

ABSTRACT OF THE DISCLOSURE

A mine sweeping robot for destroying mines burden in the ground by unmanned operation, being used in safe and secure destruction of mines regardless of the geography of the mine field.

Two cylindrical frame bodies 11, 11 are rotatably coupled coaxially to compose an outer frame 10. Inside the outer frame 10, a main body 20 for propelling the outer frame 10 by rotating and driving the frame bodies 11, 11 independently is incorporated. At a side of the main body 20, a guide bar 40 extending forward or backward in the running direction of the outer frame 10 is provided. On the outer circumference of the frame bodies 11, 11, plural probes 30, 30, ... made of elastic material are provided, extending radially from plural positions on the outer circumference. When climbing a slope, the rear end of the guide bar 40 touches the ground, and the climbability is increased. When passing over a dent, the probes 30, 30, ... contacts with the ground, and no mine is left over.