of the respective solids of revolution enclosing different angles (β) with a plane parallel to the layer of elastomeric bodies (1) at the places of contact, the generatrix of each recess (4, 4e) being an ellipsoid and the generatrix of each elastomeric body (1) being a circle, thereby the contact between the elastomeric plate elements (2) and the elastomeric bodies (1) in unloaded state is limited to theoretically point-shaped places of contact.

2. A vibration damper according to claim 1, characterized in that the elastomeric bodies (1) are interconnected by means of thin strips (6) to form a mat.
3. A vibration damper according to claim 1 or 2, characterized in that the recesses (4) in the elastomeric plate elements (2, 2a-2e) are designed with smooth, facing surfaces (4b) and peripheral flanges (4') which, when the elastomeric bodies (1) are between them, are at a distance from one another.
4. A vibration damper according to any of the preceding claims, characterized in that the plate elements (2, 2a-2e) are dishes or covers made of an elastomer having a higher hardness than the elastomeric bodies (1).
5. A vibration damper according to any of the preceding claims, characterized in that the elastomeric plate elements (2e) are provided on the sides away from the elastomeric bodies (1) with projections (9) which themselves can deform and bend under vibratory loads.
6. A vibration damper according to claim 5, characterized in that the projections (9a) are parts of spheres.
7. A vibration damper according to claim 5, charac-



terized in that the projections (9) are cylindrical or prismatic studs with flat end faces, which are arranged in groups, each group having projections with different heights and diameters.

8. A vibration damper according to any of the preceding claims, characterized in that a plurality of layers of elastomeric bodies (1), positioned one on top of the other or others, are sandwiched between plate elements (2).
9. A vibration damper according to claim 7 or 8, characterized in that the stud pattern (9, 9a) is positioned in relation to the subjacent recesses (4e) in such a way that vibrations acting on the higher studs are forced to travel through the elastomeric bodies (1) along a curved path (19) and the energy thereof is absorbed by the vibration damper.
10. A vibration damper according to any of the preceding claims, characterized by vent openings (15) in the elastomeric plate elements (2, 2a-2e).

Patentansprüche

1. Schwingungsdämpfer ohne metallische Elemente und gemacht aus ausschließlich elastomeren Teilen, der wenigstens eine Schicht von elastomeren Körpern (1) enthält, die in Längsrichtung und in Querrichtung innerhalb der Schicht (1) beabstandet sind, wobei die besagte Schicht beidseitig zwischen zwei elastomere Plattenelemente (2) gelegt ist, wobei die sich gegenüberliegenden Seiten der Schicht oder Schichten der elastomeren Körper (1) und der elastomeren Plattenelemente (2) auf eine solche Weise miteinander in Eingriff sind, daß der Kontakt zwischen ihnen im unbelasteten Zustand auf kleine Kontaktstellen begrenzt ist und wegen der Flächen der elastomeren Körper (1), die nicht in Kontakt mit den Plattenelementen (2) sind, die besagten Körper (1) im wesentlichen frei verformbar sind, so daß jeder der Körper (1), wenn er einer Last ausgesetzt wird, im wesentlichen unabhängig von den anderen verformt werden kann und die inneren elastomeren Körper (1) einfacher verformt werden können als die elastomeren Plattenelemente (2), dadurch gekennzeichnet, daß die besagten elastomeren Plattenelemente (2) Vertiefungen (4, 4e) für jede der elastomeren Körper (1) aufweisen, um eine seitliche Bewegung der inneren Schicht oder Schichten (1) zwischen den Plattenelementen (2) zu verhindern, daß wenigstens an den Kontaktstellen (3, 3') die Ausnehmungen (4, 4e) in den Plattenelementen

(2) und die elastomeren Körper (1) jeweils die Form von Teilen von Rotationskörpern haben, wobei die Erzeugenden der entsprechenden Rotationskörper verschiedene Winkel (β) mit einer Ebene einschließen, die parallel zu der Schicht der elastomeren Körper (1) an den Kontaktstellen ist, daß die Erzeugende jeder Ausnehmung (4, 4e) ein Ellipsoid ist und daß die Erzeugende eines jeden elastomeren Körpers (1) ein Kreis ist, so daß der Kontakt zwischen den elastomeren Plattenelementen (2) und den elastomeren Körpern (1) im unbelasteten Zustand theoretisch auf eine punktförmige Kontaktstelle begrenzt ist.

2. Schwingungsdämpfer gemäß Anspruch 1, dadurch gekennzeichnet, daß die elastomeren Körper (1) mittels dünner Streifen (6) verbunden sind, um eine Matte zu bilden.
3. Schwingungsdämpfer gemäß Anspruch 1 oder 2, dadurch gekennzeichnet, daß die Ausnehmungen (4) in den elastomeren Plattenelementen (2, 2a - 2e) mit glatten, sich gegenüberliegenden Flächen (4b) und äußeren Flanschen (4') gestaltet sind, die wenn die elastomeren Körper (1) zwischen ihnen sind, zueinander beabstandet sind.
4. Schwingungsdämpfer gemäß einem der vorhergehenden Ansprüche, dadurch gekennzeichnet, daß die Plattenelemente (2, 2a - 2e) Schalen oder Abdeckungen sind, die aus einem Elastomer gefertigt sind, das eine höhere Härte als die elastomeren Körper (1) hat.
5. Schwingungsdämpfer gemäß einem der vorhergehenden Ansprüche, dadurch gekennzeichnet, daß die elastomeren Plattenelemente (2e) auf den den elastomeren Körpern (1) abgewandten Seiten mit Vorsprungen (9) versehen sind, die sich unter Schwingungslast selbst verformen und biegen können.
6. Schwingungsdämpfer gemäß Anspruch 5, dadurch gekennzeichnet, daß die Vorsprünge (9a) Teile von Kugeln sind.
7. Schwingungsdämpfer gemäß Anspruch 5, dadurch gekennzeichnet, daß die Vorsprünge (9) zylindrische oder prismatische Noppen mit flachen Endflächen sind, die in Gruppen angeordnet sind, wobei jede Gruppe Vorsprünge mit unterschiedlichen Höhen und Durchmessern hat.



8. Schwingungsdämpfer gemäß einem der vorhergehenden Ansprüche, dadurch gekennzeichnet, daß eine Vielzahl von Schichten aus elastomeren Körpern (1), die auf der anderen oder den anderen angeordnet ist, zwischen Plattenelemente (2) gelegt ist.

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9. Schwingungsdämpfer gemäß den Ansprüchen 7 oder 8, dadurch gekennzeichnet, daß die Noppenmuster (9, 9a) in der Art bezogen auf die darunter liegenden Ausnehmungen (4e) angeordnet sind, daß die Schwingungen, die auf die höheren Noppen wirken, durch die elastomeren Körper (1) entlang eines gebogenen Weges (19) laufen müssen und deren Energie durch den Schwingungsdämpfer absorbiert wird.

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10. Schwingungsdämpfer gemäß einem der vorhergehenden Ansprüche, gekennzeichnet durch Entlüftungsöffnungen (15) in den elastomeren Plattenelementen (2, 2a - 2e).

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Revendications

1. Amortisseur de vibrations sans éléments métalliques et constitué de pièces exclusivement élastomères, comprenant au moins une couche de corps élastomères (1) espacés longitudinalement et transversalement dans la couche (1), ladite couche étant en sandwich entre deux éléments élastomères en plaque (2), les côtés se faisant face de la couche ou des couches des corps élastomères (1) et des éléments élastomères en plaque (2), étant assemblés les uns dans les autres d'une façon telle que le contact entre eux, dans un état non chargé, est limité à de petits endroits de contact et, pour l'aire des corps élastomères (1) non en contact avec les éléments en plaque (2), lesdits corps (1) sont substantiellement librement déformables, de sorte que chacun des corps (1), lorsqu'il est soumis à une charge, peut être déformé substantiellement indépendamment des autres, et les corps élastomères internes (1) peuvent être plus aisément déformés que les éléments élastomères en plaque (2), caractérisé en ce que lesdits éléments élastomères en plaque (2) comprennent des creux (4, 4e) pour chacun des corps élastomères (1) afin d'empêcher un mouvement latéral de la couche interne ou des couches internes (1) entre les éléments en plaque (2),

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en ce qu'au moins aux endroits de contact (3, 3') les creux (4, 4e) dans les éléments en plaque (2) et les corps élastomères (1) ont chacun

la forme de parties de solides de révolution, les génératrices des solides de révolution respectifs incluant différents angles avec un plan parallèle à la couche de corps élastomères (1) aux endroits de contact,

et en ce que la génératrice de chaque creux (4, 4e) est un ellipsoïde et la génératrice de chaque corps élastomère (1) étant un cercle, de sorte que le contact entre les éléments élastomères en plaque (2) et les corps élastomères (1), dans un état non chargé, est limité à des endroits de contact théoriquement en forme de point.

2. Amortisseur de vibrations selon la revendication 1, caractérisé en ce que les corps élastomères (1) sont interconnectés au moyen de bandes minces (6) pour former une nappe ou claie.

3. Amortisseur de vibrations selon la revendication 1 ou 2, caractérisé en ce que les creux (4) dans les éléments élastomères en plaque (2, 2a à 2e) sont conçus avec des surfaces lisses se faisant face (4b) et des bourrelets périphériques (4') qui, lorsque les corps élastomères (1) sont entre eux, sont écartés les uns des autres.

4. Amortisseur de vibrations selon l'une quelconque des revendications précédentes, caractérisé en ce que les éléments en plaque (2, 2a à 2e) sont des cuvettes ou des couvercles réalisés en un élastomère ayant une dureté plus élevée que les corps élastomères (1).

5. Amortisseur de vibrations selon l'une quelconque des revendications précédentes, caractérisé en ce que les éléments élastomères en plaque (2e) sont pourvus, sur leur côtés éloignés des corps élastomères (1), de saillies (9) qui peuvent elles-mêmes se déformer et plier sous des charges vibratoires.

6. Amortisseur de vibrations selon la revendication 5, caractérisé en ce que les saillies (9a) sont des parties de sphères.

7. Amortisseur de vibrations selon la revendication 5, caractérisé en ce que les saillies (9) sont des tenons cylindriques ou prismatiques avec des faces terminales plates, qui sont arrangés en groupes, chaque groupe comprenant des saillies de hauteur et diamètres différents.

8. Amortisseur de vibrations selon l'une quelconque des revendications précédentes, caractérisé en ce que plusieurs couches de corps élastomères (1), disposées l'une sur le dessus de l'autre ou des autres, sont en sandwich entre des éléments en plaque (2).



9. Amortisseur de vibrations selon la revendication 7 à 8, caractérisé en ce que le motif de tenons (9, 9a) est positionné par rapport aux creux sous-jacents (4e) de telle manière que les vibrations s'exerçant sur les tenons plus hauts sont forcées de traverser les corps élastomères (1) en suivant un chemin incurvé (19) et que leur énergie est absorbée par l'amortisseur de vibrations.

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10. Amortisseur de vibrations selon l'une quelconque des revendications précédentes, caractérisé par des ouvertures d'évent (15) dans les éléments élastomères en plaque (2, 2a à 2e).

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