

SYSTEM, APPARATUS, AND METHOD FOR MONITORING A SUBSEA FLOW DEVICE

BACKGROUND OF THE INVENTION

[0001] 1. Field of the Invention

[0002] This invention relates to the monitoring of a subsea flow device, such as the monitoring of the temperature of a subsea flow line used in the production of fluids from a hydrocarbon reservoir, and the powering of such a monitoring operation.

[0003] 2. Description of Related Art

[0004] In the production of fluids from a subsea hydrocarbon reservoir, a variety of subsea flow devices are typically used, such as a pipeline or flowline that is disposed on the seafloor and provides a passage through which the fluids be communicated. For example, a subsea well can provide produced fluids from the subsea reservoir to a subsea flowline that carries the fluids away from the well. The flowline can carry the fluids to an on-shore facility, other subsea equipment, a riser that carries the fluid to a topside facility, or the like. Other subsea flow devices can include flow storage, actuation, or control equipment, such as tanks, pumps, motors, valves, and the like.

[0005] The monitoring of such subsea flow devices can be important to achieving successful and optimal production from the well. For example, subsea flowlines that carry high temperature fluids can be exposed to severe temperature gradients and variations, especially for flowlines that operate in deep water. Even for insulated flowlines, high thermal gradients can result between the inside and outside of the flowline by virtue of the difference in temperature of the produced fluids inside the flowline and the seawater outside the flowline. Temperature variations over time can result from changes in the flow of the produced fluid, such as between times of production when the presence of the produced fluid can heat the pipe, and times of no production when the pipe is either empty of produced fluid or contains produced fluid that cools when it does not flow. The thermal effects on the pipeline can include stress, strain, and movement of the pipeline on the seafloor. In some cases, such effects can threaten the integrity of the flowline.

[0006] A subsea flowline can be monitored in an effort to assess the ongoing integrity of the flowline and thereby facilitate planned preventative measures and avoid unplanned interventions for unforeseen events, such as unplanned interruption of production. One conventional monitoring method includes performing periodic visual inspections of the flowlines using a Remotely Operated Vehicle (ROV) that can travel along the flowline and gather information with a camera. Alternatively, an in-place monitoring system can be installed on the flowline. The system can include multiple transducers that detect thermal or other data from a plurality of locations along the flowline, and the transducers can communicate the data via a fiber optic cable that extends along the flowline to a receiver. In some cases, the transducers can be powered by the thermal differential that exists between the flowline and the surrounding seawater. While the monitoring system could potentially provide more information than a visual inspection, such systems can be complex, expensive, and unreliable, e.g., because the fiber optic cable can break. Further, the installation of the system can be incompatible with some types of flowlines and certain flowline deployment techniques, and can increase the cost of providing, deploying, and maintaining the flowline.

[0007] A continued need exists for an improved system, apparatus, and method for monitoring a subsea flow device, such for monitoring the temperature or other characteristics along a flowline that is disposed on the seafloor and carries hot produced fluid in an environment of cold sea water. The system, apparatus, and method should be compatible with different types of deployment and provide reliable monitoring of the flow device.

SUMMARY OF THE INVENTION

[0008] The embodiments of the present invention generally provide a system, apparatus, and method for monitoring a subsea flow device, such as a subsea flowline that carries produced fluids from a subsea well. The apparatus generally includes a thermoelectric device and a sensor. The thermoelectric device is adapted to generate electric power from a thermal potential between the subsea flow device and surrounding seawater. For example, the subsea flow device can be a subsea flowline that is formed of a plurality of successive pipe segments joined at joints, and the thermoelectric device can be mounted to the flowline at one of the joints. The apparatus can be attached to the flowline during assembly and deployment of the flowline. With the flowline in

operation, a temperature differential can exist across the thermoelectric device by virtue of the temperature difference between the relatively hot produced fluids in the flowline and the relatively cold seawater surrounding the flowline.

[0009] The sensor is powered by the thermoelectric device and adapted to monitor a characteristic of the flow device and provide a radiation output that is indicative of the monitored characteristic. For example, the sensor can be configured to monitor the temperature of and/or the strain in the flowline and communicate a signal that is indicative of the temperature and/or strain by varying the radiation output to indicate the characteristic(s) monitored by the sensor, such as by providing a varying light output. The light output can be provided on the flowline, i.e., at the location of the flowline so that it can be observed subsea along with the flowline. The apparatus can also include a solar cell and/or a battery. The solar cell can be configured to receive sunlight to charge the battery before deployment of the apparatus, receive light from an underwater source after deployment of the apparatus, and power the sensor to monitor the characteristic of the flow device.

[0010] In some cases, the apparatus includes a memory that is collocated with the thermoelectric device and the sensor. The memory can be adapted to store information from the sensor that is indicative of the measured characteristic over a period of time and output the information for the period of time.

[0011] One system of the present invention for monitoring a subsea flow device includes a plurality of the apparatuses. Each of the apparatuses can be disposed respectively at successive joints along the length of the flowline. In some cases, each apparatus located at a respective joint can also be configured to communicate signals indicative of the characteristic at a plurality of joints to a successive one of the apparatuses located at a joint successive to the respective joint.

[0012] According to another embodiment, the present invention provides a method for monitoring a subsea flow device. The method includes generating electric power from a thermal potential between the subsea flow device and surrounding seawater, using the electric power to operate a sensor and thereby monitoring a characteristic of the flow device, and providing a radiation output that is indicative of the characteristic monitored by the sensor.

[0013] The method can include using a solar cell to receive light from an underwater source and thereby provide light-derived power, and powering the sensor with the light-derived power. In some cases, a solar cell is used to receive sunlight before the flow device is deployed to a subsea location and thereby provide sunlight-derived power. For example, the solar cell can receive light before and immediately after entering the water, and the solar cell can convert the light to electricity to power the sensor, thereby allowing the sensor to monitor the flowline during the installation of the flowline. A battery is charged with the sunlight-derived power, and the sensor is powered with the battery when the thermal potential is not sufficient for powering the sensor. Subsequent to the powering of the sensor with the battery, the solar cell can also be used to receive light from an underwater source and thereby provide light-derived power, which can be used to power the sensor. For example, the underwater source can be provided by an underwater vehicle, which can also detect the radiation output from the sensor to thereby determine the characteristic monitored by the sensor.

[0014] The method can also include mounting an apparatus to the subsea flow device, the apparatus being configured to perform the operations of generating the electric power, using the electric power, and providing the radiation output. More particularly, the subsea flow device can be a subsea flowline that has a plurality of successive pipe segments that are joined at joints, and the thermoelectric device can be mounted to the pipe at one of the joints. The radiation output can be provided by varying a light output on the flowline to thereby indicate the characteristic of the flowline, e.g., a temperature and/or a strain of the flowline. The operations of generating the electric power, using the electric power, and providing the radiation output can be performed at a plurality of locations at successive positions along the length of the flowline. Further, an underwater vehicle can be passed along the flowline to successively detect the radiation output from the sensors and thereby determine the characteristic monitored by each of the sensors.

[0015] Information from the sensor of each apparatus can be stored in a memory mounted on the subsea flow device. The information can be indicative of the characteristic over a period of time, and the information can be output for the period of time from the memory. In some cases, a signal that is indicative of the temperature and/or strain of the flow device can be communicated from the sensor to a distal receiver. The operations of generating electric power, using the power, and providing

the radiation output can include generating electric power at a plurality of locations along the subsea flow device, using the electric power to operate a sensor at each location, and providing a radiation output at each location that is indicative of the characteristic monitored by the sensor at the location. Signals indicative of the characteristic monitored by a plurality of the sensors can be communicated from each sensor to a successive one of the sensors at a successive one of the locations such that the signals are communicated step-wise along the subsea flow device. For example, each sensor can be configured to communicate wirelessly and directly with at least two successive sensors along the subsea flow device.

[0016] The system, apparatus, and method of the present invention can generally provide monitoring of the flow device, information which can be useful in understanding and maintaining the integrity of the flow device and assisting in keeping the flow device in operation. In some cases, each monitoring apparatus can be relatively simple, small, and inexpensive compared to conventional, more complex systems.

[0017] BRIEF DESCRIPTION OF THE DRAWINGS

[0018] Having thus described the invention in general terms, reference will now be made to the accompanying drawings, which are not necessarily drawn to scale, and wherein:

[0019] FIG. 1 is a schematic view illustrating a system for monitoring a subsea flow device according to one embodiment of the present invention;

[0020] FIG. 2 is a schematic view illustrating the system of FIG. 1 during assembly and deployment;

[0021] FIG. 2A is an enlarged view illustrating a joint between two adjacent pipe segments of the system of FIG. 2;

[0022] FIG. 3 is a section view schematically illustrating one monitoring apparatus and a joint of the flowline of the system of FIG. 1; and

[0023] FIG. 4 is a schematic view illustrating a portion of the system of FIG. 1, shown with an underwater vehicle collecting information from the system.

DETAILED DESCRIPTION OF THE INVENTION

[0024] The present invention now will be described more fully hereinafter with reference to the accompanying drawings, in which some, but not all embodiments of the invention are shown. Indeed, this invention may be embodied in many different forms and should not be construed as limited to the embodiments set forth herein; rather, these embodiments are provided so that this disclosure will satisfy applicable legal requirements. Like numbers refer to like elements throughout.

[0025] Referring now to the drawings and, in particular, to FIG. 1, there is shown a system **10** for monitoring a subsea flow device according to one embodiment of the present invention. Generally, the system **10** can be used to monitor a subsea flowline **12**, a pipeline that is configured to receive produced fluid from a subsea well **14** and deliver the fluids along the seabed **16**, upward to a floating surface facility **18**, to a land facility, or otherwise. It is appreciated that the system **10** can include and can monitor other types of flow devices such as valves, spools, pumps, motors, and other subsea equipment.

[0026] In the illustrated embodiment, the subsea flowline **12** is made of a plurality of successive pipe segments **20** that are joined to form a desired length. The topside facility **18** can be a structure that is rigidly fixed to the seabed **16**, a floating structure, or a moored structure. For example, in some cases, topside facility **18** can be a ship with special equipment for assembling and deploying the flowline **12**. The flowline **12** can extend to the topside facility **18**, or the flowline **12** can be connected to the topside facility **18** by a riser **22** or other tubular member.

[0027] FIG. 1 illustrates the flowline **12** in a typical deployed configuration, extending from one or more subsea wells **14** to a pipeline end terminal ("PLET") **24**. At a first end **26**, the flowline **12** is configured to receive produced fluid from the well **14** and a reservoir **28** under the seabed **16**, and additional equipment such as pumps, can be provided facilitating the transportation and handling of the fluid. At the opposite, second end **30**, the flowline **12** can be connected by the PLET **24** to the riser **22** that delivers the produced fluid to a topside facility **18**, which can be the same or a different structure than the facility **18** that was previously used to deploy the flowline **12**. The PLET **24** can be configured to accommodate movement of the end **30** of the flowline **12**, e.g., to allow the flowline **12** to extend or contract as it heats or cools.

[0028] FIG. 2 illustrates the assembly and deployment of the flowline 12, which, in the illustrated embodiment, is formed of a plurality of the pipe segments 20 and defines joints 32 between adjacent segments 20. Before deployment of the flowline 12, the pipe segments 20 can be provided to the topside facility 18 in uniform lengths that are sufficiently short to facilitate transport and handling, such as lengths of about 40 feet or less that can be delivered by truck and otherwise handled using conventional equipment. The pipe segments 20 are typically joined as part of the deployment operation, using assembly equipment that can be provided at the topside location. For example, the topside facility 18 can be, or can include, a ship or other facility with equipment for handling and assembling the pipe segments 20. The segments 20 can be assembled and lowered according to various conventional methods, typically by joining successive segments 20 to form a long flowline 12 that is successively lowered below the water surface 34 and deployed on the seabed 16.

[0029] The connections or “field joints” 32 of successive pipe segments 20 typically included welded connections 36, which are formed by welding the segments 20 together during deployment. If the pipe segments 20 are multi-layer tubular members that include thermal insulation, the insulation typically does not extend to the ends of the segments 20. For example, as shown in FIGS. 2A and 3, the pipe segments 20 can include steel pipe 40 with insulation 42 on the outside surface 44 thereof. The insulation 42 on each segment 20 can leave an end portion 46 of the steel pipe 40 exposed before assembly of the segments 20. Thus, each segment 20 can have a small end portion 46 at each end where the steel pipe 40 is exposed to facilitate the welding of the successive segments 20. After welding two successive segments 20, the gap or “field joint area” 48 between the insulation 42 of the two segments 20 can be filled with a fluid field joint fill material 50, such as injection-molded polypropylene, that cures or dries before or after the joint 32 is lowered into the water and to the seabed 16.

[0030] The monitoring system 10 as illustrated in FIGS. 1 and 2 includes a plurality of monitoring apparatuses (individually indicated in FIG. 2 by reference numerals 60', 60'', 60''', 60'''' and referred to collectively by reference numeral 60), which are disposed at successive joints 32 along the length of the flowline 12. More particularly, at least one monitoring apparatus 60 can be disposed at each joint 32, and each apparatus 60 can be disposed on the flowline 12 during the deployment of the flowline 12. For example, if the flowline 12 is assembled from a plurality of insulated

segments 20, the apparatuses 60 can be attached to the flowline 12 at the joints 32, e.g., before the field joint material 50 is applied. Thus, as illustrated in FIG. 3, the apparatus 60 can be disposed within the field joint material 50 so that the field joint material 50 at least partially surrounds the apparatus 60 and, in some cases, the apparatus 60 is disposed between a layer of the field joint material 50 and the underlying steel pipe 40.

[0031] The apparatuses 60 can be provided various locations along the flowline 12, e.g., at some or all of the field joints 32. Each apparatus 60 can be configured to monitor the flowline 12 at the position of the apparatus 60, e.g., at the respective joints 32 where the apparatus 60 is located, and thereby provide an output that is indicative of the flowline 12. Thus, a condition or characteristic of the flowline 12, and throughout the length of the flowline 12, can be determined by receiving signals from the various monitoring apparatus 60 along the length of the flowline 12. In some cases, the apparatuses 60 can be placed at select locations along the flowline 12 where the flowline 12 is believed to be more likely to experience bending, buckling, stress, strain, temperature variations, or other conditions. Each monitoring apparatus 60 can also include one or more electric generation devices configured for generating power that can be used for monitoring the flowline 12 and providing an output representative of the flowline 12, e.g., so that the apparatus 60 is not dependent on an energy supply that must be entirely pre-stored in the apparatus 60 before deployment.

[0032] FIG. 3 is a sectional view illustrating one of the monitoring apparatuses 60 attached to a flowline 12 through which a hot, mixed-phase produced fluid 82 is flowing. As illustrated, the apparatus 60 includes a sensor 62 for monitoring a characteristic of the flowline 12. For example, the sensor 62 can include a strain gauge for detecting strain in the flowline 12; a thermocouple, resistance temperature detector, or other device for detecting the temperature or temperature change of the flowline 12; a location or motion detection device for detecting movement or position of the flowline 12; and/or other devices for monitoring other characteristics of the flowline 12. The apparatus 60 generally can be attached to the flowline 12 by mechanical connections, adhesives, or the like. For example, a thermal epoxy resin can be used to connect the apparatus 60 and, in particular, to achieve a sufficient bond between the sensor 62 and the steel pipe 40.

[0033] The sensor 62 can be configured to provide a light output that is indicative of the temperature. For example, the sensor 62 can include an electromagnetic radiation

emission device 64, such as a light emitting diode or other light emitter. The radiation emission device 64 can be adapted to provide a radiation output that varies according to the monitored condition of the flowline 12. For example, if the radiation emission device 64 is a light emitting diode, the diode can be configured to pulse at a frequency that indicates the condition of the flowline 12, shine with an intensity that indicates the condition of the flowline 12, change color to indicate the condition of the flowline 12, emit a coded pattern that indicates the condition of the flowline 12, or otherwise change its output to indicate the condition of the flowline 12. In some cases, the radiation emission device 64 can vary in numerous (or limitless) different variations, e.g., at any frequency, intensity, or color in a given range. Alternatively, the radiation emission device 64 can be configured to provide a limited number of variations in output to indicate certain discrete conditions of the flowline 12. For example, the emission device 64 can be configured to emit a first color if the flowline 12 is operating at a first condition (such as a normal condition), and a second color, or no color, if the flowline 12 is operating at a second condition (such as an abnormal condition).

[0034] The sensor 62 can be electrically powered by one or more electric generation devices, such as a thermoelectric device 66 and/or a solar cell 68, as illustrated in FIG. 3. The thermoelectric device 66 can operate according to the Peltier--Seebeck effect to generate electricity from a thermal potential, such as a thermal potential that may exist between the fluid in the flowline 12 and the seawater 70 that surrounds the flowline 12. A first side 72 of the thermoelectric device 66 can be directed radially inward toward the outside surface 44 of the steel pipe 40, and the second side 74 of the thermoelectric device 66 can be directed radially outward from the pipe 40 toward the seawater 70 that surrounds the flowline 12 when disposed subsea. When a temperature differential exists between the outside surface 44 of the pipe 40 and the seawater 70, the thermoelectric device 66 can generate electricity, which can be used to power the sensor 62.

[0035] The solar cell 68 can be configured to receive light and generate electricity from the solar energy. The solar cell 68 can be directed outward from the steel pipe 40 and configured to receive sunlight or other light that would otherwise impinge on the flowline 12. The solar cell 68 can be used instead of, or in combination with, the thermoelectric device 66. In either case, a battery 80 or other energy storage device can also be provided for storing energy from the electric generation device(s) 66,

68 so that the energy can be used at a time when sufficient generation of electricity may not be possible. For example, before the apparatus 60 is deployed subsea, the solar cell 68 may be exposed to sunlight, e.g., while the pipe segments 20 are stored or assembled, and the solar cell 68 can convert the sunlight to charge the battery 80 before deployment of the apparatus 60. In addition, or alternative, to charging a battery, the solar cell 68 can be used to power the sensor 62 prior to deployment and operation of the flowline 12, even though hot fluid is not passing through the flowline 12 and the thermoelectric device 66 is typically unable to power the sensor 62. For example, the solar cell 68 can be used to power the sensor 62 during the process of installing the flowline 12 to determine stresses, strains, or other characteristics of the flowline 12 before its final deployment. After deployment of the flowline 12 to its subsea location, the solar cell 68 may not receive sufficient light to power the sensor 62. At that time, the thermoelectric device 66 may generate sufficient energy to power the sensor 62, e.g., if the flowline 12 is being used to convey hot fluid 82. Energy from the thermoelectric device 66 may also be stored in the battery 80. If the thermoelectric device 66 is not able to generate sufficient energy, e.g., because hot fluid 82 has not entered the flowline 12 yet or the fluid in the flowline 12 has been evacuated or cooled during a period of non-use of the flowline 12, the battery 80 can be used to power the apparatus 60.

[0036] The output of the electric generation devices 66, 68 can be controlled by a controller 84. The controller 84 can communicate with the components of the apparatus 60 and control the operation of the apparatus 60 and/or each component of the apparatus 60. For example, the controller 84 can be configured to operate the apparatus 60 during some periods and not during others, such as according to a predetermined schedule or according to parameters of the environment of the apparatus 60. In some cases, the controller 84 can also process the data collected by the sensor 62.

[0037] Information detected by the sensor 62 can be stored in the apparatus 60, communicated from the apparatus 60 in real time, and/or communicated from the apparatus 60 in a delayed manner. More particularly, the sensor 62 can include a memory 86 that is configured to receive a signal from the sensor 62 and store some or all of the information from the sensor 62. For example, the memory 86 can store a log of information indicative of the output of the sensor 62 at regular time intervals. Alternatively, the memory 86 can be configured to store only certain information or information occurring at certain times, e.g., data values that are above or below

predetermined thresholds that might indicate that the apparatus 60 is operating outside of a certain mode of operation, such as a high strain level or an extreme change in strain level that could indicate excess stress, damage, movement, or other changes in the flowline 12. The radiation emission device 64 can provide an output signal that generally is indicative of the present detection by the sensor 62, or the radiation emission device 64 can provide an output signal that is representative of data that was previously stored in the memory 86.

[0038] The apparatus 60 can include a transmitter 88 and/or receiver 90, which can be separate or combined devices. The transmitter 88 can be configured to transmit information from the apparatus 60 to another apparatus 60 and/or another receiver. In some cases, the transmitter 88 of a first apparatus 60' on the flowline 12 can be configured to communicate information to a second, successive apparatus 60'' along the flowline 12. The second apparatus 60'' can then communicate information from the first and second apparatuses 60', 60'' to a third, successive apparatus 60''' along the flowline 12, and the communication can continue along the flowline 12 so that information from all of the apparatuses 60 is passed successively along the flowline 12. Such apparatus-to-apparatus communication can be performed via a wire, other media that extends between the apparatuses 60, or through the pipe 40 itself, or the apparatuses 60 can be configured to communicate wirelessly. Each apparatus 60 can also be configured to communicate with more than one of the successive apparatuses 60 so that communication along the flowline 12 is not prevented by the failure of one apparatus 60. For example, the first apparatus 60' can communicate directly to the second and third apparatuses 60'', 60''', the second apparatus 60'' can communicate directly with the third and fourth apparatuses 60''', 60'''', and so on.

[0039] The system 10 can include a receiver that is configured to receive the signals from the various apparatuses 60, either directly from each apparatus 60 or via one or more other apparatuses 60 as described above. The receiver can be located subsea or above the seafloor 34. For example, as shown in FIG. 2, a receiver 92a can be located on the PLET 24, and the receiver 92a can be configured to communicate via an umbilical or other cable 93 with a remote receiver device 92b at a topside location, e.g., via a flying lead connection to the umbilical 93 and/or via a subsea distribution unit or the like. The receiver 92a on the PLET 24 can also detect and record the displacement and/or force loading of the flowline 12, and this information can be stored in the receiver

92a and/or communicated with the topside receiver device **92b**. In some cases, an underwater vehicle, as described below in connection with FIG. 4, can retrieve information from the receiver **92a** on the PLET **24**, i.e., so that the vehicle can obtain from one location various data from the apparatuses **60** and/or information measured at the PLET **24**.

[0040] The solar cell **68** can receive light for powering the apparatus **60** and/or recharging the battery **80** even while the apparatus **60** is disposed subsea. For example, a light source can be passed along the flowline **12** so that the light source successively shines light on the apparatuses **60** along the length of the flowline **12**, thereby providing energy for the apparatus **60**. In particular, as shown in FIG. 4, the light source **94** can be carried by an underwater vehicle **96**, such as an ROV or an automated underwater vehicle (AUV). The underwater vehicle **96** can travel along the length of the flowline **12** and can include cameras or other equipment for visually inspecting the flowline **12**. The light source **94** carried by the underwater vehicle **96** can provide sufficient light to illuminate the flowline **12** for the visual inspection. The light source **94** can also provide sufficient light to the solar cell **68** to temporarily power the apparatus **60**, e.g., so that the apparatus **60** can provide a wirelessly communicated output signal to the underwater vehicle **96**.

[0041] The underwater vehicle **96** includes a receiver **98** that receives the output signal from the apparatus **60**, as indicated by reference numeral **100**. For example, if the radiation emission device **64** is configured to provide a light output, the receiver **98** can be a light detector that measures the intensity, frequency, or other characteristic of the light output. The underwater vehicle **96** can retransmit the information from the apparatus **60** to another, remote receiver, such as the receiver **92**, and/or the underwater vehicle **96** can store the information from each apparatus **60** so that the information can be downloaded from the underwater vehicle **96** after the vehicle **96** completes its inspection of the flowline **12**.

[0042] It is appreciated that the apparatus **60** can generally be relatively simple, small, and inexpensive. Further, the apparatuses **60** can be integrated to form the system **10**, which can be customized to provide any desired type and amount of monitoring and communication, and which can be adapted according to the changing needs of a particular flowline **12** or other monitored device.

[0043] Many modifications and other embodiments of the inventions set forth herein will come to mind to one skilled in the art to which these inventions pertain having the benefit of the teachings presented in the foregoing descriptions and the associated drawings. Therefore, it is to be understood that the invention is not to be limited to the specific embodiments disclosed and that modifications and other embodiments are intended to be included within the scope of the appended claims. Although specific terms are employed herein, they are used in a generic and descriptive sense only and not for purposes of limitation.

WHAT IS CLAIMED IS:

1. An apparatus for monitoring a subsea flow device, the apparatus comprising:
a thermoelectric device adapted to generate electric power from a thermal potential between the subsea flow device and surrounding seawater; and
a sensor powered by the thermoelectric device and adapted to monitor a characteristic of the flow device and provide a radiation output that is indicative of the characteristic.
2. An apparatus according to Claim 1, further comprising a solar cell and a battery, wherein the solar cell is configured to receive sunlight to charge the battery before deployment of the apparatus, receive light from an underwater source after deployment of the apparatus, and power the sensor to monitor the characteristic of the flow device.
3. An apparatus according to Claim 1, wherein the sensor is adapted to vary the radiation output to indicate the characteristic monitored by the sensor.
4. An apparatus according to Claim 1, wherein the subsea flow device is a subsea flowline formed of a plurality of successive pipe segments joined at joints, and wherein the thermoelectric device is mounted to the flowline at one of the joints, and wherein the sensor is configured to monitor at least one of a temperature and a strain of the flowline and communicate a signal indicative of at least one of the temperature and strain by providing a varying light output on the flowline.
5. An apparatus according to Claim 1, further comprising a memory collocated with the thermoelectric device and the sensor, the memory being adapted to store information from the sensor that is indicative of the characteristic over a period of time and output the information for the period of time.
6. A system for monitoring a subsea flow device, the system comprising a plurality of the apparatuses of Claim 4, the apparatuses being disposed respectively at successive joints along the length of the flowline, and wherein each apparatus located at a respective joint is configured to communicate signals indicative of the characteristic at a plurality of

joints to a successive one of the apparatuses located at a joint successive to the respective joint.

7. A method for monitoring a subsea flow device, the method comprising:
generating electric power from a thermal potential between the subsea flow device and surrounding seawater;
using the electric power to operate a sensor and thereby monitoring a characteristic of the flow device; and
providing a radiation output that is indicative of the characteristic monitored by the sensor.
8. A method according to Claim 7, further comprising using a solar cell to receive light from an underwater source and thereby provide light-derived power, and powering the sensor with the light-derived power.
9. A method according to Claim 7, further comprising:
using a solar cell to receive sunlight before the flow device is deployed to a subsea location and thereby provide sunlight-derived power;
charging a battery with the sunlight-derived power; and
powering the sensor with the battery when the thermal potential is not sufficient for powering the sensor.
10. A method according to Claim 9, further comprising:
subsequent to said step of powering the sensor with the battery, using the solar cell to receive light from an underwater source and thereby provide light-derived power;
and
powering the sensor with the light-derived power, wherein the underwater source is provided by an underwater vehicle, and
detecting the radiation output from the sensor with the underwater vehicle to thereby determine the characteristic monitored by the sensor.
11. A method according to Claim 7, further comprising mounting an apparatus to the subsea flow device, the apparatus being configured to perform the steps of generating the electric power, using the electric power, and providing the radiation output, wherein the

subsea flow device is a subsea flowline having a plurality of successive pipe segments joined at joints, and wherein the thermoelectric device is mounted to the pipe at one of the joints.

12. A method according to Claim 11, wherein providing the radiation output comprises varying a light output on the flowline and thereby indicating at least one of a temperature and a strain of the flowline.

13. A method according to Claim 11, wherein the steps of generating the electric power, using the electric power, and providing the radiation output are performed at a plurality of locations at successive positions along the length of the flowline.

14. A method according to Claim 13, further comprising passing an underwater vehicle along the flowline and successively detecting the radiation output from the sensors with the underwater vehicle to thereby determine the characteristic monitored by each of the sensors.

15. A method according to Claim 7, further comprising storing information from the sensor in a memory mounted on the subsea flow device, the information being indicative of the characteristic over a period of time, and outputting the information for the period of time from the memory.

16. A method according to Claim 7, further comprising communicating a signal indicative of at least one of the temperature and the strain of the flow device from the sensor to a distal receiver, and wherein the generating, using, and providing steps comprise generating electric power at a plurality of locations along the subsea flow device, using the electric power to operate a sensor at each location, and providing a radiation output at each location that is indicative of the characteristic monitored by the sensor at the location.

17. A method according to Claim 16, further comprising communicating signals indicative of the characteristic monitored by a plurality of the sensors from each sensor to a successive one of the sensors at a successive one of the locations such that the signals are communicated step-wise along the subsea flow device.

18. A method according to Claim 17, wherein each sensor is configured to communicate wirelessly, directly with at least two successive sensors along the subsea flow device.