



(43) International Publication Date
23 June 2016 (23.06.2016)

(51) International Patent Classification:

B63B 27/14 (2006.01) *E01D 15/24* (2006.01)
B64F 1/305 (2006.01)

(21) International Application Number:

PCT/NO2015/050247

(22) International Filing Date:

16 December 2015 (16.12.2015)

(25) Filing Language:

Norwegian

(26) Publication Language:

English

(30) Priority Data:

20141527 18 December 2014 (18.12.2014) NO

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(81) Designated States (unless otherwise indicated, for every kind of national protection available): AE, AG, AL, AM,

AO, AT, AU, AZ, BA, BB, BG, BH, BN, BR, BW, BY, BZ, CA, CH, CL, CN, CO, CR, CU, CZ, DE, DK, DM, DO, DZ, EC, EE, EG, ES, FI, GB, GD, GE, GH, GM, GT, HN, HR, HU, ID, IL, IN, IR, IS, JP, KE, KG, KN, KP, KR, KZ, LA, LC, LK, LR, LS, LU, LY, MA, MD, ME, MG, MK, MN, MW, MX, MY, MZ, NA, NG, NI, NO, NZ, OM, PA, PE, PG, PH, PL, PT, QA, RO, RS, RU, RW, SA, SC, SD, SE, SG, SK, SL, SM, ST, SV, SY, TH, TJ, TM, TN, TR, TT, TZ, UA, UG, US, UZ, VC, VN, ZA, ZM, ZW.

(84) Designated States (unless otherwise indicated, for every kind of regional protection available): ARIPO (BW, GH, GM, KE, LR, LS, MW, MZ, NA, RW, SD, SL, ST, SZ, TZ, UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, RU, TJ, TM), European (AL, AT, BE, BG, CH, CY, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HR, HU, IE, IS, IT, LT, LU, LV, MC, MK, MT, NL, NO, PL, PT, RO, RS, SE, SI, SK, SM, TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, KM, ML, MR, NE, SN, TD, TG).

Published:

— with international search report (Art. 21(3))

(54) Title: CONTROL SYSTEM AND METHOD OF LANDING AN END PORTION OF A FREELY PROJECTING ELONGATED ELEMENT, AND USE OF AN IMAGE PROCESSOR FOR GENERATING OF CONTROL PARAMETERS FOR THE CONTROL SYSTEM

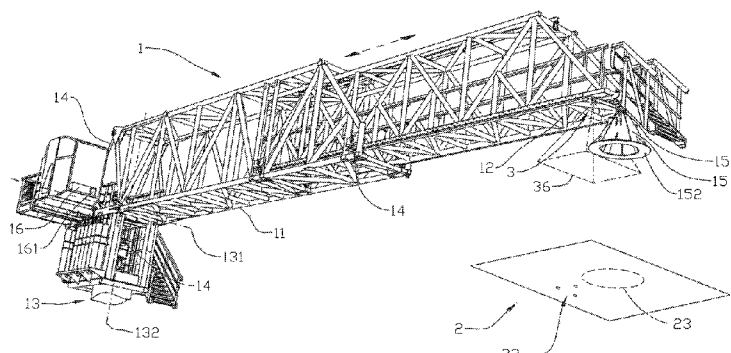


Fig. 1

(57) Abstract: A control system (16) and a method for manoeuvring an elongated element (1) which projects in a pivotable manner from a foundation (13) are described, wherein the landing place (2) is provided with a camera-readable pattern (22); the projecting end portion (12) is provided with at least one camera (31, 32) which is arranged to image the graphic pattern (22) when said end portion (12) is near the landing place (2); the at least one camera (31, 32) is connected in a signal-communicating manner to an image processor (161); and the image processor (161) is arranged to determine the position of the at least one camera (31, 32) relative to the pattern (22) by an image analysis and convert the image information into control parameters for the control system (16) to position the projecting end portion (12) relative to the landing place (2).