

Description

The present invention relates to a sun tracking apparatus comprising a rotatable vertical shaft 15, a horizontal shaft 5 which is rotatably supported by the vertical shaft and whose axis is orthogonal to the axis of the vertical shaft, a first pair of optical detectors, which are at symmetrically opposed positions substantially on an axis parallel to the axis of the horizontal shaft, a second pair of optical detectors, which are supported by the horizontal shaft, so as to rotate therewith, at symmetrically opposed positions substantially on an axis perpendicular to the horizontal axis, a first driving means connected to the vertical shaft for rotating the same in a predetermined direction in accordance with outputs of the first pair of optical detectors, and a second driving means connected to the horizontal shaft for rotating the horizontal shaft in a predetermined direction in accordance with outputs of the second pair of optical detectors, said first and second driving means being driven only when there are differences in outputs between the first pair of optical detectors and between the second pair of optical detectors, resp.

A sun tracking apparatus of this type is known from DE—A—27 00 313. According to this document the two pairs of optical detectors serve for roughly positioning a sunlight collecting means comprising further sensor means for the fine adjustment during the tracking movement. Thus, the known apparatus is rather complicated and expensive.

Further, various kinds of solar light energy utilizing equipment and devices with lens means for collecting solar light energy are known. Such solar light energy utilizing equipment or devices must be able to effectively collect the largest amount of solar light energy possible. In order to collect the largest amount of the solar light energy possible, it is necessary for the lens means to always face the sun. The sun, however, changes in location and angle seasonally, daily, and hourly. Therefore, the lens means must be continuously moved to follow the sun.

Hitherto unknown has been a solar energy collecting apparatus having a simple sun tracking apparatus which can continuously and precisely follow such seasonal, daily, and hourly changes in the sun's location and altitude.

It is the object of the present invention, therefore, to provide a simple sun tracking apparatus which ensures that the solar energy collecting apparatus always faces the sun and which can be easily and inexpensively manufactured.

This object is accomplished according to the invention in that

- a) the first pair of optical detectors are supported by the vertical shaft and fixed near the axis of the horizontal shaft;
- b) the first pair of optical detectors have sub-

stantially vertical outer sunlight receiving surfaces which face outside in opposite directions to one another;

- c) the second pair of optical detectors have substantially parallel inner sunlight receiving surfaces facing each other; and
- d) modifying means are provided for modifying the output of one optical detector of the second pair of optical detectors in accordance with the altitude of the sun.

The sun tracking apparatus of the present invention has a possible minimum number of optical detectors for detecting the sun's location. Preferably, the optical detectors comprise two pairs of photosensors or photocells arranged at opposing points along two perpendicular axes.

Other features, additional objects, and many of the attendant advantages of this invention will readily be appreciated through the following detailed description of preferred embodiments with reference to the appended drawings, in which:

Fig. 1 is a schematic perspective view of a sun tracking apparatus according to the present invention;

Fig. 2 is a front elevational view of the apparatus illustrated in Fig. 1, shown at a different position;

Fig. 3 is a side elevational view of Fig. 1;

Fig. 4 is a diagram of an example of a drive circuit operating in accordance with differential outputs of the photosensors; and

Fig. 5 is a schematic view showing successive positions of the plane defined by the first and second axis which follows the movement of the sun.

The apparatus of this invention has a rotatable vertical shaft 15 substantially orthogonal to the ground, i.e., lying along the above-mentioned third axis 14. The vertical shaft 15 supports a generally U-shaped arm 7 arranged symmetrical to the shaft.

The apparatus also has a horizontal shaft 5 perpendicular to the axis of vertical shaft 15, i.e., lying along the above-mentioned first axis 16. The horizontal shaft 5 supports therebetween a circular ring frame 3, arranged symmetrical to the shaft, and is rotatably supported by the arm 7. An optical lens means, preferably composed of a circular Fresnel lens 1, is supported by and held in the ring frame 3.

The vertical shaft 15 is rotatably supported on a base frame 10 by means of a bearing 19. The vertical shaft 15 has a gear wheel 21 integral therewith which is engaged with a gear wheel 23 which is, in turn, connected to a first driving motor 27. The first motor 27 can be supported, for example, by a bracket 11 integral with the base frame 10. The first motor 27 rotates the vertical shaft 15 together with the arm 7.

To one end of the horizontal shaft 5 is connected a second driving motor 13 which is



supported by a bracket 9 integral with the base frame 10. The second motor 13 rotates the horizontal shaft 5 together with the ring frame 3.

The ring frame 3 has supporting frames 29 (Fig. 3) which are secured thereto and which generally form an inverted imaginary cone. The bottom apex of the imaginary cone defined by the supporting frames 29 is located at the focus point of the Fresnel lens 1. An inlet end 31a of an optical fiber cable 31 is located at and connected to the bottom apex of the imaginary cone of the supporting frames 29. The sunlight collected by the lens 1 is collected by the cable 31. The vertical shaft 15 is preferably hollow, so that the cable 31 extending through the arm 7 can extend in the vertical shaft 15 to a solar energy utilizing device (not shown).

Four optical detectors, such as photosensors (or photocells) 50E, 50W, 50N, and 50S are provided to detect the amount of sunlight. These photosensors, which are themselves known, issue electrical outputs when they receive sunlight and feed the outputs to a central processing unit (CPU) 70 on the base frame 10. In the position of the lens 1 shown in Fig. 1, the photosensors 50E, 50W, 50N, and 50S are located at the four cardinal points, i.e. east, west, north, and south, respectively. Accordingly, they are represented by the suffixes E, W, N, and S for convenience's sake. It should be, however, noted that the location of the photosensors changes in accordance with the azimuth and altitude of the sun, as will be described hereinafter.

The first pair of photosensors 50E and 50W are held by and secured to vertical plates 53E and 53W, respectively, which are in turn secured to the ends of the arm 7. The photosensors 50E and 50W are located at diametrically opposed positions near to the axis of the horizontal shaft 5, i.e., substantially on the above-mentioned second axis 18. The photosensors 50E and 50W have substantially vertical outer sunlight receiving surfaces 51E and 51W, respectively, facing outside in opposite directions.

The second pair of photosensors 50N and 50S are held by and secured to vertical plates 53N and 53S, respectively, which are in turn secured to the peripheral surface of the ring frame 3. The photosensors 50N and 50S are located at diametrically opposed positions substantially on an axis perpendicular to the horizontal shaft 5, i.e., substantially on the above-mentioned second axis 18. The photosensors 50N and 50S have substantially vertical inner sunlight receiving surfaces 51N and 51S, respectively, which face inside.

A fifth optical detector, such as photosensor (or photocell) 60 is also provided on the ring frame 3. The fifth photosensor 60 has an upper sunlight receiving surface 61 substantially parallel to the plane of the lens 1. The sunlight receiving surface 61 faces the sun when the lens 1 faces the sun. The fifth photosensor 60 detects the presence or absence of sunlight and

effects the sun tracking operation, described later, only when there is sunlight and stops the sun tracking operation when there is no sunlight, for example, at night.

The apparatus of this invention operates as follows. In the discussion to follow, the movement of the lens is described in reference to installation sites in the northern hemisphere.

When the lens 1 precisely faces the sun that is, when sunlight is received in a direction L_0 (Fig. 3) perpendicular to the plane of the lens 1, none of the photosensors 50E, 50W, 50N, or 50S receive direct sunlight since their sunlight receiving surfaces are all parallel to the direct sunlight. In this state, (referred to below as the "desired position"), these photosensors only receive minor indirect sunlight, i.e., diffused light.

On the other hand, when the lens 1 is deviated from the desired position and does not precisely face the sun, that is, when direct sunlight is received in directions not perpendicular to the plane of the lens, certain of the photosensors 50E, 50W, 50N, or 50S will receive direct sunlight.

For example, when the direct sunlight is received at an angle from the third axis in the plane defined by the third axis and second axis, the photosensor 50S will receive direct sunlight in directions L_1 (Fig. 3), while the photosensor 50N will not, or the photosensor 50N will receive direct sunlight in direction L_2 , while photosensor 50S will not.

The CPU 70 has a differential amplifier DIF 1 (Fig. 4) which compares the outputs of the photosensors 50N and 50S. When there is a difference between said outputs, it drives the second motor 13 in a predetermined direction until that difference is eliminated. When the direct sunlight is received at an angle from the third axis in the plane defined by the third axis and the first axis, the same situation occurs. The CPU 70 also has a differential amplifier DIF 2 which compares the outputs of the photosensors 50E and 50W. When there is a difference between said outputs, it drives the first motor 27 in a predetermined direction until that difference is eliminated.

As can be understood from the above, the apparatus according to the present invention can therefore track the daily, hourly and seasonal movement of the sun to keep the lens continuously and directly facing the sun, thus allowing effective collection of solar light energy.

The movement of the lens 1 as it follows the sun is schematically shown in Fig. 5. In Fig. 5, only rotation of the horizontal shaft 5 is shown. In Fig. 5, direct sunlight falls along the direction L_0 . The direction L_0 changes from a 75° altitude θ just after high noon to a 15° altitude θ near sunset.

It should be noted that the total quantity Q_0 of sunlight is the sum of the quantity Q_1 of direct

sunlight and the quantity Q_2 of indirect sunlight (indirect spacious rays). That is,

$$Q_0 = Q_1 + Q_2$$

Most indirect sunlight, as is well known is perpendicular to the ground or at only slight angles to the line perpendicular to the ground independent of the location of the sun.

Now, when the altitude θ of the sun is small, as at about sunset (or sunrise), the angle β of the incline of the lens 1 is large. Also at sunset (or sunrise), however, the quantity of indirect sunlight falling from above is large while the quantity of indirect sunlight rising from below is small. In such a position, there is a large difference between the quantity of indirect sunlight received by the photosensors 50S and 50N. That is, the quantity of the indirect spacious rays which the photosensor 50S receives is considerably larger than that received by the photosensor 50N. The quantity of the indirect sunlight which the photosensor 50N receives is very small, almost zero, when the angle β of incline of the lens 1 is almost 90° .

This creates problems particularly at about sunset or sunrise. If the motor 13 were to rotate until the output of the photosensor 50N became equal to the output of the photosensor 50S at that time, the lens would go past the desired position. As obvious from the above explanation, this is because the output of the photosensor 50S is larger than the output of the photosensor 50N by a value corresponding to the difference in the quantity of the indirect sunlight received by the photosensors 50N and 50S even when the lens directly faces the sun.

The difference between the amount of the indirect sunlight received by the photosensors 50N and 50S increases as the inclined angle β of the lens 1 increases. The following table shows experimental findings on the relationship between the altitude θ of the sun and the ratio between the total quantities Q_N and Q_S of the sunlight received by the photosensors 50N and 50S, respectively. In the experiments, the lens was positioned to directly face the sun, that is, the sum of the altitude θ of the sun and the inclined angle β of the lens 1 was always 90° (θ is a complementary angle of β).

θ	Q_S/Q_N
$\theta=20^\circ$ ($\beta=70^\circ$)	2.1
$\theta=30^\circ$ ($\beta=60^\circ$)	1.9
$\theta=40^\circ$ ($\beta=50^\circ$)	1.6
$\theta=50^\circ$ ($\beta=40^\circ$)	1.4
$\theta=60^\circ$ ($\beta=30^\circ$)	1.2
$\theta=70^\circ$ ($\beta=20^\circ$)	1.1

As can be seen from the above table, in spite of the fact that the lens 1 precisely faced the sun, there was a difference between Q_S and Q_N . That is, Q_N was always smaller than Q_S ($Q_S > Q_N$). The difference increased as the angle β increased. As mentioned above, the difference results from the difference in the amount of indirect sunlight received by the photosensors 50N and 50S.

In order to prevent the CPU 70 from moving the lens 1 past the desired position, it is necessary to compensate for this difference. The simplest solution is to multiply the output of the photosensor 50S by an adjusting coefficient λ which is a reciprocal number of the ratio and which is a function of the altitude θ of the sun or the inclined angle β of the lens 1. By multiplying Q_S by a reciprocal number of Q_S/Q_N , the multiplied Q_S (Q_S/λ) becomes equal to Q_N , so that the movement of the lens 1 can be stopped just at the desired position. The multiplication operation can be effected in the CPU 70.

If no highly precise adjustment of the inclined angle of the lens following the movement of the sun is necessary, no adjustment of the output of the photosensor 50S by multiplying it by the adjusting coefficient λ is necessary. Furthermore, if no highly precise adjustment of the inclined angle of the lens is necessary, the sunlight receiving surfaces of the two pairs of photosensors may be slightly inclined

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(13)

with respect to the incident direct sunlight when the lens is put in the desired position.

Alternatively, it is also possible to control the movement of the lens 1 in such a way that the output of the photosensor 50S is multiplied by the adjusting coefficient λ only when the total amount Q_s of the sunlight received by the photosensor 50S is larger than the total amount Q_c of sunlight received by the photosensor 60. This is because Q_c , which is usually larger than Q_s in the daytime, is smaller than Q_s at about sunset or sunrise. This is because of sunset or sunrise, on the one hand, the direct sunlight received by the photosensor 60 is small and, on the other hand, the indirect sunlight received by the photosensor 50S is large. In the above-mentioned alternative method, the motor 13 is controlled in such a way that lens 1 rotates until $|Q_s - Q_c| = 0$ under the condition of $Q_c > Q_s$ and until $|Q_s/\lambda - Q_c| = 0$ under the condition of $Q_c \leq Q_s$.

Claims

1. A sun tracking apparatus comprising a rotatable vertical shaft (15), a horizontal shaft (5) which is rotatably supported by the vertical shaft (15) and whose axis is orthogonal to the axis of the vertical shaft (15), a first pair of optical detectors (50E, 50W) which are at symmetrically opposed positions substantially on an axis parallel to the axis of the horizontal shaft (5), a second pair of optical detectors (50N, 50S) which are supported by the horizontal shaft (5), so as to rotate therewith, at symmetrically opposed positions substantially on an axis perpendicular to the horizontal axis, a first driving means connected to the vertical shaft (15) for rotating the same in a predetermined direction in accordance with outputs of the first pair of optical detectors (50E, 50W), and a second driving means (13) connected to the horizontal shaft (5) for rotating the horizontal shaft (5) in a predetermined direction in accordance with outputs of the second pair of optical detectors (50N, 50S), said first and second driving means being driven only when there are differences in outputs between the first pair of optical detectors (50E, 50W) and between the second pair of optical detectors (50N, 50S), respectively, characterized in that:

- a) the first pair of optical detectors (50E, 50W) are supported by the vertical shaft (15) and fixed near the axis (16) of the horizontal shaft (5);
- b) the first pair of optical detectors (50E, 50W) have substantially vertical outer sunlight receiving surfaces (51E, 51W) which face outside in opposite directions to one another;
- c) the second pair of optical detectors (50N, 50S) have substantially parallel inner sunlight receiving surfaces (51N, 51S) facing each other; and
- d) modifying means (70) are provided for

modifying the output of one optical detector (50N) of the second pair of optical detectors (50N, 50S) in accordance with the altitude of the sun.

2. Apparatus according to claim 1, characterized in that a fifth optical detector (60) is provided which is supported on a ring frame (3) which is supported by the horizontal shaft (5) and on which the second pair of optical detectors (50N, 50S) is located in a diametral arrangement, said fifth optical detector (60) having an upper sunlight receiving surface (61) substantially parallel to the plane of the frame (3) to detect the total amount of the sunlight and that means are provided for modifying the output of said one optical detector (50N) of the second pair of optical detectors (50N, 50S) only when the output of said one optical detector (50N) is larger than the output of said fifth optical detector (60).

3. Apparatus according to claim 1 or 2, characterized in that each of said optical detectors comprises a photosensor (50N, 50E, 50S, 50W, 60).

4. Apparatus according to one of claims 1 to 3, characterized in that a lens means (1) for collecting the sunlight is supported by the horizontal shaft (5).

5. Apparatus according to claim 4, characterized in that said lense means comprises a circular Fresnel lens (1).

6. Apparatus according to claim 2 and 5, characterized in that said ring frame (3) is holding the Fresnel lens (1).

7. Apparatus according to one of claims 4 to 6, characterized in that an optical fiber cable (31) is provided which has an inlet end located at the focal point of the lens means (1).

Revendications

1. Un appareil de poursuite du soleil comprenant un arbre vertical tournant (15), un arbre horizontal (5) qui est supporté avec possibilité de rotation par l'arbre vertical (15) et dont l'axe est orthogonal à l'axe de l'arbre vertical (15), une première paire de détecteur optiques (50E, 50W) qui sont dans des positions symétriquement opposées, à peu près sur un axe parallèle à l'axe de l'arbre horizontal (5), une seconde paire de détecteurs optiques (50N, 50S) qui sont supportés par l'arbre horizontal (5) de manière à tourner avec celui-ci, dans des positions symétriquement opposées, à peu près sur un axe perpendiculaire à l'axe horizontal, des premiers moyens d'entraînement reliés à l'arbre vertical (15) pour faire tourner ce dernier dans un sens prédéterminé en fonction des sorties de la première paire de détecteurs optiques (50E, 50W) et des seconds moyens d'entraînement (13) reliés à l'arbre horizontal (5) pour faire tourner l'arbre horizontal (5) dans un sens prédéterminé en fonction des sorties de la seconde paire de détecteurs optiques (50N,

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with respect to the incident direct sunlight when the lens is put in the desired position.

Alternatively, it is also possible to control the movement of the lens 1 in such a way that the output of the photosensor 50S is multiplied by the adjusting coefficient λ only when the total amount Q_s of the sunlight received by the photosensor 50S is larger than the total amount Q_c of sunlight received by the photosensor 60. This is because Q_c , which is usually larger than Q_s in the daytime, is smaller than Q_s at about sunset or sunrise. This is because of sunset or sunrise, on the one hand, the direct sunlight received by the photosensor 60 is small and, on the other hand, the indirect sunlight received by the photosensor 50S is large. In the above-mentioned alternative method, the motor 13 is controlled in such a way that lens 1 rotates until $|Q_s - Q_n| = 0$ under the condition of $Q_c > Q_s$ and until $|Q_s/\lambda - Q_n| = 0$ under the condition of $Q_c \leq Q_s$.

Claims

1. A sun tracking apparatus comprising a rotatable vertical shaft (15), a horizontal shaft (5) which is rotatably supported by the vertical shaft (15) and whose axis is orthogonal to the axis of the vertical shaft (15), a first pair of optical detectors (50E, 50W) which are at symmetrically opposed positions substantially on an axis parallel to the axis of the horizontal shaft (5), a second pair of optical detectors (50N, 50S) which are supported by the horizontal shaft (5), so as to rotate therewith, at symmetrically opposed positions substantially on an axis perpendicular to the horizontal axis, a first driving means connected to the vertical shaft (15) for rotating the same in a predetermined direction in accordance with outputs of the first pair of optical detectors (50E, 50W), and a second driving means (13) connected to the horizontal shaft (5) for rotating the horizontal shaft (5) in a predetermined direction in accordance with outputs of the second pair of optical detectors (50N, 50S), said first and second driving means being driven only when there are differences in outputs between the first pair of optical detectors (50E, 50W) and between the second pair of optical detectors (50N, 50S), respectively, characterized in that:

- a) the first pair of optical detectors (50E, 50W) are supported by the vertical shaft (15) and fixed near the axis (16) of the horizontal shaft (5);
- b) the first pair of optical detectors (50E, 50W) have substantially vertical outer sunlight receiving surfaces (51E, 51W) which face outside in opposite directions to one another;
- c) the second pair of optical detectors (50N, 50S) have substantially parallel inner sunlight receiving surfaces (51N, 51S) facing each other; and
- d) modifying means (70) are provided for

modifying the output of one optical detector (50N) of the second pair of optical detectors (50N, 50S) in accordance with the altitude of the sun.

2. Apparatus according to claim 1, characterized in that a fifth optical detector (60) is provided which is supported on a ring frame (3) which is supported by the horizontal shaft (5) and on which the second pair of optical detectors (50N, 50S) is located in a diametral arrangement, said fifth optical detector (60) having an upper sunlight receiving surface (61) substantially parallel to the plane of the frame (3) to detect the total amount of the sunlight and that means are provided for modifying the output of said one optical detector (50N) of the second pair of optical detectors (50N, 50S) only when the output of said one optical detector (50N) is larger than the output of said fifth optical detector (60).

3. Apparatus according to claim 1 or 2, characterized in that each of said optical detectors comprises a photosensor (50N, 50E, 50S, 50W, 60).

4. Apparatus according to one of claims 1 to 3, characterized in that a lens means (1) for collecting the sunlight is supported by the horizontal shaft (5).

5. Apparatus according to claim 4, characterized in that said lense means comprises a circular Fresnel lens (1).

6. Apparatus according to claim 2 and 5, characterized in that said ring frame (3) is holding the Fresnel lens (1).

7. Apparatus according to one of claims 4 to 6, characterized in that an optical fiber cable (31) is provided which has an inlet end located at the focal point of the lens means (1).

Revendications

1. Un appareil de poursuite du soleil comprenant un arbre vertical tournant (15), un arbre horizontal (5) qui est supporté avec possibilité de rotation par l'arbre vertical (15) et dont l'axe est orthogonal à l'axe de l'arbre vertical (15), une première paire de détecteurs optiques (50E, 50W) qui sont dans des positions symétriquement opposées, à peu près sur un axe parallèle à l'axe de l'arbre horizontal (5), une seconde paire de détecteurs optiques (50N, 50S) qui sont supportés par l'arbre horizontal (5) de manière à tourner avec celui-ci, dans des positions symétriquement opposées, à peu près sur un axe perpendiculaire à l'axe horizontal, des premiers moyens d'entraînement reliés à l'arbre vertical (15) pour faire tourner ce dernier dans un sens prédéterminé en fonction des sorties de la première paire de détecteurs optiques (50E, 50W) et des seconds moyens d'entraînement (13) reliés à l'arbre horizontal (5) pour faire tourner l'arbre horizontal (5) dans un sens prédéterminé en fonction des sorties de la seconde paire de détecteurs optiques (50N,



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50S), lesdits premiers et seconds moyens d'entraînement étant activés uniquement lorsqu'il existe des différences de sortie entre les détecteurs optiques de la première paire (50E, 50W) et entre les détecteurs optiques de la seconde paire (50N, 50S) respectivement, caractérisé en ce que: a) les détecteurs optiques de la première paire (50E, 50W) sont supportés par l'arbre vertical (15) et fixés à proximité de l'axe (16) de l'arbre horizontal (5); b) les détecteurs optiques de la première paire (50E, 50W) ont des surfaces extérieures réceptrices de la lumière solaire (51E, 51W) à peu près verticales qui font face vers l'extérieur dans des directions opposées l'une de l'autre; c) les détecteurs optiques (50N, 50S) de la seconde paire possèdent les surfaces intérieures réceptrices de lumière solaire à peu près parallèles (51N, 51S) qui se font mutuellement face; et d) des moyens modificateurs (70) sont prévus pour modifier la sortie d'un détecteur optique (50N) de la seconde paire de détecteurs optiques (50N, 50S) en fonction de l'altitude du soleil.

2. Appareil selon la revendication 1, caractérisé en ce qu'il est prévu un cinquième détecteur optique (60) qui est supporté sur un cadre annulaire (3) qui est supporté par l'arbre horizontal (5) et sur lequel la seconde paire de détecteurs optiques (50N, 50S) est placée dans un arrangement diamétral, ledit cinquième détecteur optique (60) possédant une surface supérieure réceptrice de lumière solaire (61) à peu près parallèle au plan du cadre (3) pour détecter la quantité totale de lumière solaire, et en ce que des moyens sont prévus pour modifier la sortie dudit premier détecteur optique (50N) de la seconde paire de détecteurs optiques (50N, 50S) uniquement lorsque la sortie dudit premier détecteur optique (50N) est plus grande que la sortie dudit cinquième détecteur optique (60).

3. Appareil selon la revendication 1 ou 2, caractérisé en ce que chacun desdits détecteurs optiques comprend un photo-capteur (50N, 50E, 50S, 50W, 60).

4. Appareil selon une des revendications 1 à 3, caractérisé en ce que des moyens du type lentille (1) destinés à collecter la lumière solaire sont supportés par l'arbre horizontal (5).

5. Appareil selon la revendication 4, caractérisé en ce que lesdits moyens du type lentille comprennent une lentille de Fresnel circulaire (1).

6. Appareil selon les revendications 2 et 5, caractérisé en ce que ledit cadre annulaire (3) tient la lentille de Fresnel (1).

7. Appareil selon l'une des revendications 4 à 6, caractérisé en ce qu'il comprend un câble à fibres optiques (31) qui possède une extrémité d'entrée située au foyer des moyens (1) du type lentille.

Patentansprüche

1. Sonnennachführvorrichtung mit einer

drehbaren vertikalen Welle (15), einer horizontalen Welle (5), welche drehbar von der vertikalen Welle (15) getragen wird und deren Achse rechtwinklig zur Achse der vertikalen Welle (15) verläuft, mit einem ersten Paar optischer Detektoren (50E, 50W), welche in einander symmetrisch gegenüberliegenden Positionen im wesentlichen auf einer parallel zur Achse der horizontalen Welle (5) verlaufenden Achse angeordnet sind, mit einem zweiten Paar optischer Detektoren (50N, 50S), welche von der horizontalen Welle (5) getragen werden, so daß sie sich mit dieser drehen und zwar in einander symmetrisch gegenüberliegenden Positionen, die im wesentlichen auf einer zur horizontalen Achse senkrechten Achse liegen, mit einer ersten Antriebseinrichtung, die mit der vertikalen Welle (15) verbunden ist, um diese in Übereinstimmung mit den Ausgangssignalen des ersten Paares optischer Detektoren (50E, 50W) in einer vorgegebenen Richtung zu drehen und mit einer zweiten Antriebseinrichtung (13), die mit der horizontalen Welle (5) verbunden ist, um die horizontale Welle (5) in Übereinstimmung mit den Ausgangssignalen des zweiten Paares optischer Detektoren (50N, 50S) in einer vorgegebenen Richtung zu drehen, wobei die erste und die zweite Antriebseinrichtung nur angetrieben werden, wenn Unterschiede zwischen den Ausgangssignalen der optischen Detektoren (50E, 50W) des ersten Paares bzw. zwischen den Ausgangssignalen der optischen Detektoren (50N, 50S) des zweiten Paares vorliegen, dadurch gekennzeichnet, daß:

- a) das erste Paar optischer Detektoren (50E, 50W) von der vertikalen Welle (15) getragen wird und in der Nähe der Achse (16) der horizontalen Welle (5) befestigt ist;
- b) das zweite Paar optischer Detektoren (50E, 50W) im wesentlichen vertikale äussere Sonnenlicht-Empfangsflächen (51E, 51W) aufweist, welche in entgegengesetzten Richtungen nach aussen gewandt sind;
- c) das zweite Paar optischer Detektoren (50N, 50S) im wesentlichen parallele innere Sonnenlicht-Empfangsflächen (51N, 51S) aufweist, die einander zugewandt sind; und
- d) Modifiziereinrichtungen (7) vorgesehen sind, um das Ausgangssignal eines der optischen Detektoren (50N) des zweiten Paares optischer Detektoren (50N, 50S) in Abhängigkeit von der Höhe der Sonne zu modifizieren.

2. Vorrichtung gemäss Anspruch 1, dadurch gekennzeichnet, daß ein fünfter optischer Detektor (60) vorgesehen ist, der von einem Ringrahmen (3) getragen wird, der durch die horizontale Welle (5) getragen wird und auf dem die optischen Detektoren (50N, 50S) des zweiten Paares einander diametral gegenüberliegend angeordnet sind, wobei der fünfte optische Detektor (60) eine obere Sonnenlicht-



empfangsfläche (61) aufweist, die im wesentlichen parallel zur Ebene des Rahmens (3) ausgerichtet ist, um die Gesamtmenge des Sonnenlichtes zu erfassen, und daß Einrichtungen vorgesehen sind, um das Ausgangssignal dieses optischen Detektors (50N) des zweiten Paares optischer Detektoren (50N, 50S) nur dann zu modifizieren, wenn das Ausgangssignal dieses optischen Detektors (50N) grösser als das Ausgangssignal des fünften optischen Detektors (60) ist.

3. Vorrichtung nach Anspruch 1 oder 2, dadurch gekennzeichnet, daß jeder der optischen Detektoren einen Fotosensor (50N, 50E, 50S, 50W, 60) umfasst.

4. Vorrichtung nach einem der Ansprüche 1 bis 3, dadurch gekennzeichnet, daß eine Linsen-anordnung (1) zum Sammeln des Sonnenlichts von der horizontalen Welle (5) getragen wird.

5. Vorrichtung nach Anspruch 4, dadurch gekennzeichnet, daß die Linsen-anordnung eine runde Fresnel-Linse (1) umfasst.

6. Vorrichtung nach Anspruch 2 und 5, dadurch gekennzeichnet, daß der Ringrahmen (3) die Fresnel-Linse (1) hält.

7. Vorrichtung nach einem der Ansprüche 4 bis 6, dadurch gekennzeichnet, daß ein Kabel (31) aus optischen Fasern vorgesehen ist, welches ein Einlassende besitzt, das am Brennpunkt der Linsen-anordnung (1) angeordnet ist.

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