

ABSTRACT

The present disclosure provides a distribution robot, and a control method and control device thereof, relating to the field of logistics distribution. According to the present disclosure, a top plane of a distribution robot body is fully used, a touch screen is vertically arranged on one side of the top plane, and parcel contour measuring units are arranged on the top plane of the distribution robot body and the touch screen, such that whether the size of a parcel exceeds a range can be determined very conveniently and rapidly; and a gravity sensing device is arranged below the top plane, such that the distribution robot can automatically weigh and price the parcel and determine whether the total weight of the parcel exceeds the range, operation is simple and convenient, and the efficiency is high.