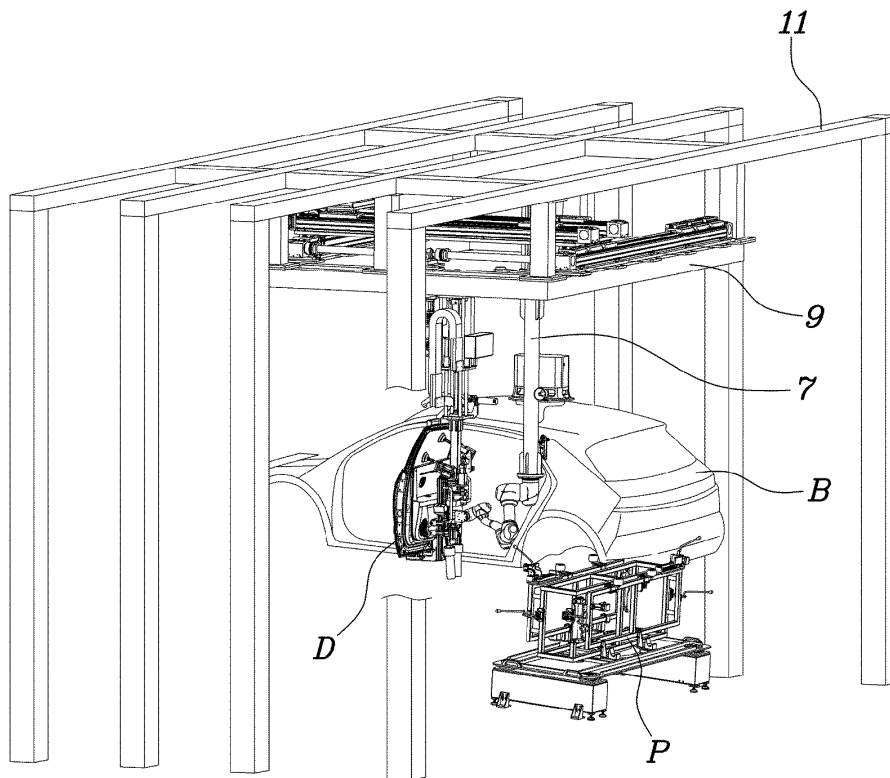
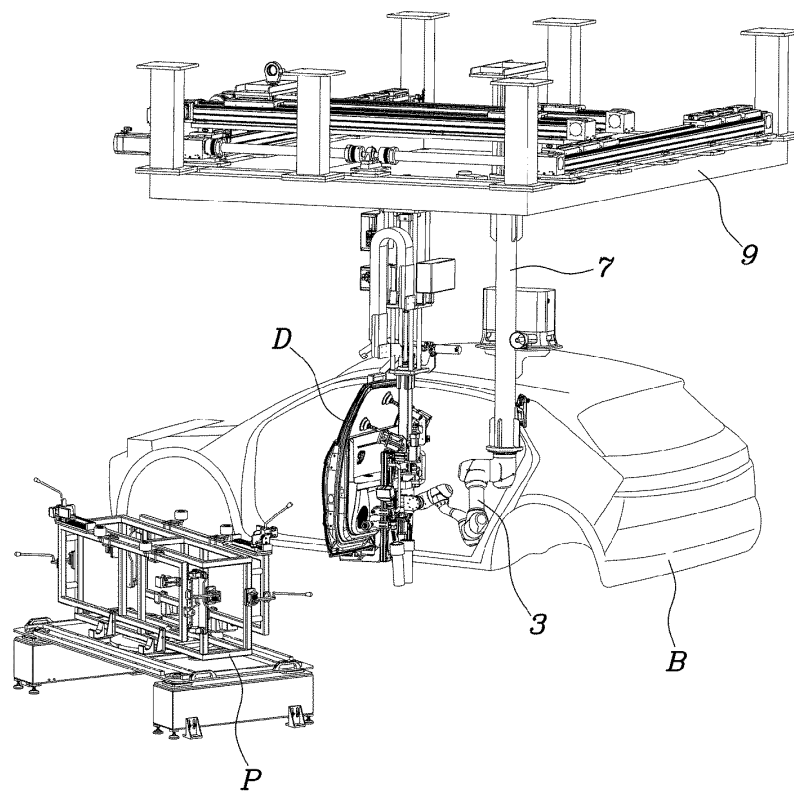


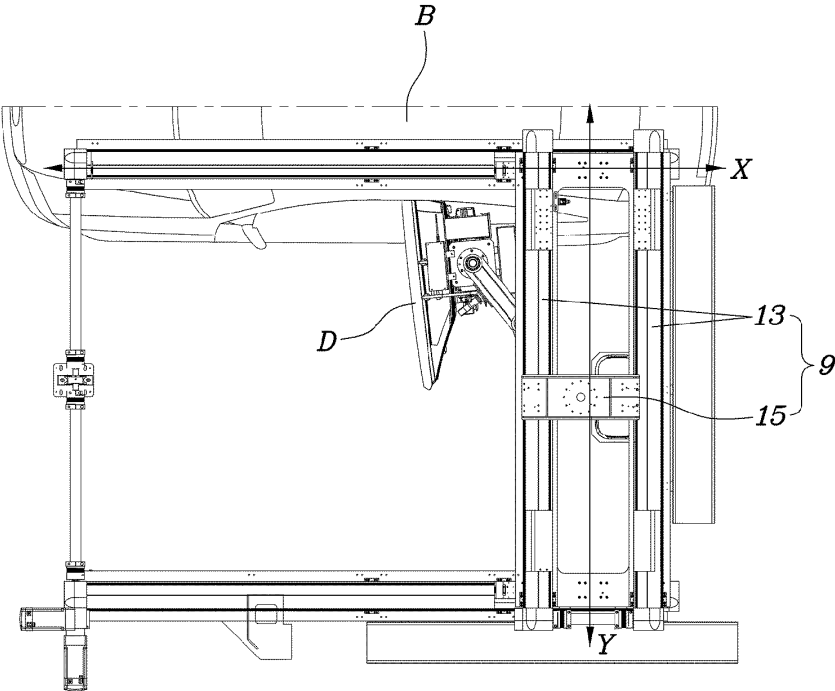
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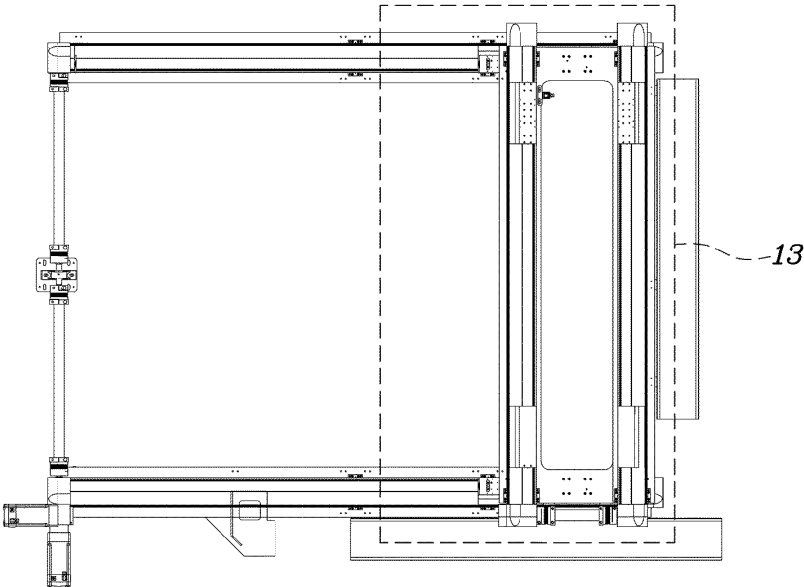
[도2]



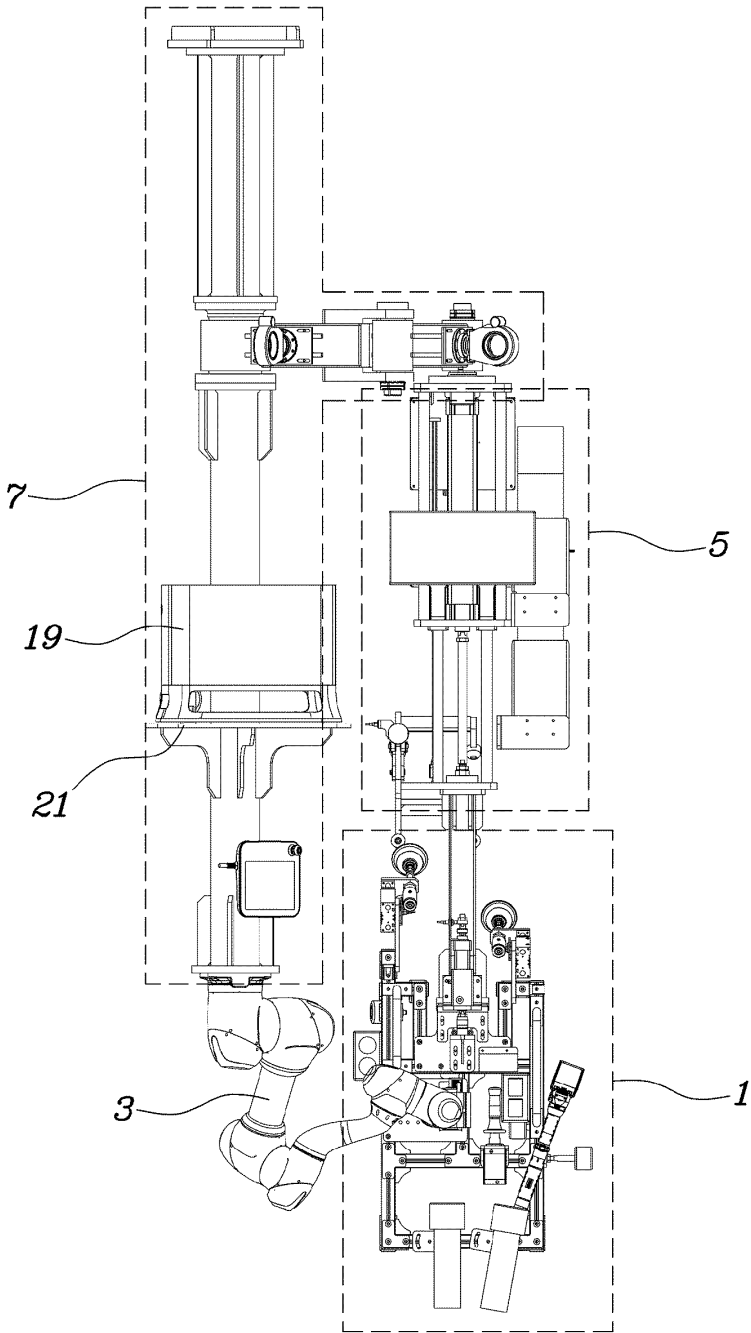
[도3]



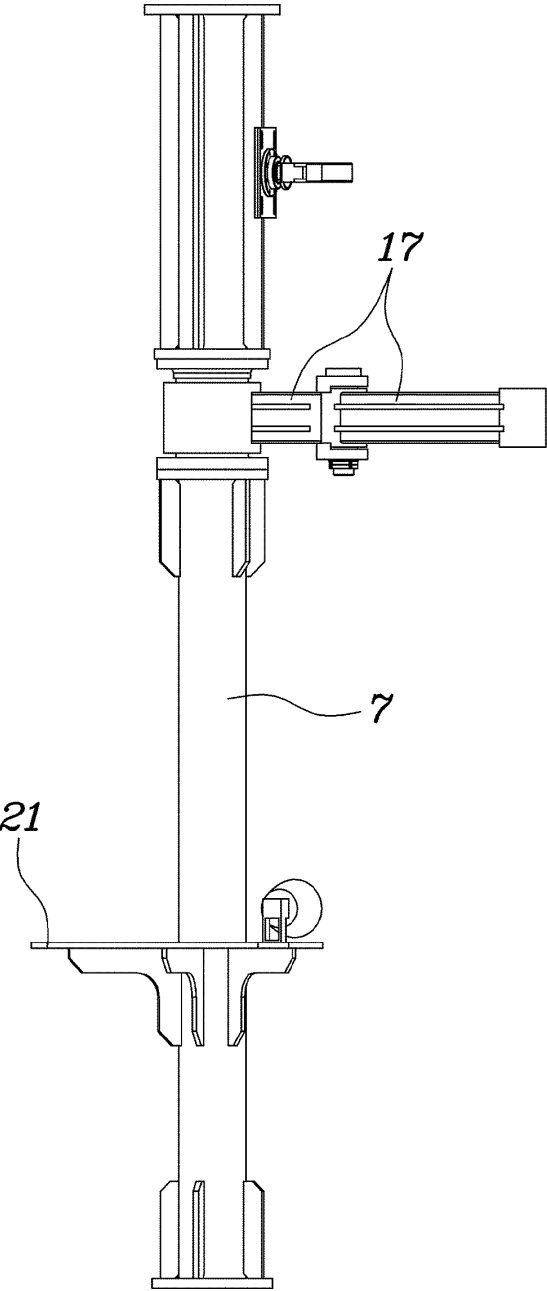
[도4]



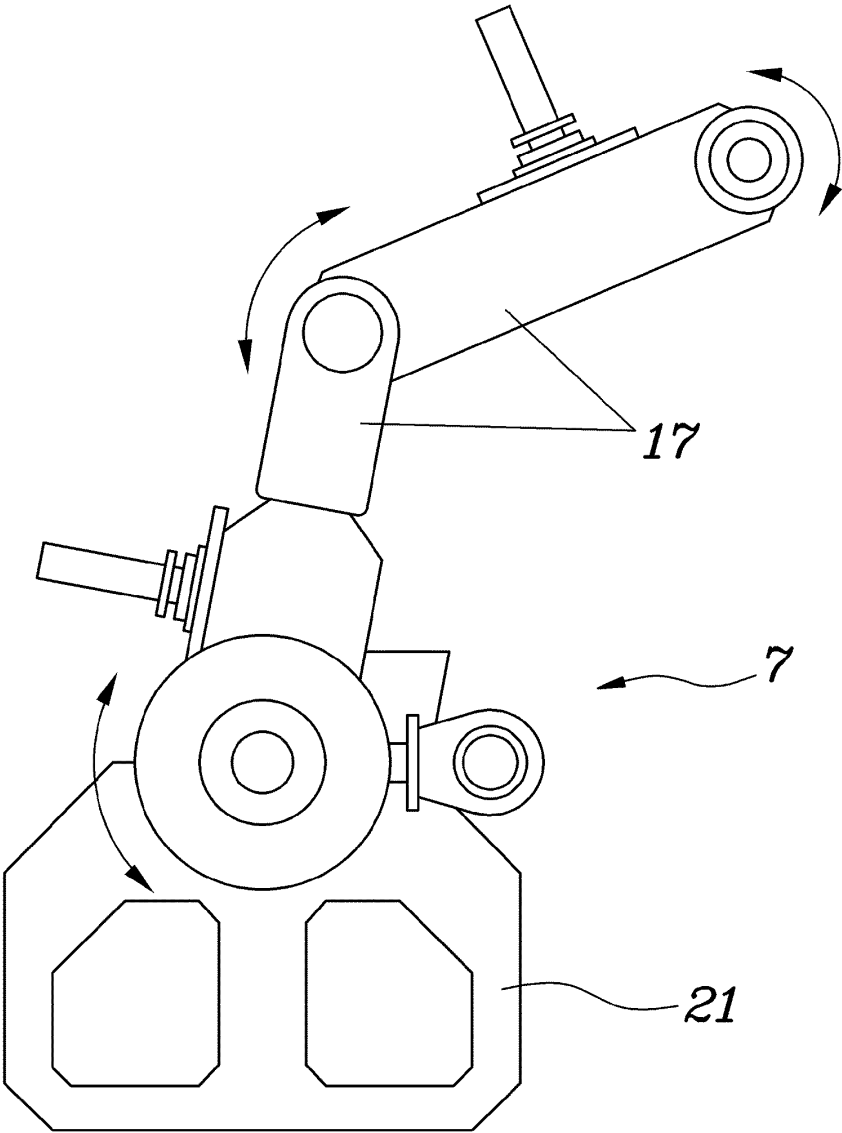
[도5]



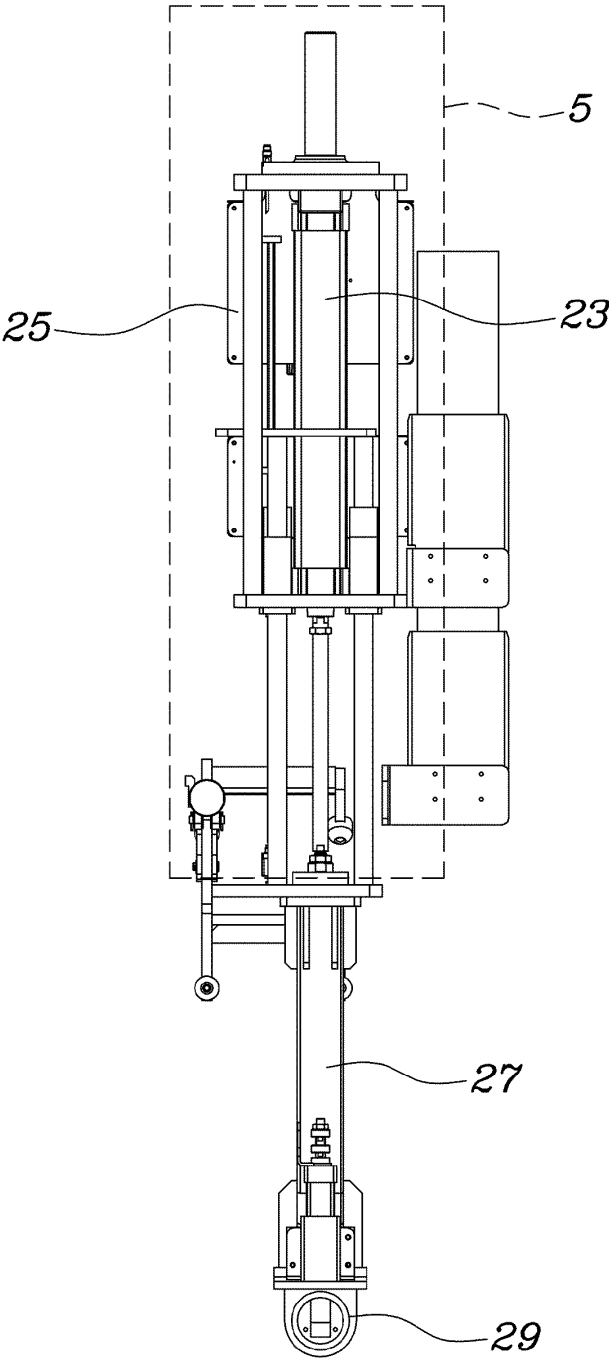
[도6]



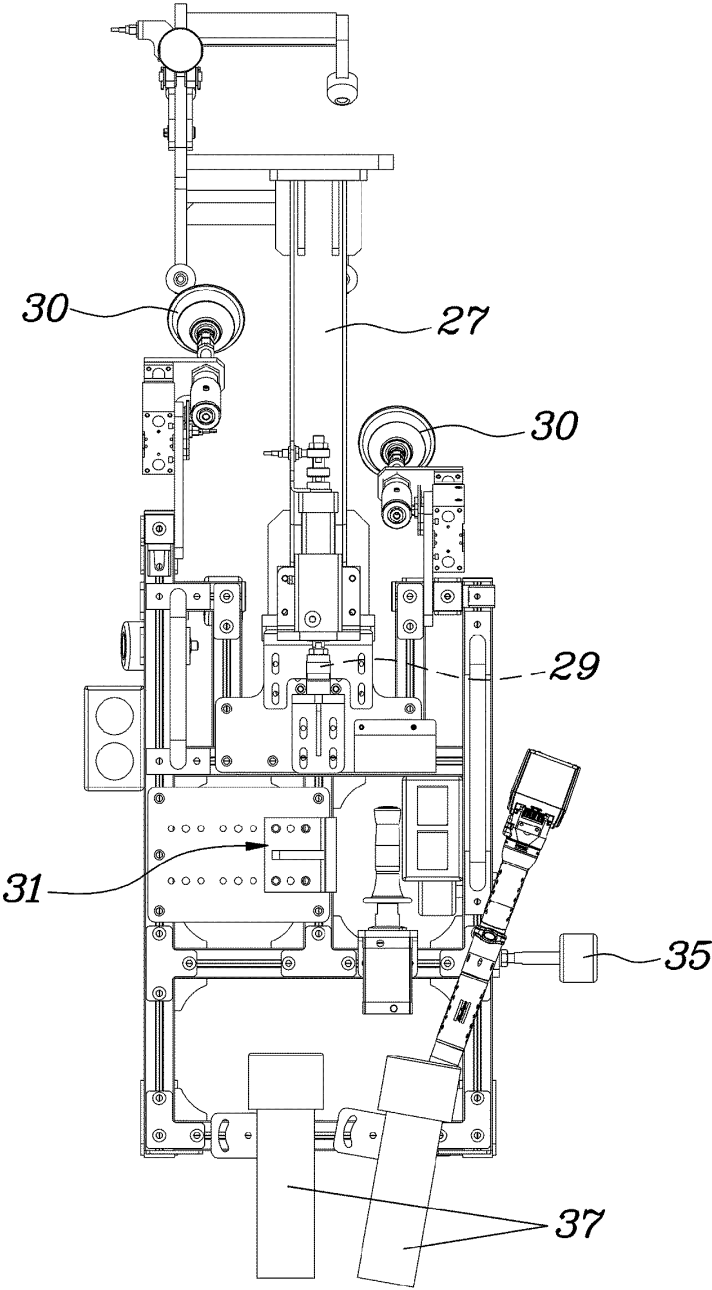
[도7]



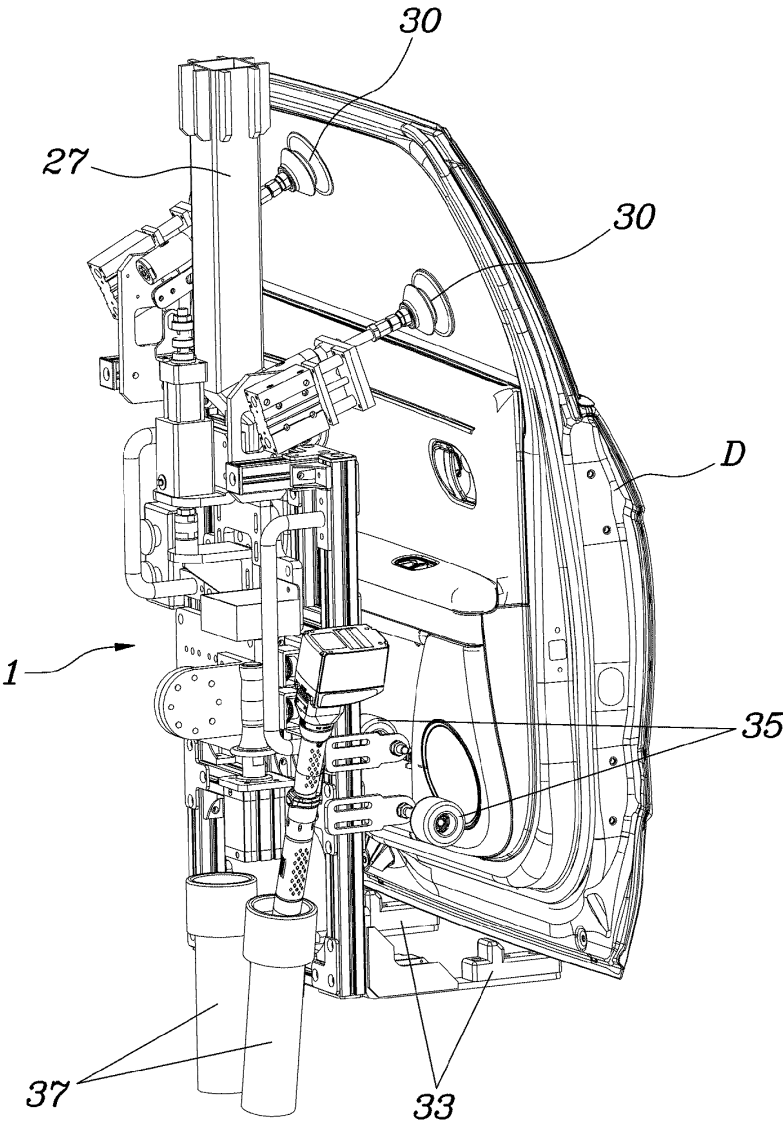
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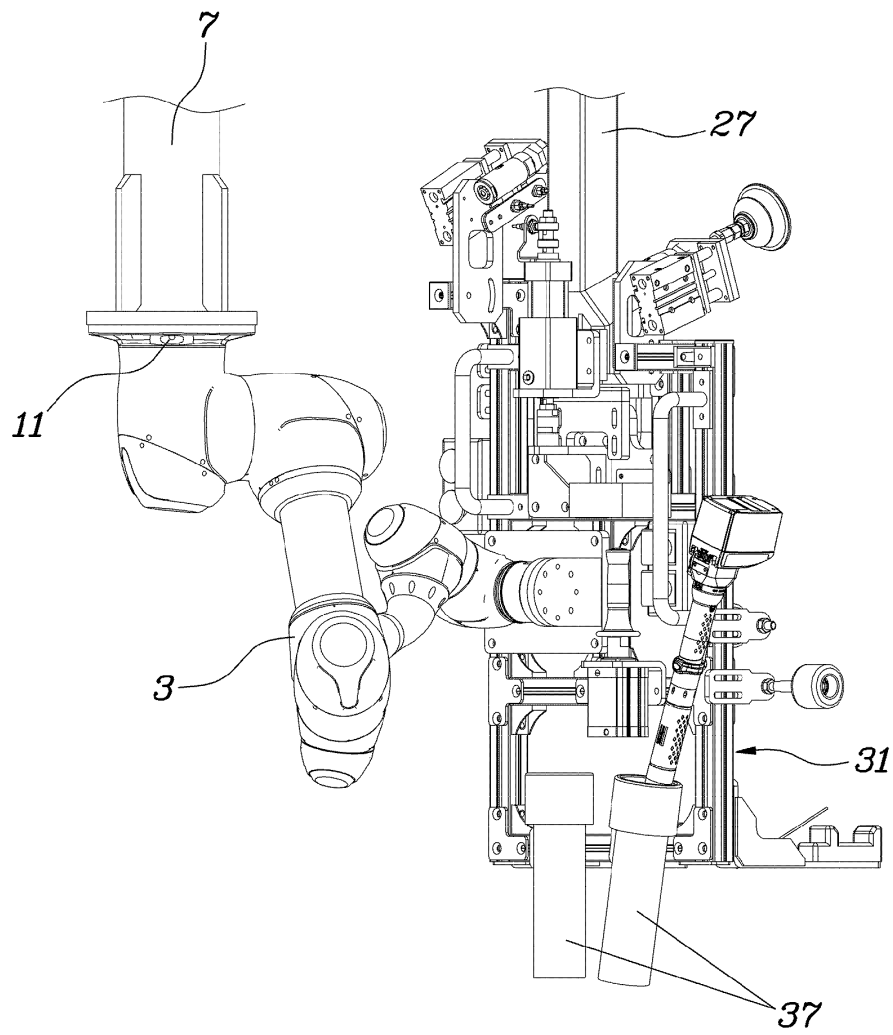
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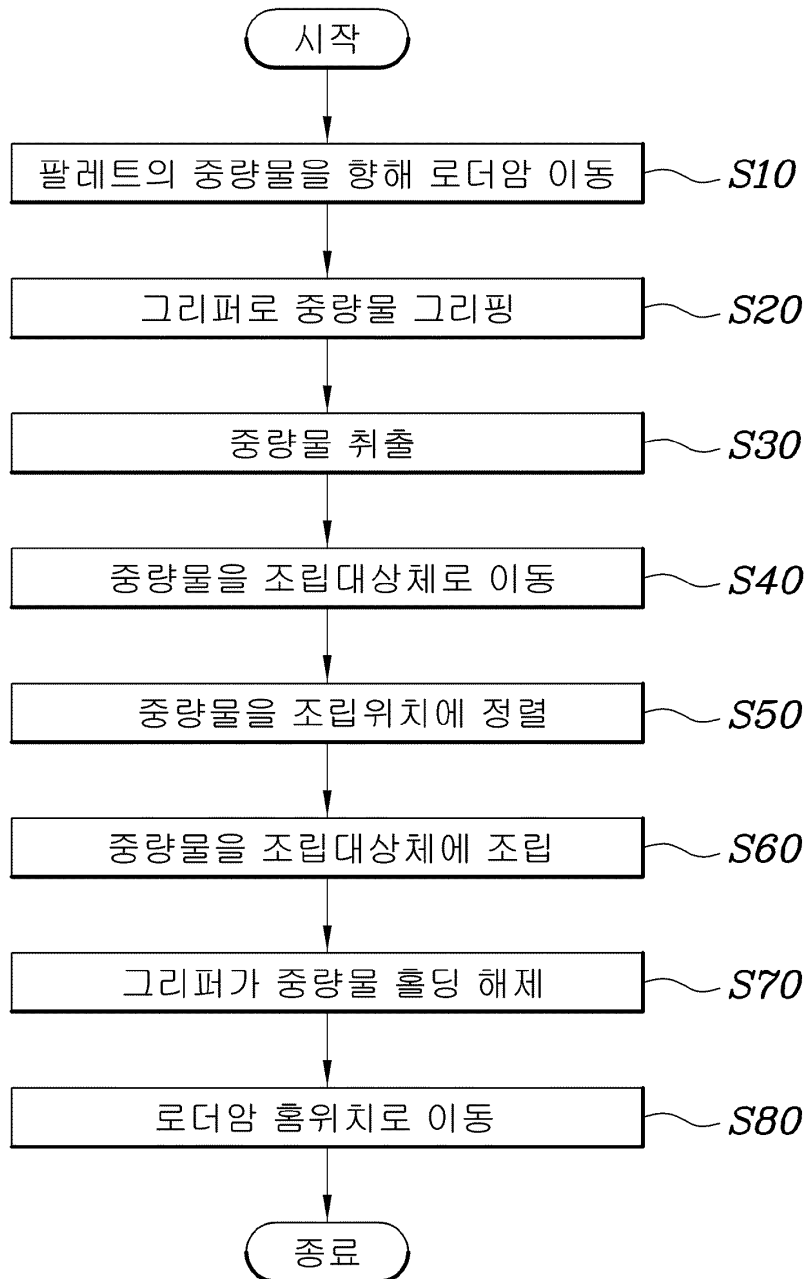
[도10]



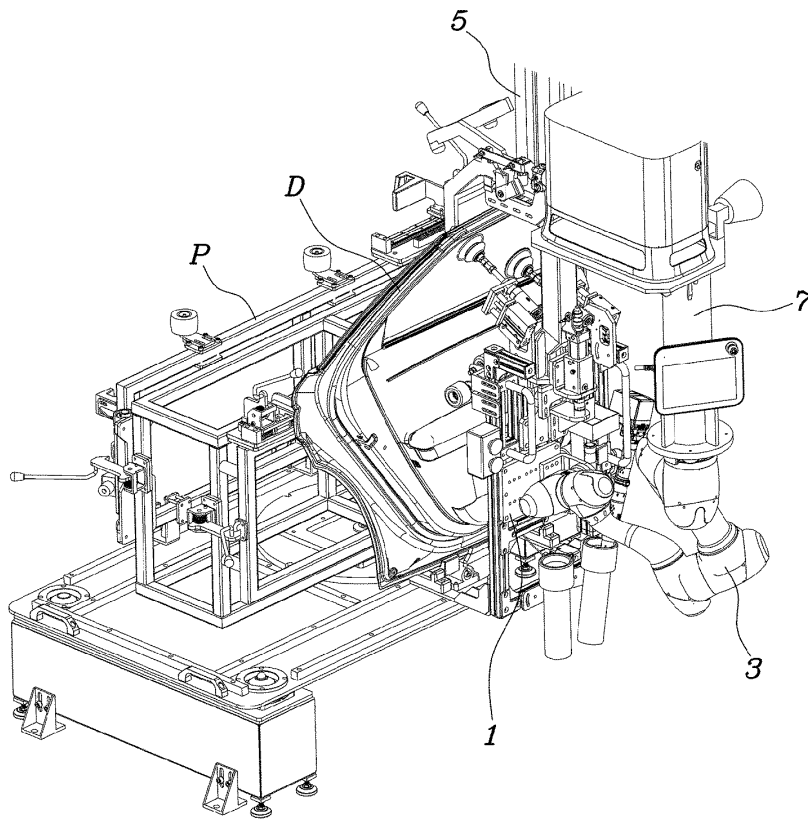
[도11]



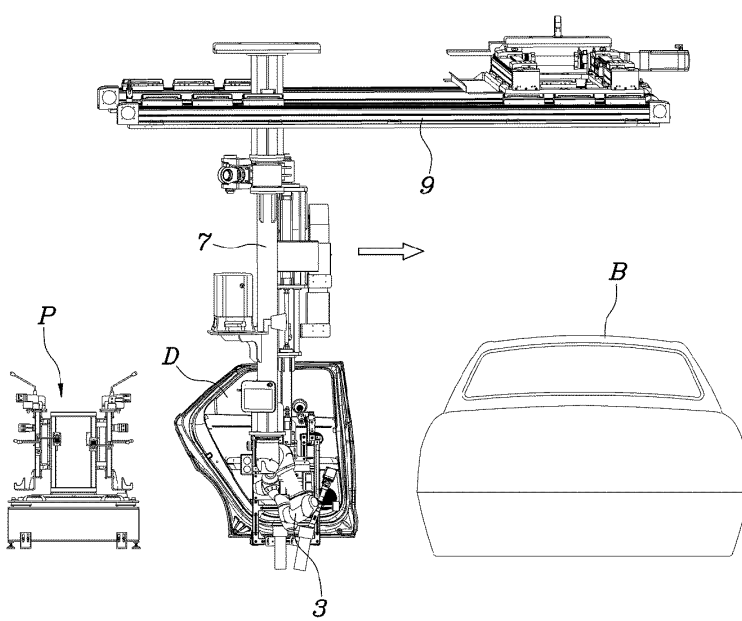
[도12]



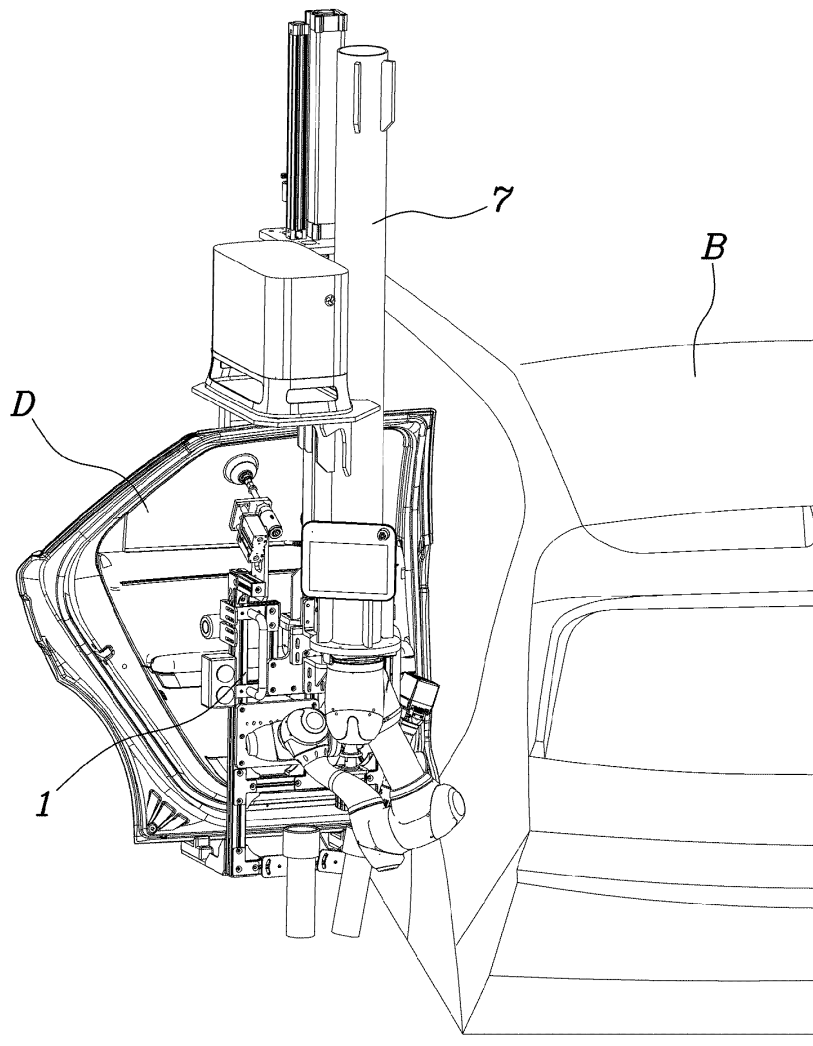
[도13]



[도14]



[도15]



[도 16]

협동로봇	밸런서	그리퍼진공흡착컵	서보갠트리
로더안을도어클램페이동 - 도어위치: 팔레트	■ 자동운전mode 도어그리퍼자세설정	■ Load guided mode 중량지지: 그리퍼	■ 로더이송 홀위치→도어취출위치
도어그리퍼 - 도어위치: 팔레트	■ 직접교시mode	■ 진공흡착 OFF→ON	■ 로더정지 도어취출위치
도어취출 - 도어위치: 그리퍼	■ 자동운전mode 도어취출자세설정	■ 진공흡착 ON	■ 로더정지 도어취출위치
도어이송 - 도어위치: 그리퍼	■ 자동운전mode 도어장착자세설정	■ 진공흡착 ON	■ 로더이송 도어취출위치→도어장착 위치
도어정렬및장착 - 도어위치: 그리퍼	■ 원순응제이mode 사람조작의력에의한위치 설정	■ 진공흡착 ON	■ 로더정지 도어장착위치
도어장착및분할그리퍼 - 도어위치: 차량바디	■ 직접교시mode	■ 진공흡착 ON→OFF	■ 로더정지 도어장착위치
로더안출위치가이동 - 도어위치: 차량바디	■ 자동운전mode 홀위치가자세설정	■ 진공흡착 OFF	■ 로더이송 도어장착위치→열비홀위치