

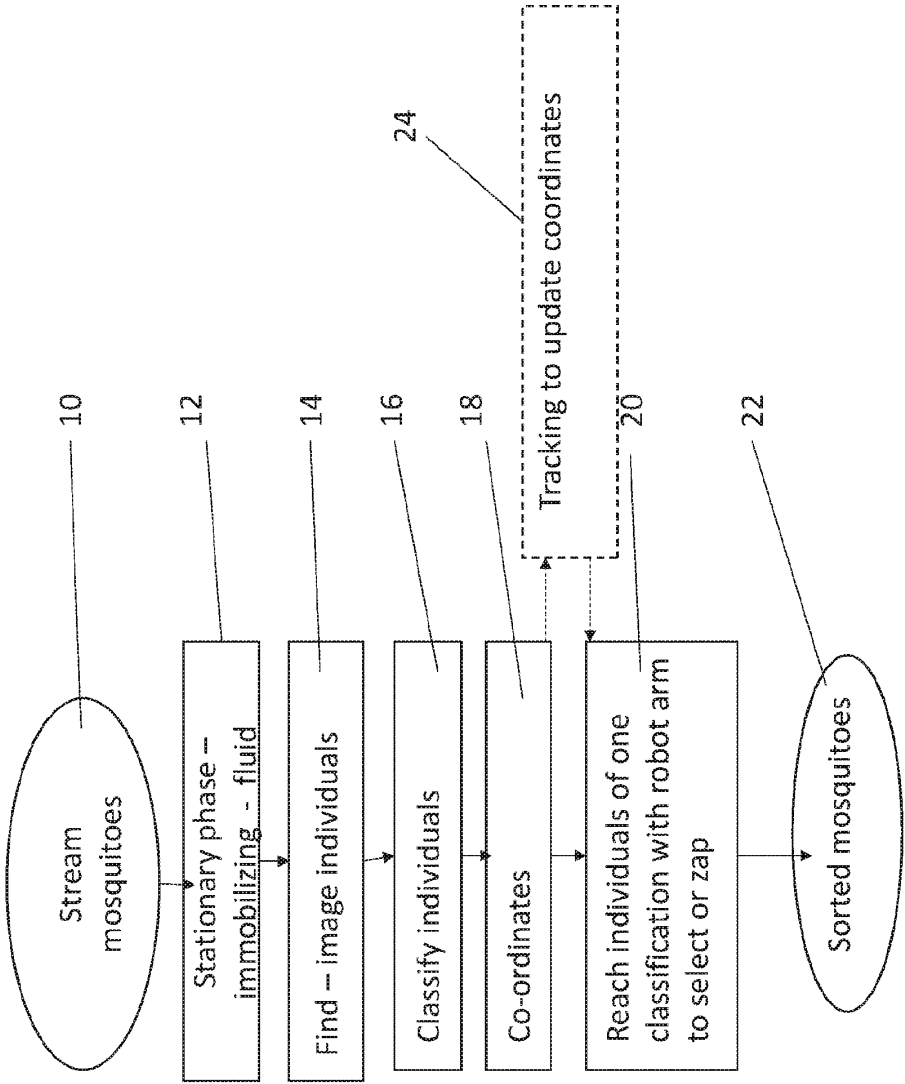
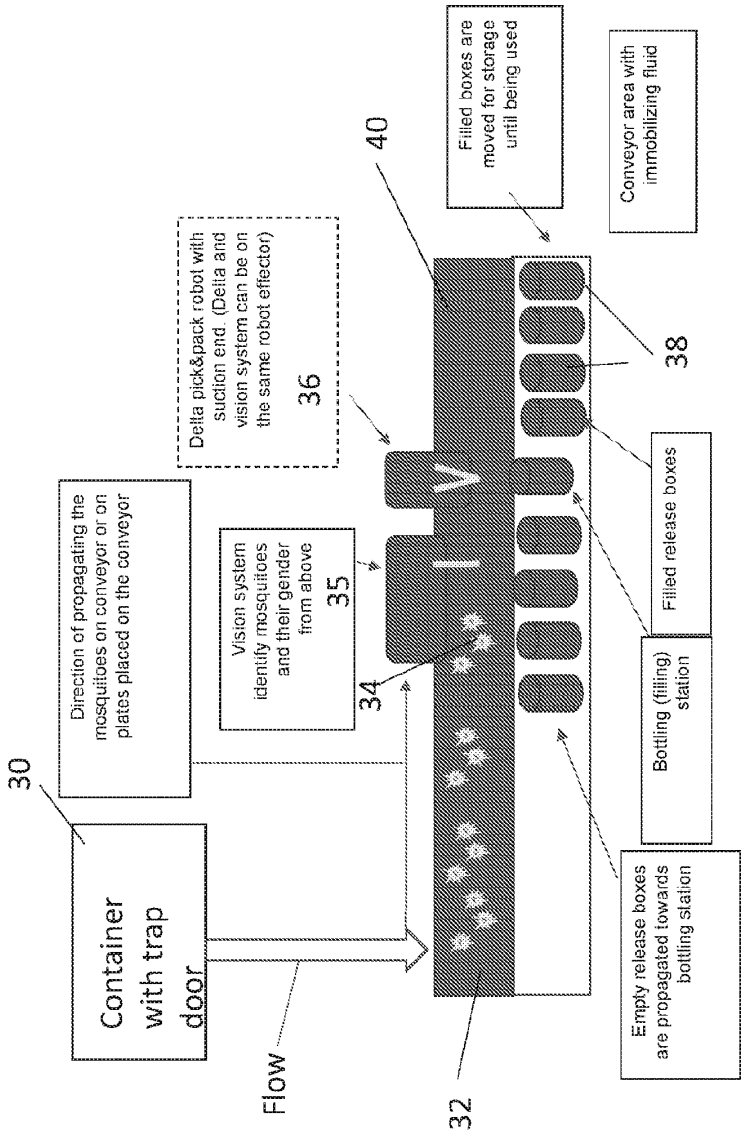


Fig. 1



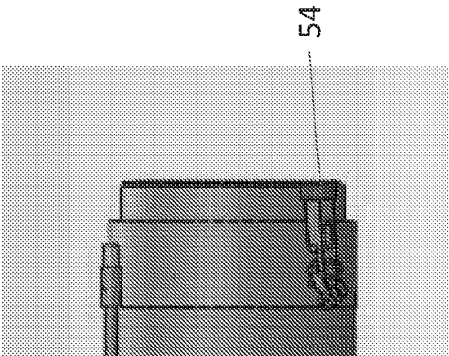


FIG. 3C

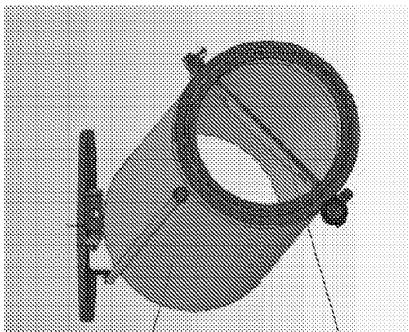


FIG. 3B

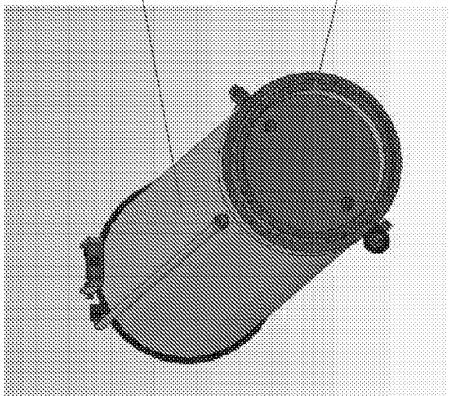
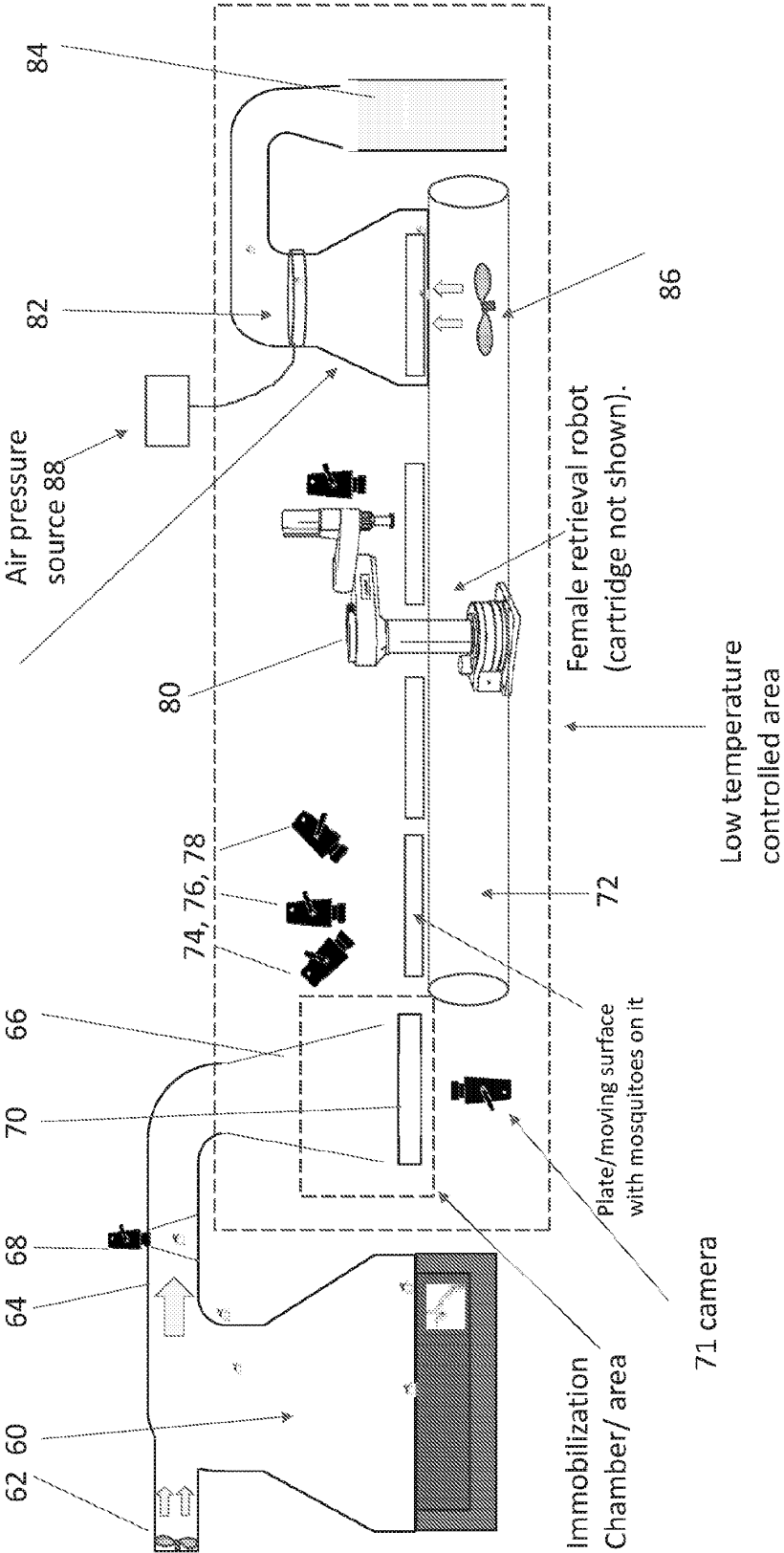
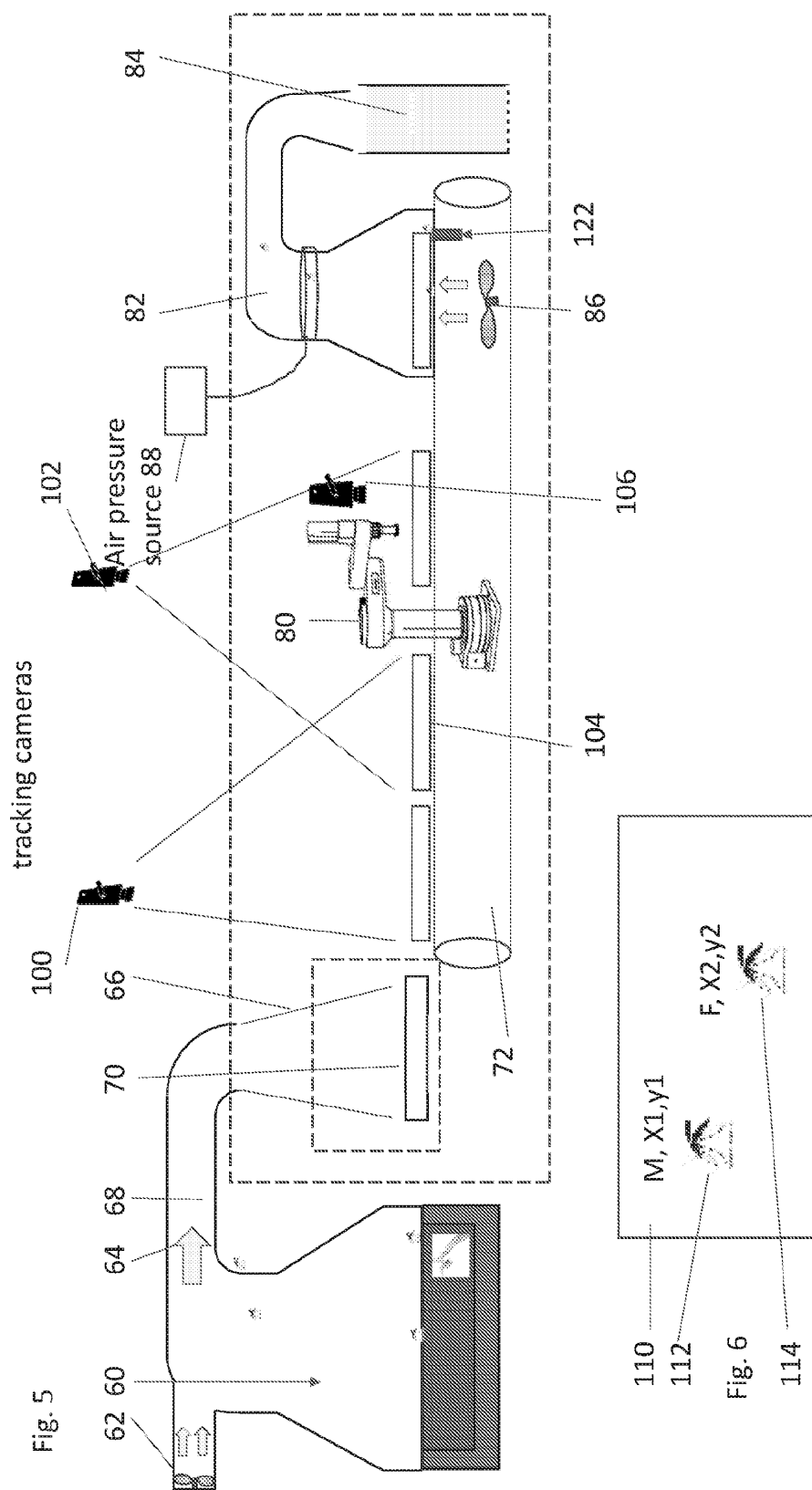


Fig. 3A

Fig. 4





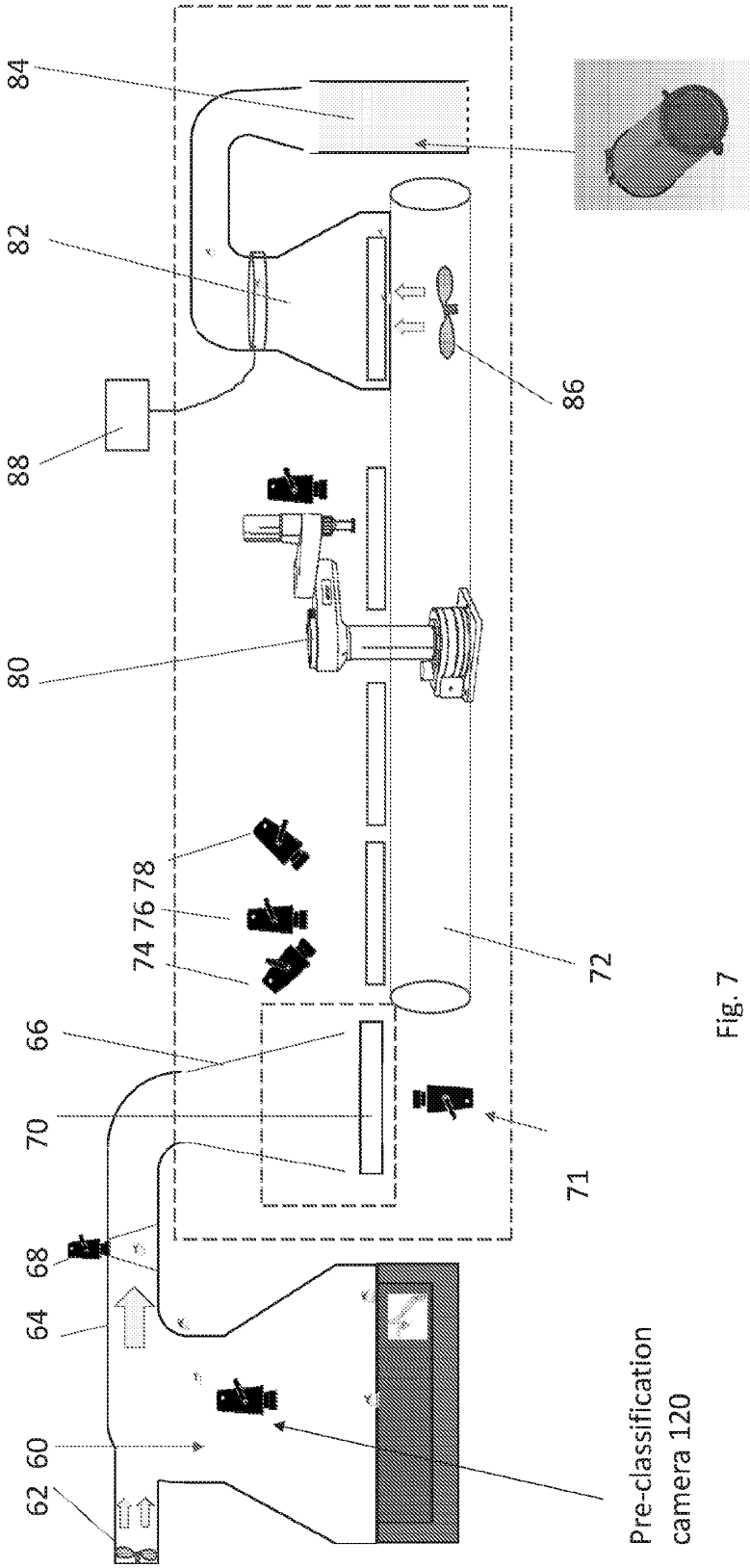


Fig. 7

Pre-classification
camera 120

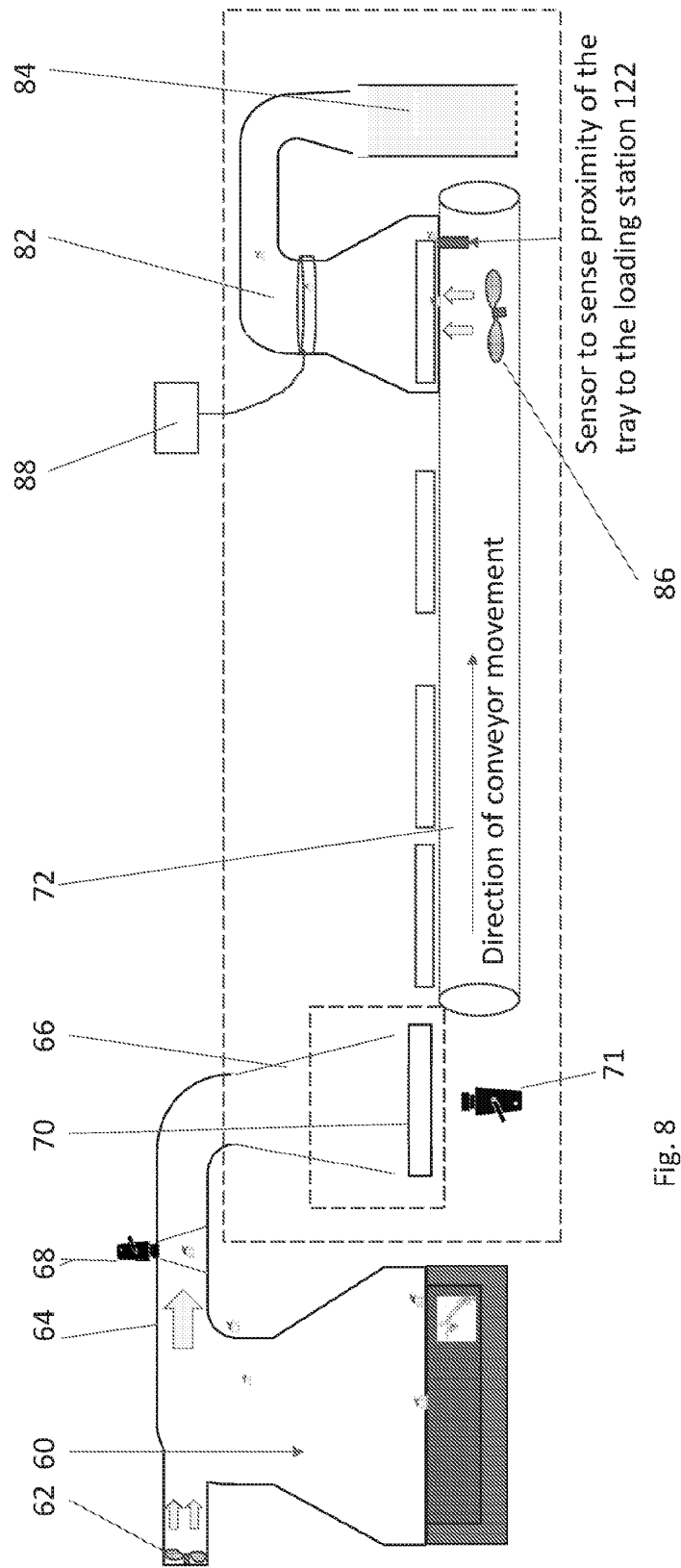


Fig. 8

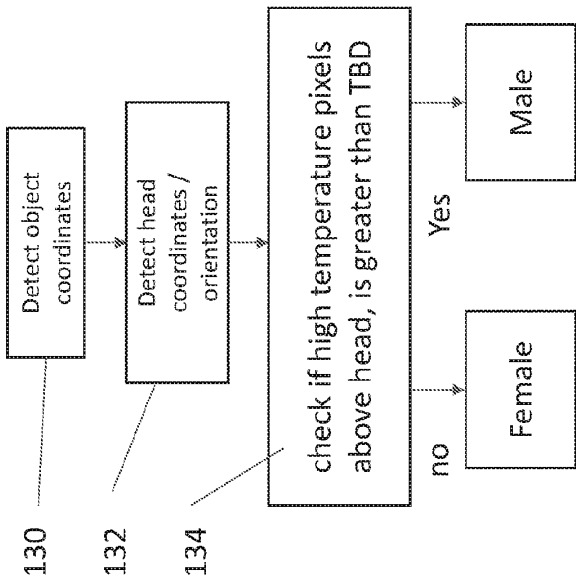


Fig. 10

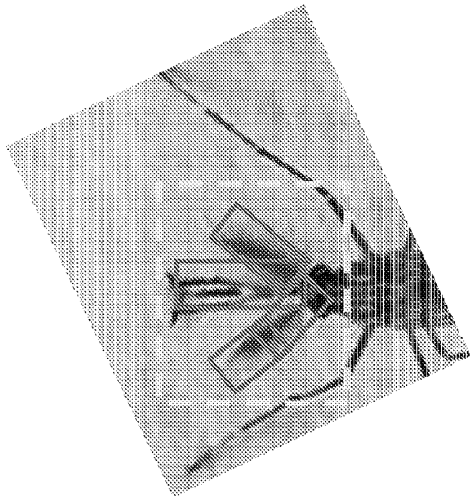


Fig. 9A

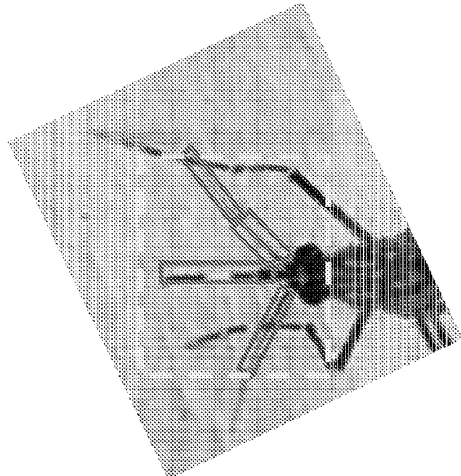
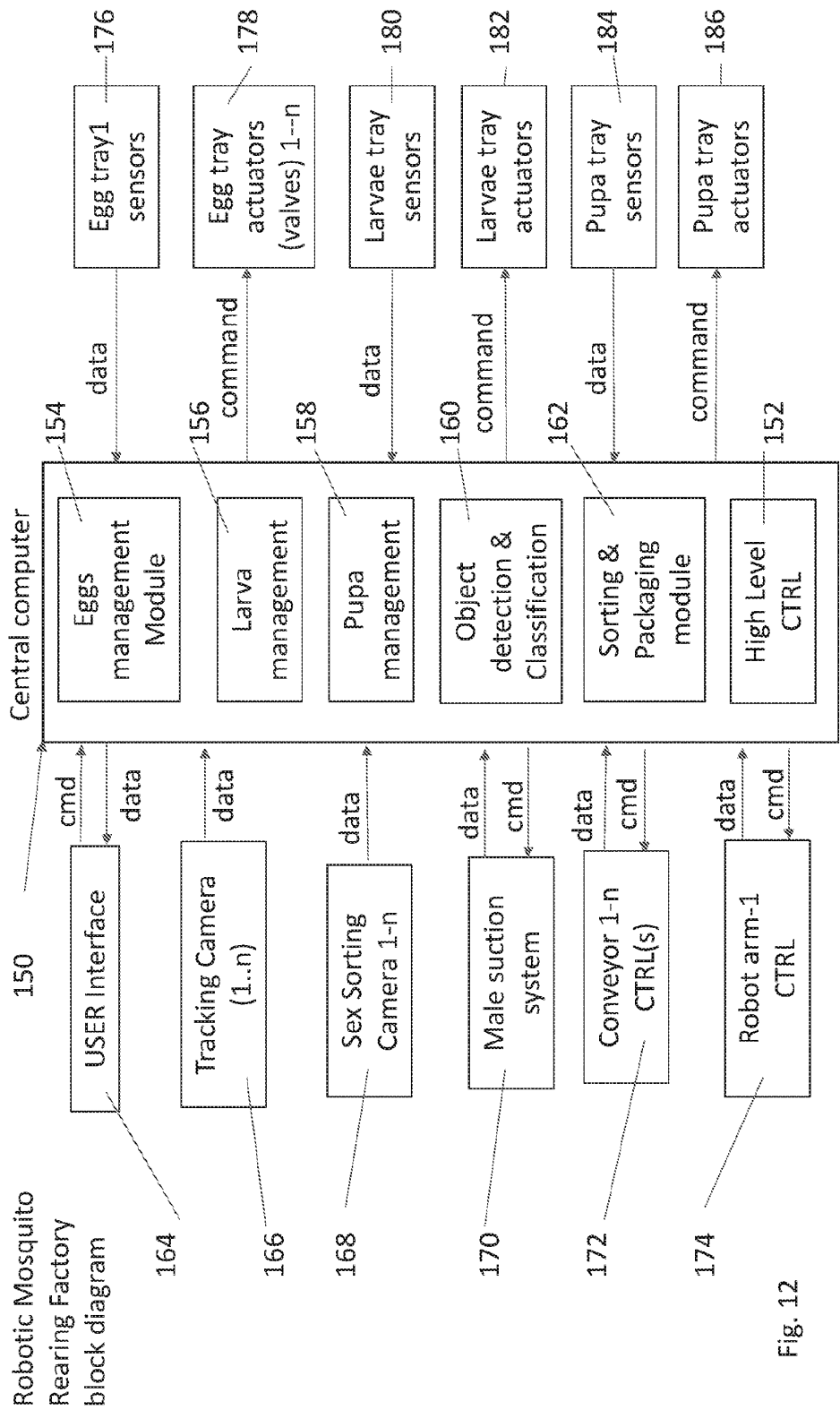


Fig. 9B



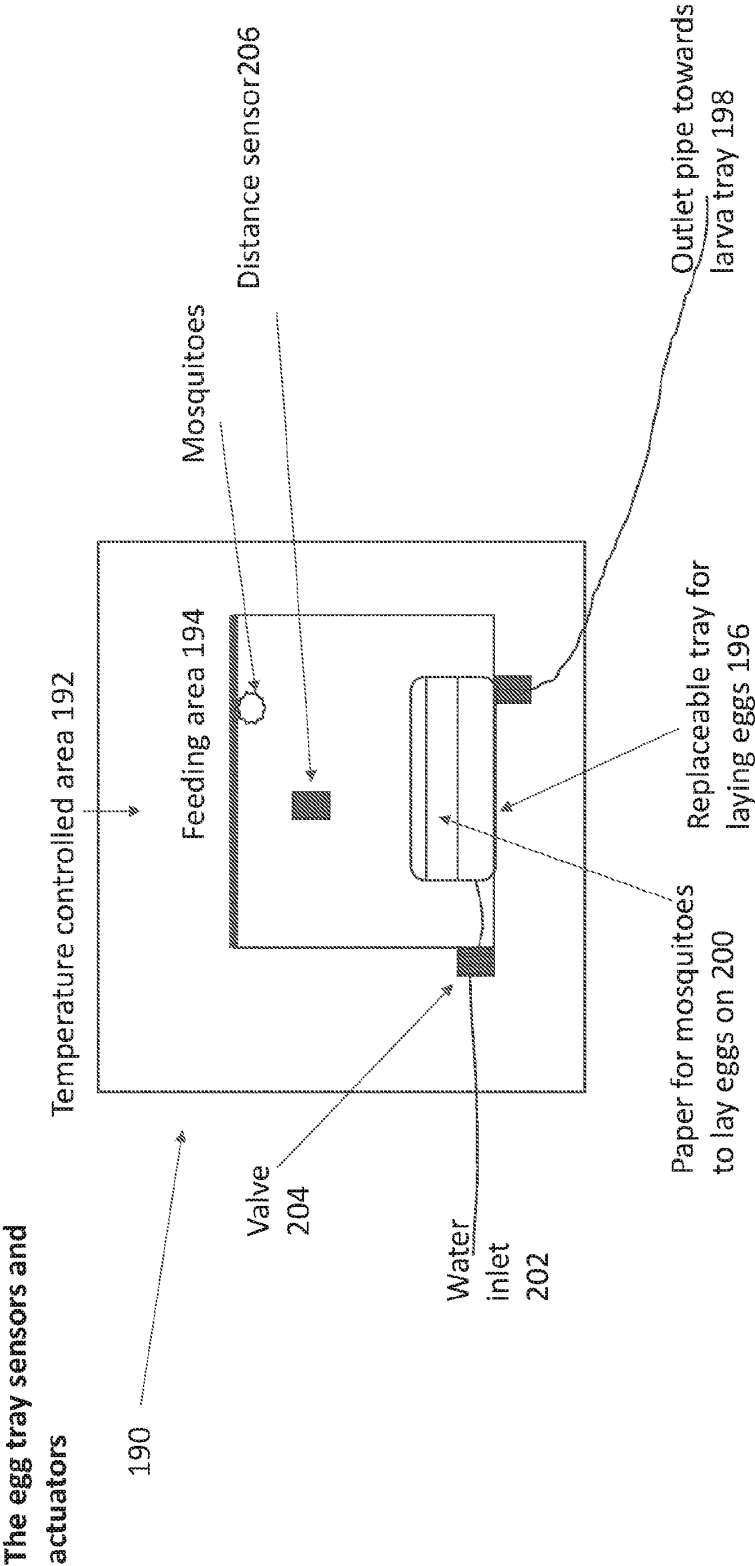


Fig. 13

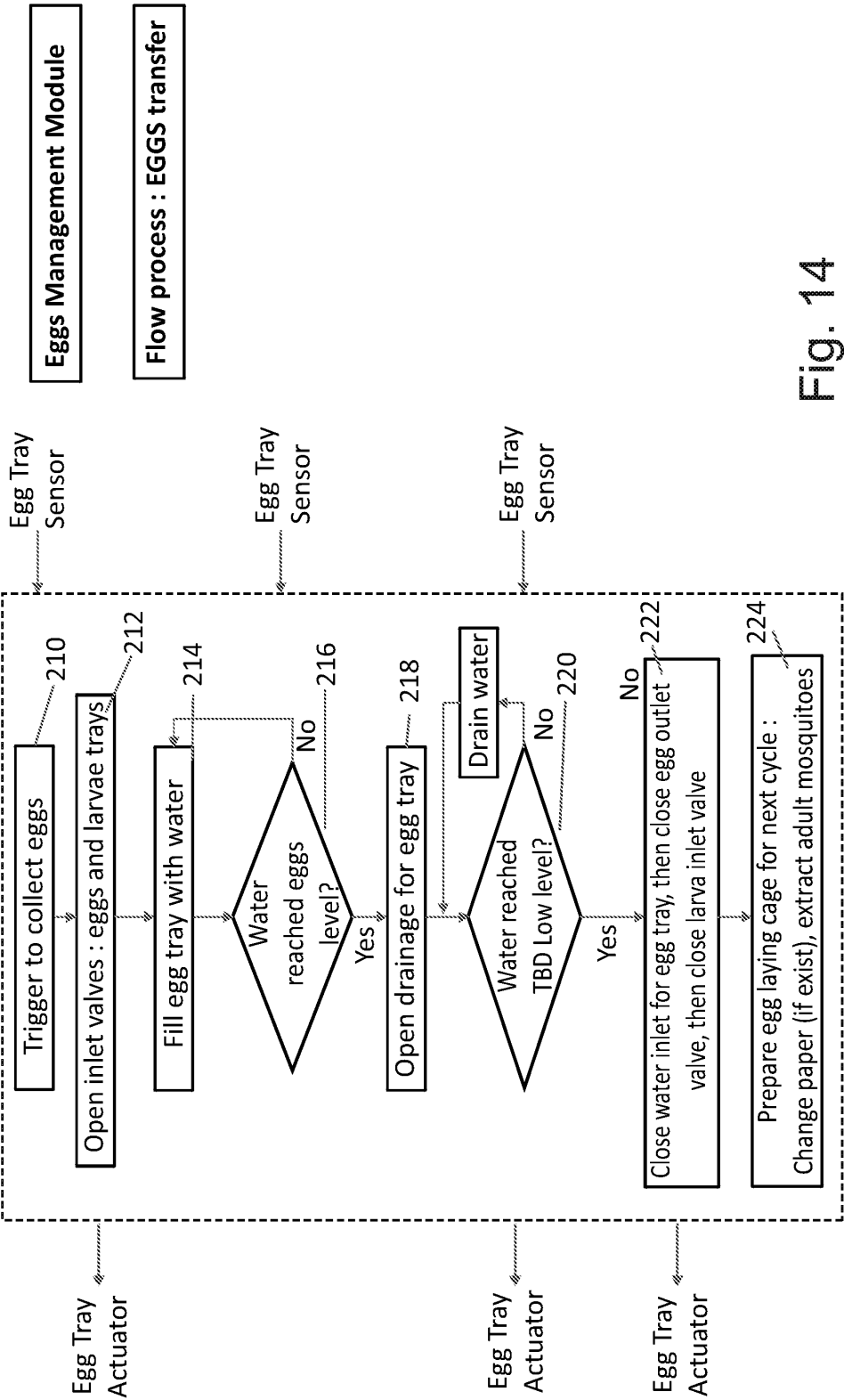


Fig. 14

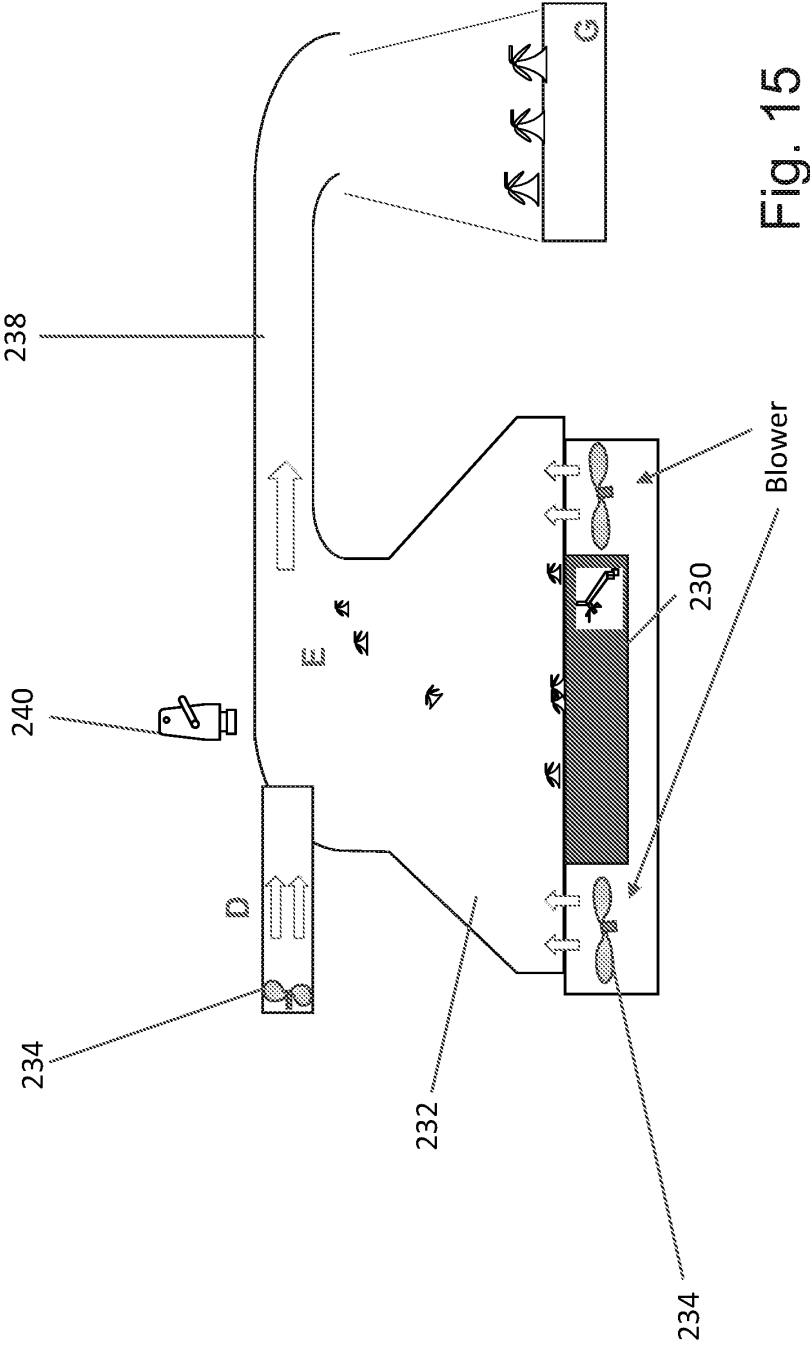


Fig. 15

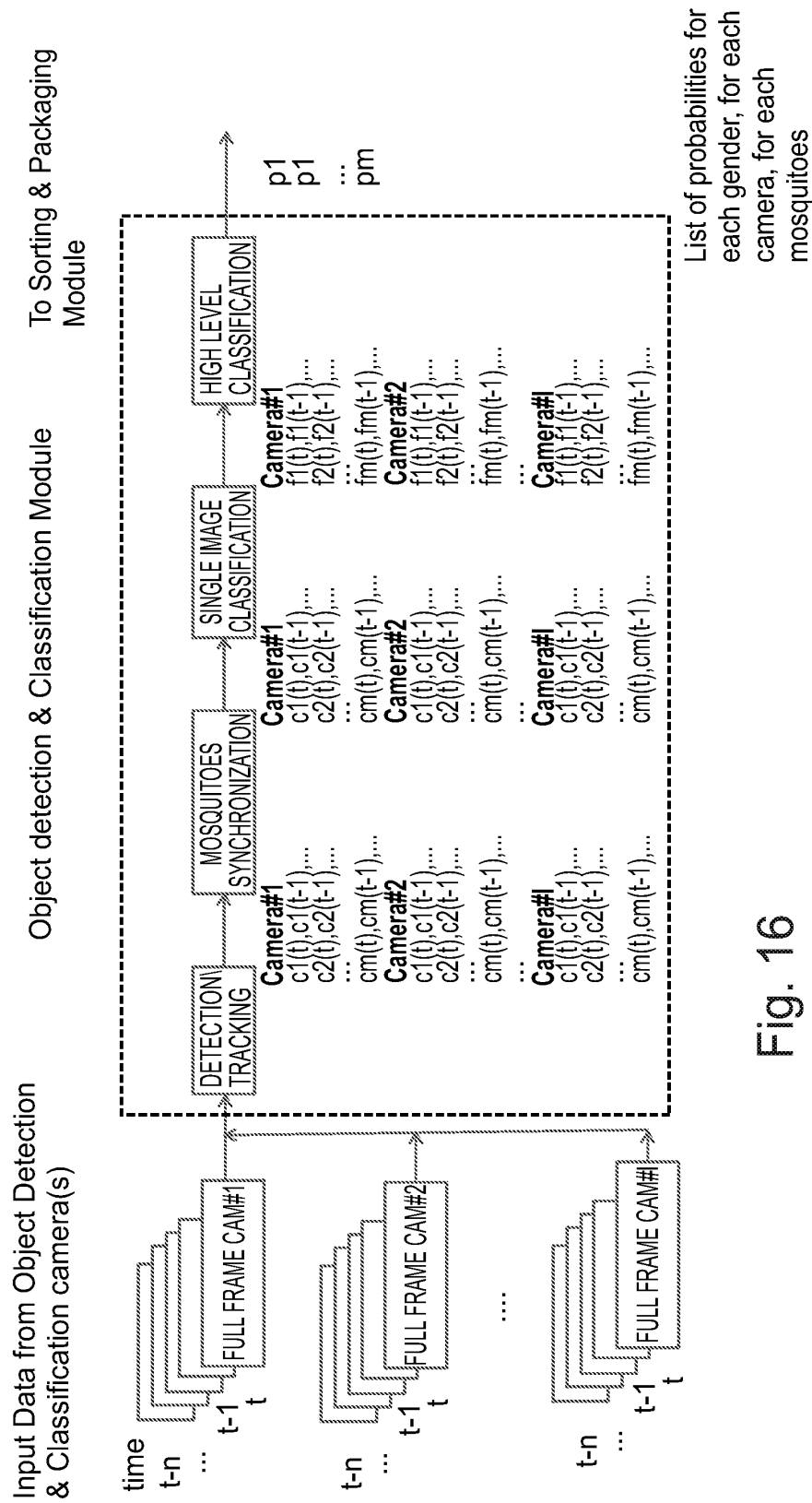


Fig. 16

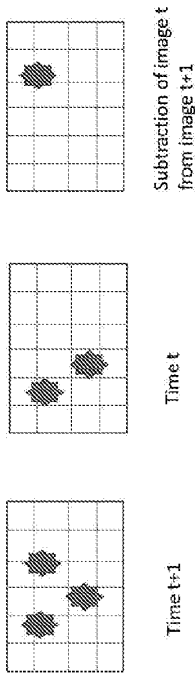
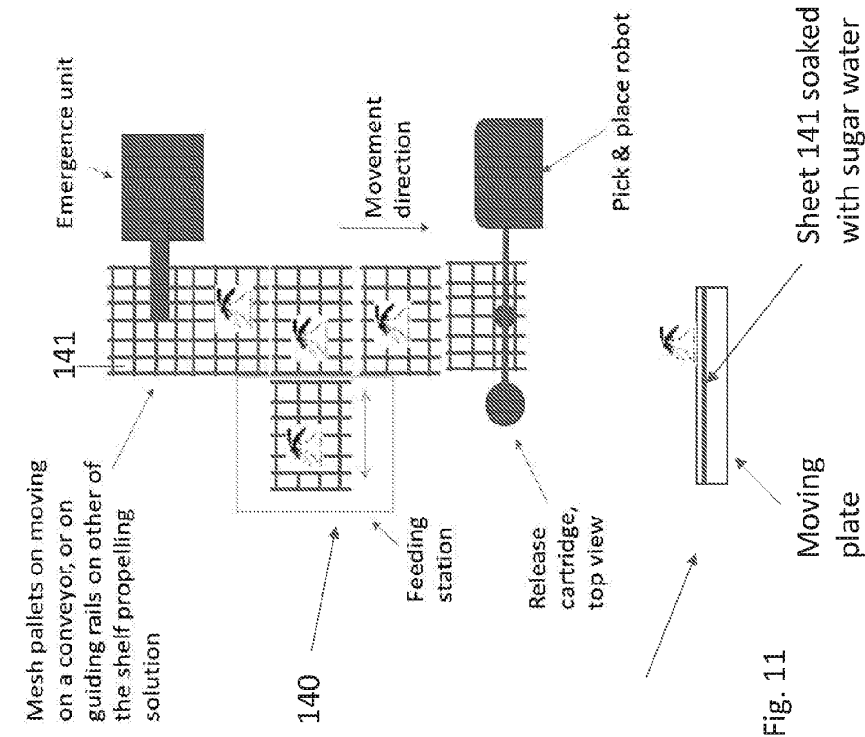
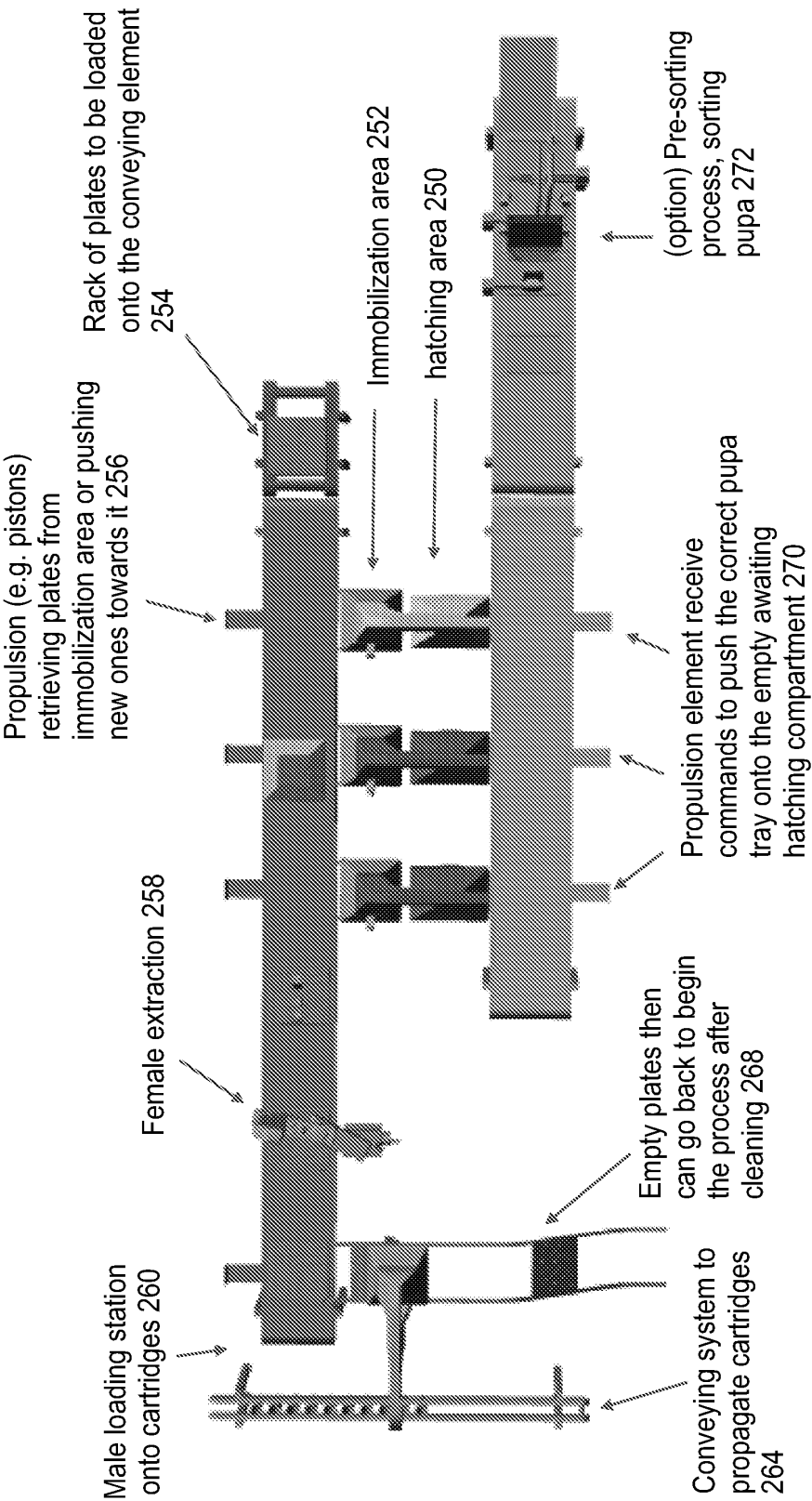


Fig. 18



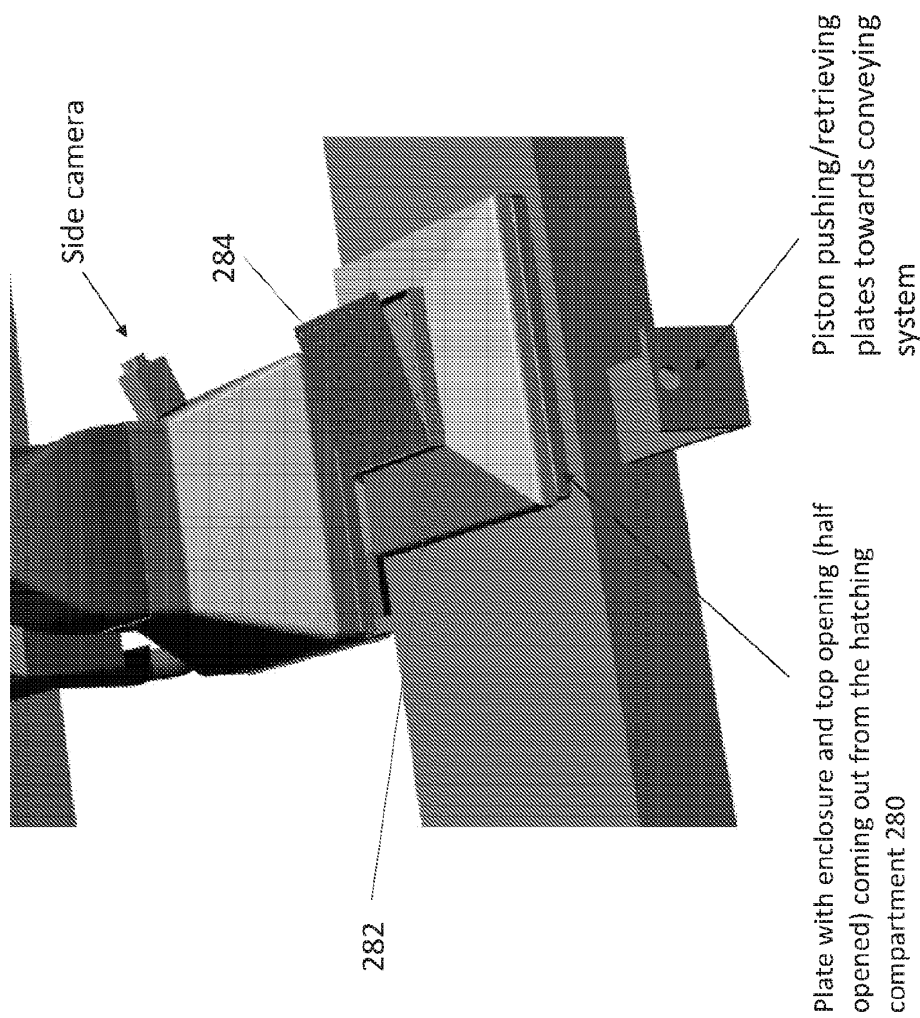


Fig. 19

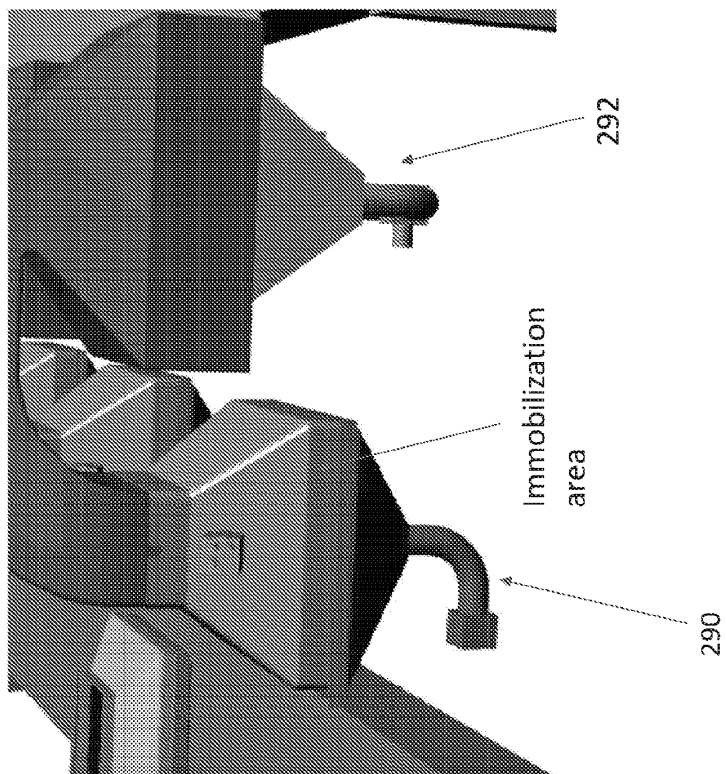
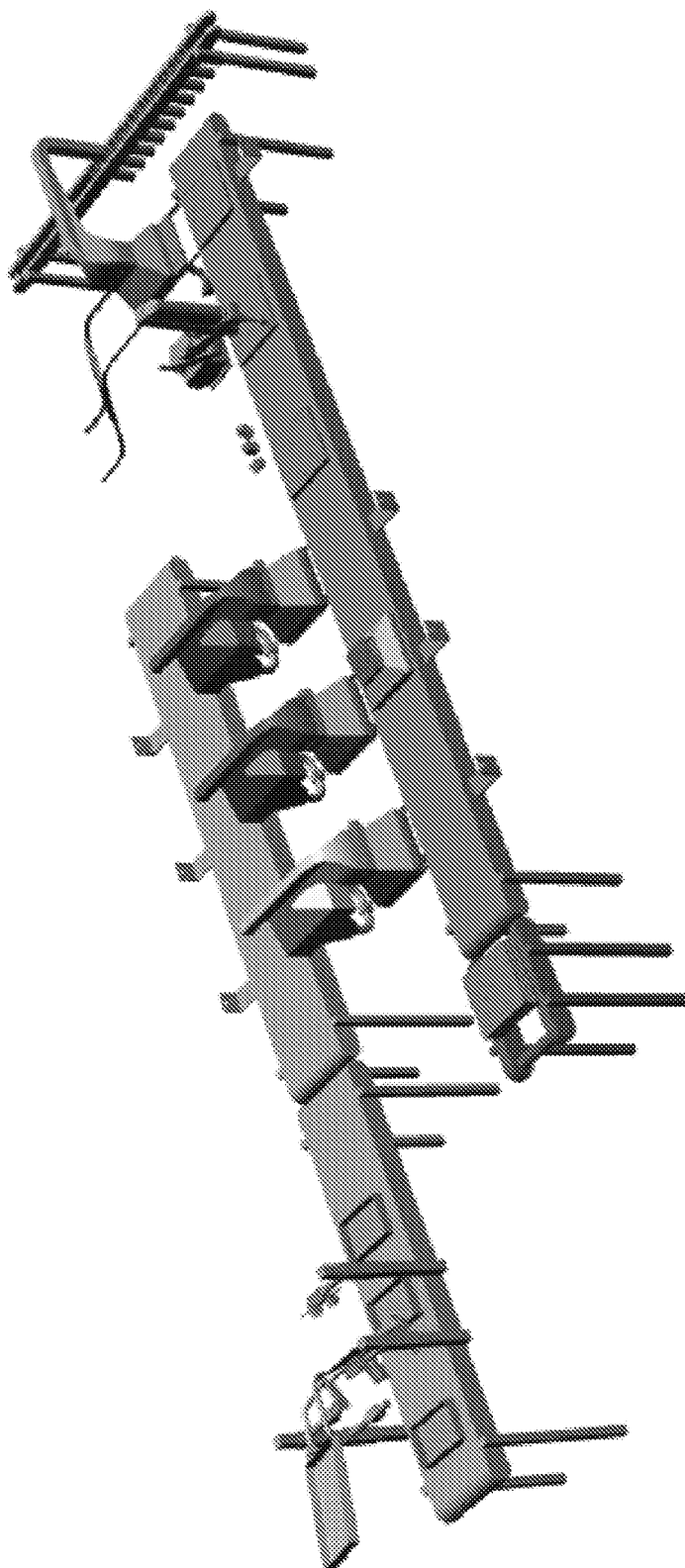


Fig. 20

Fig. 21



The plate with the enclosure moving
on the conveying system

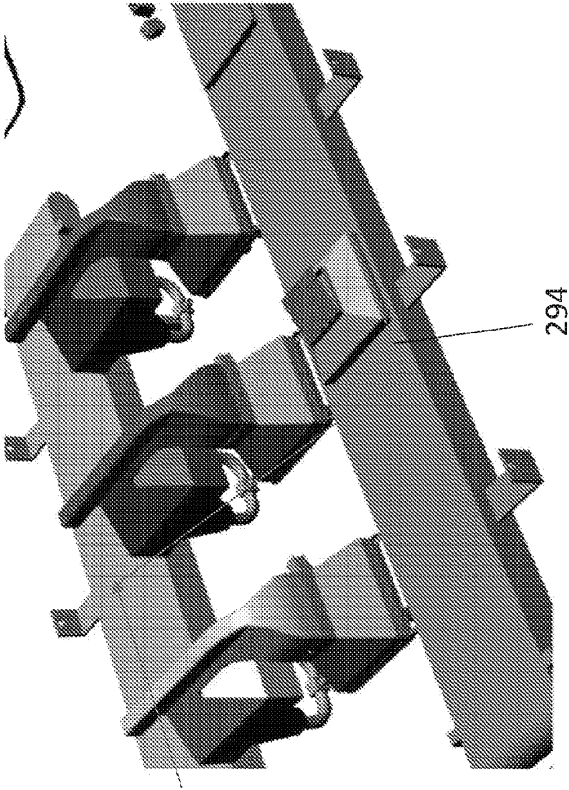


Fig. 22A

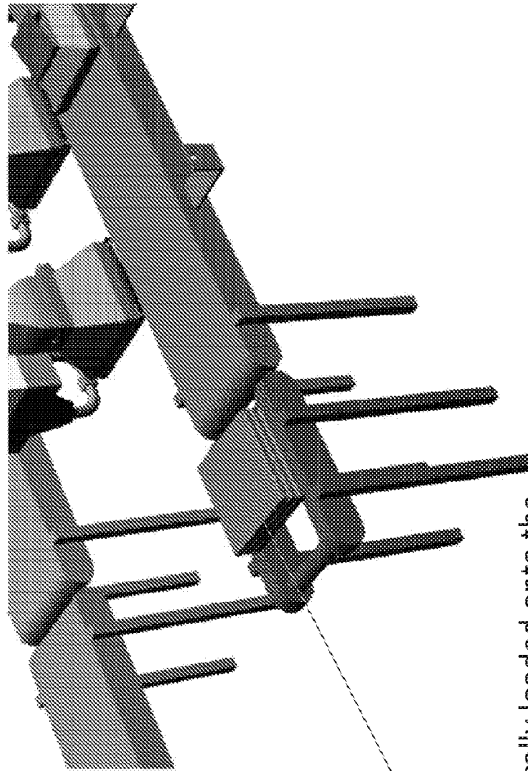
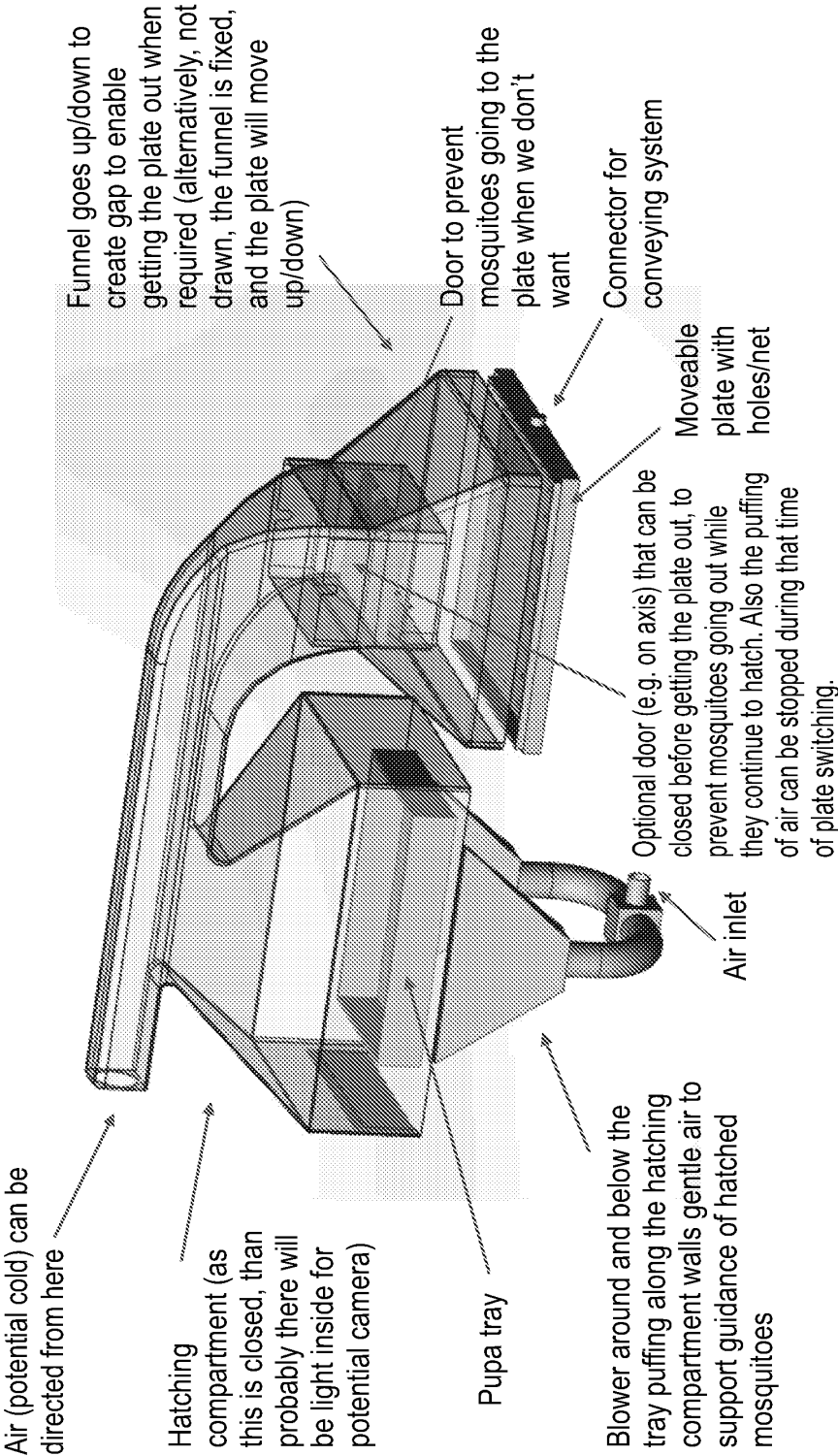


Fig. 22B

Rack of plates can be automatically loaded onto the conveying system, so the propelling (e.g. pistons) system will move them towards the correct empty immobilization area preferably before a tray of pupa entered that hatching compartment.

Fig. 23



Door to prevent
mosquitoes going to
plate at wrong time

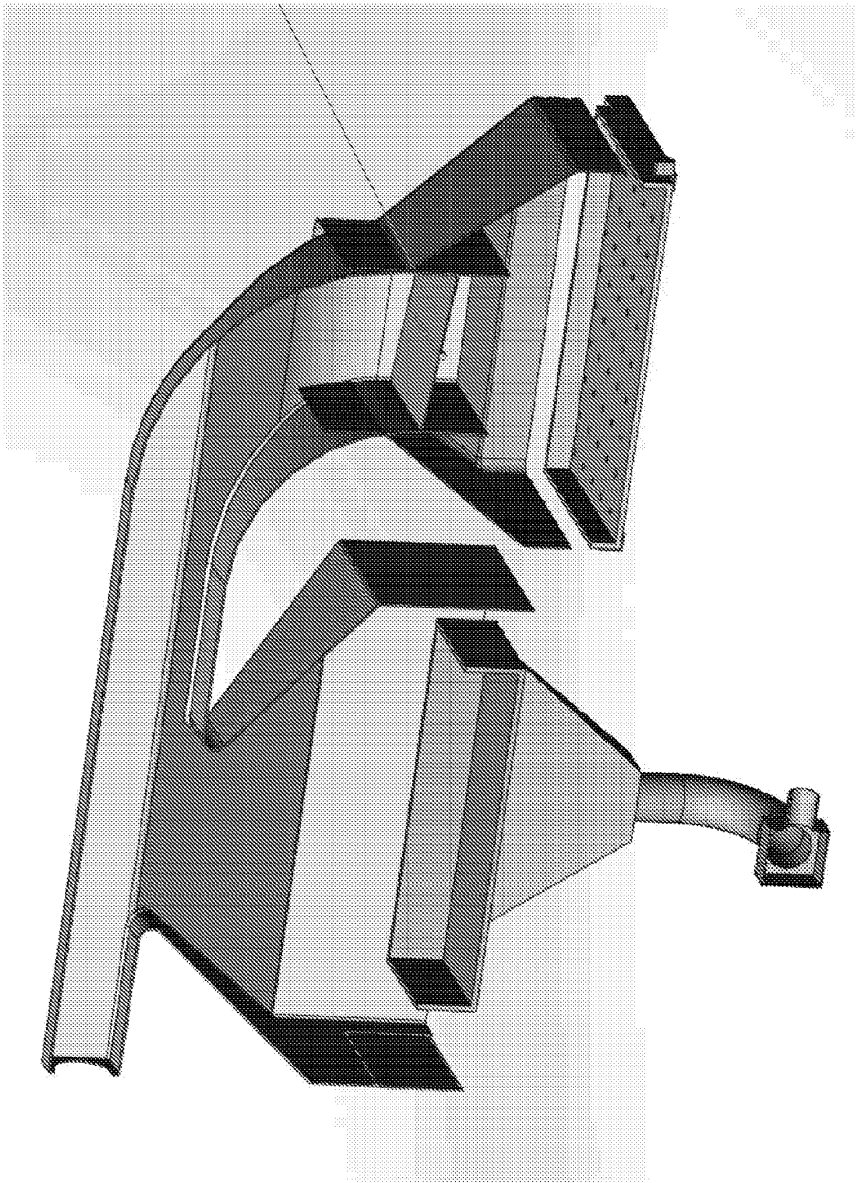
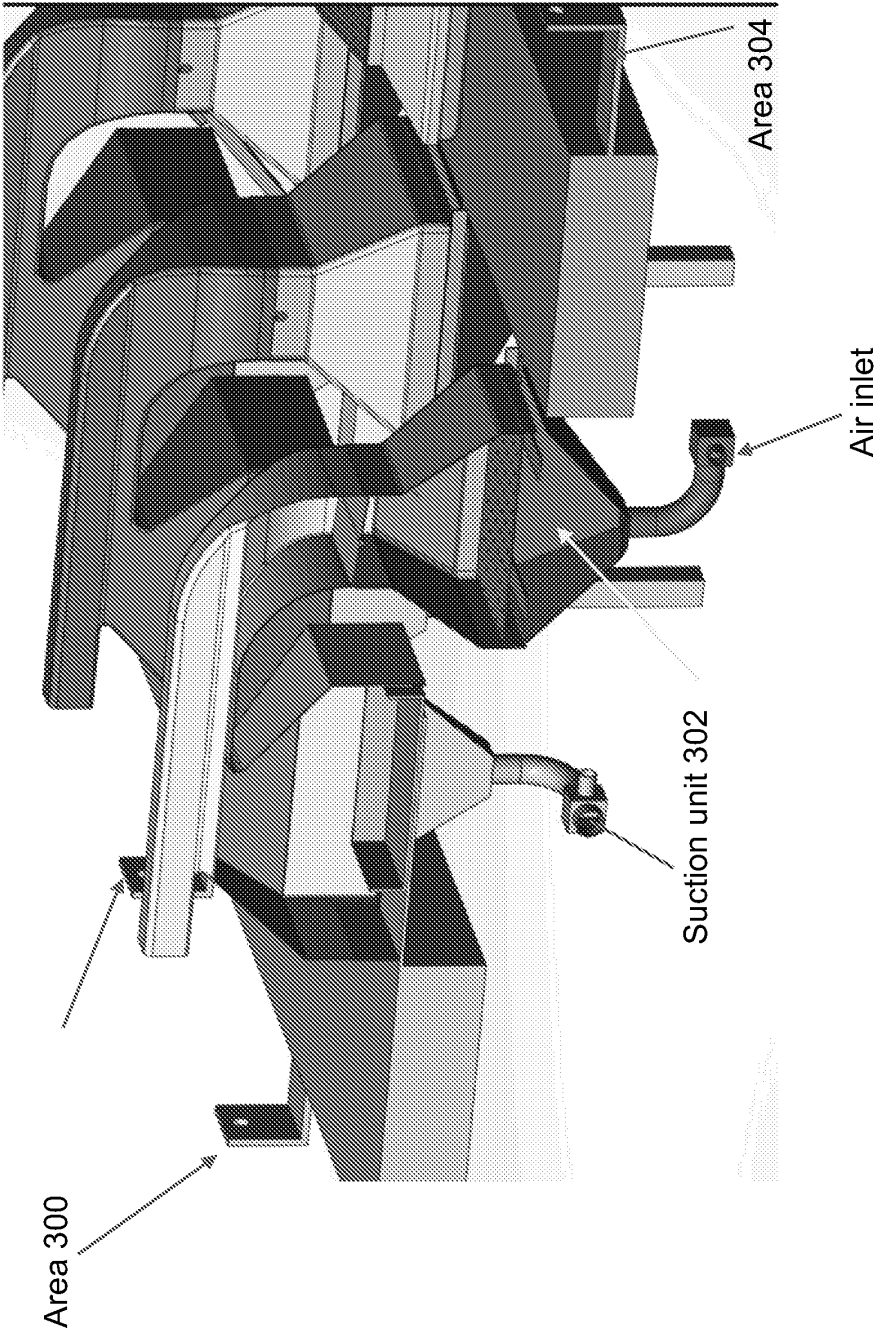


Fig. 24

Fig. 25



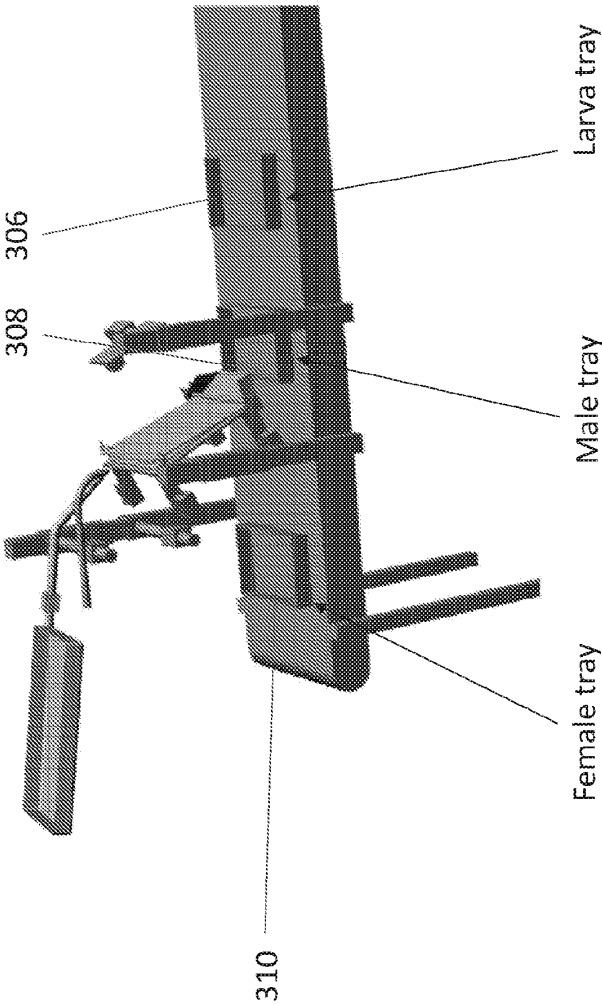


Fig. 26

Fig. 27

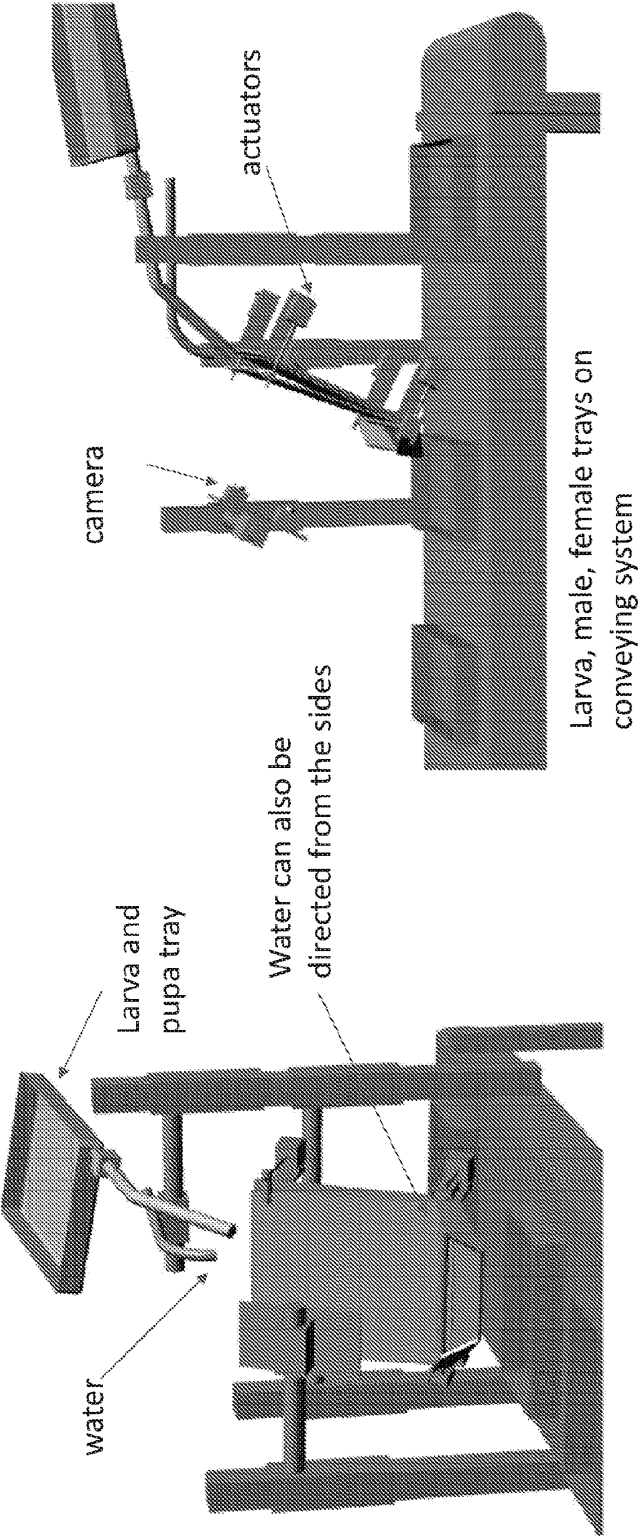
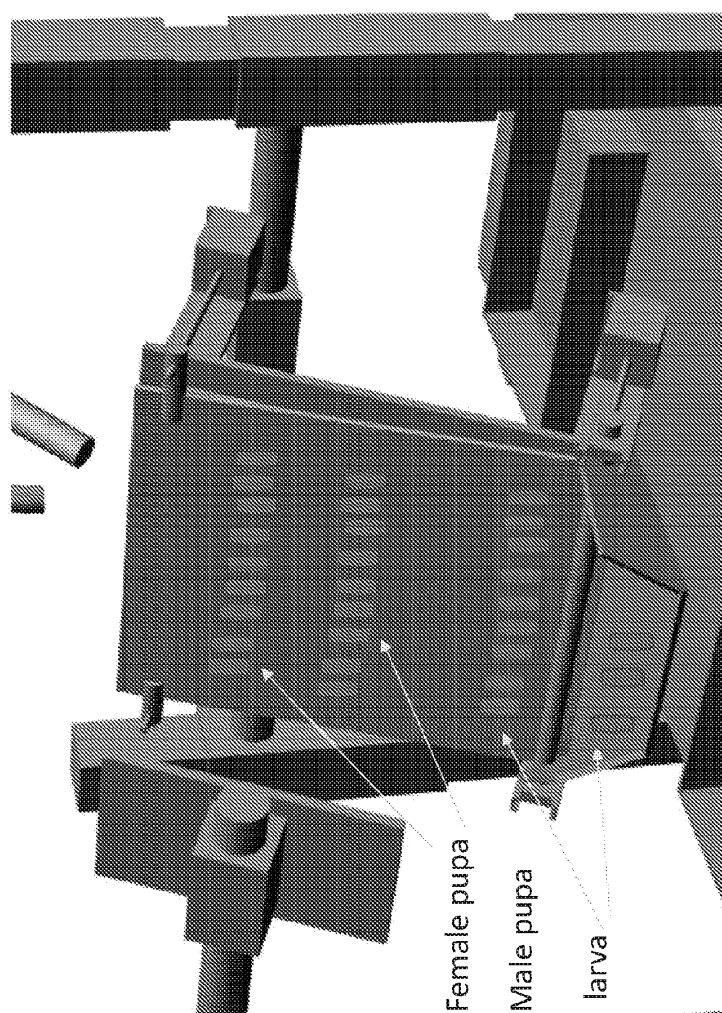


Fig. 28



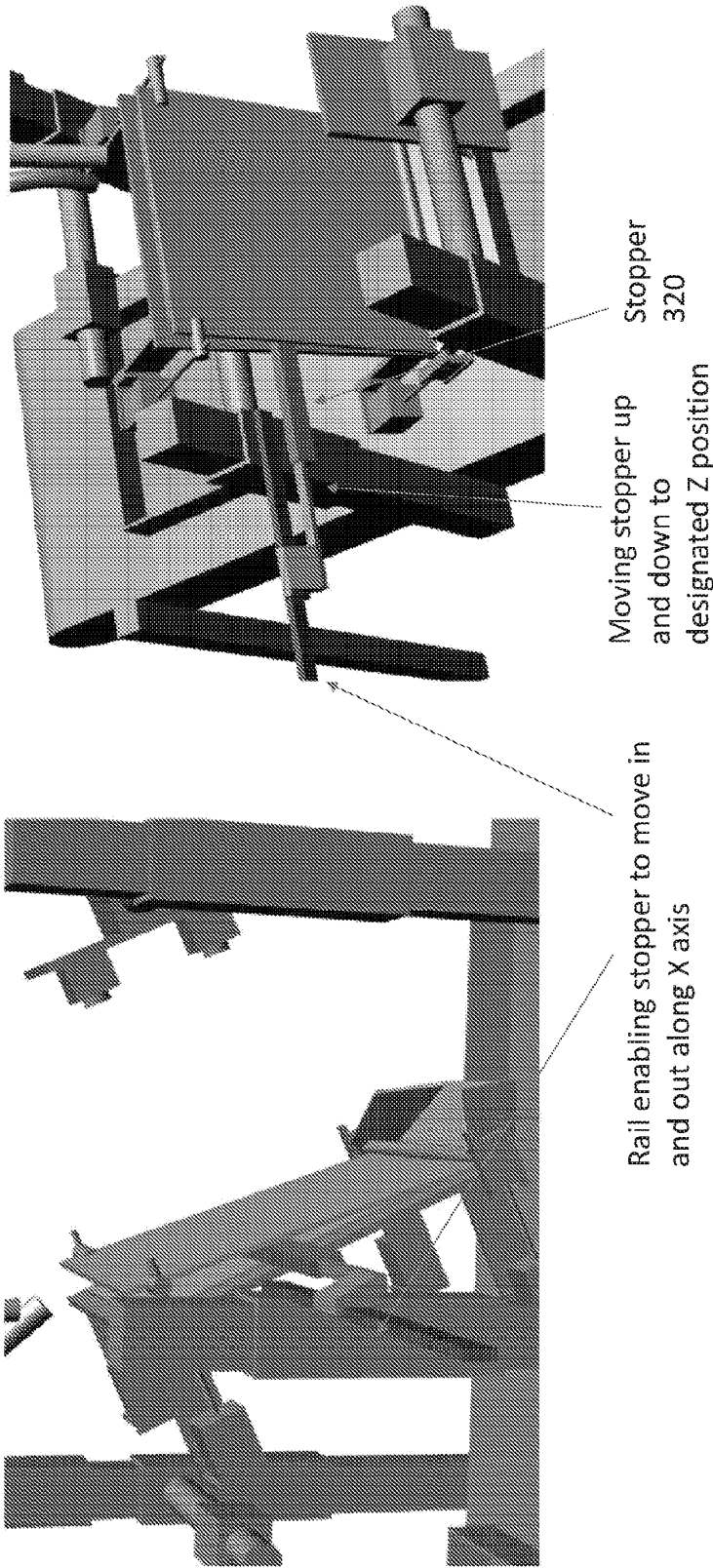
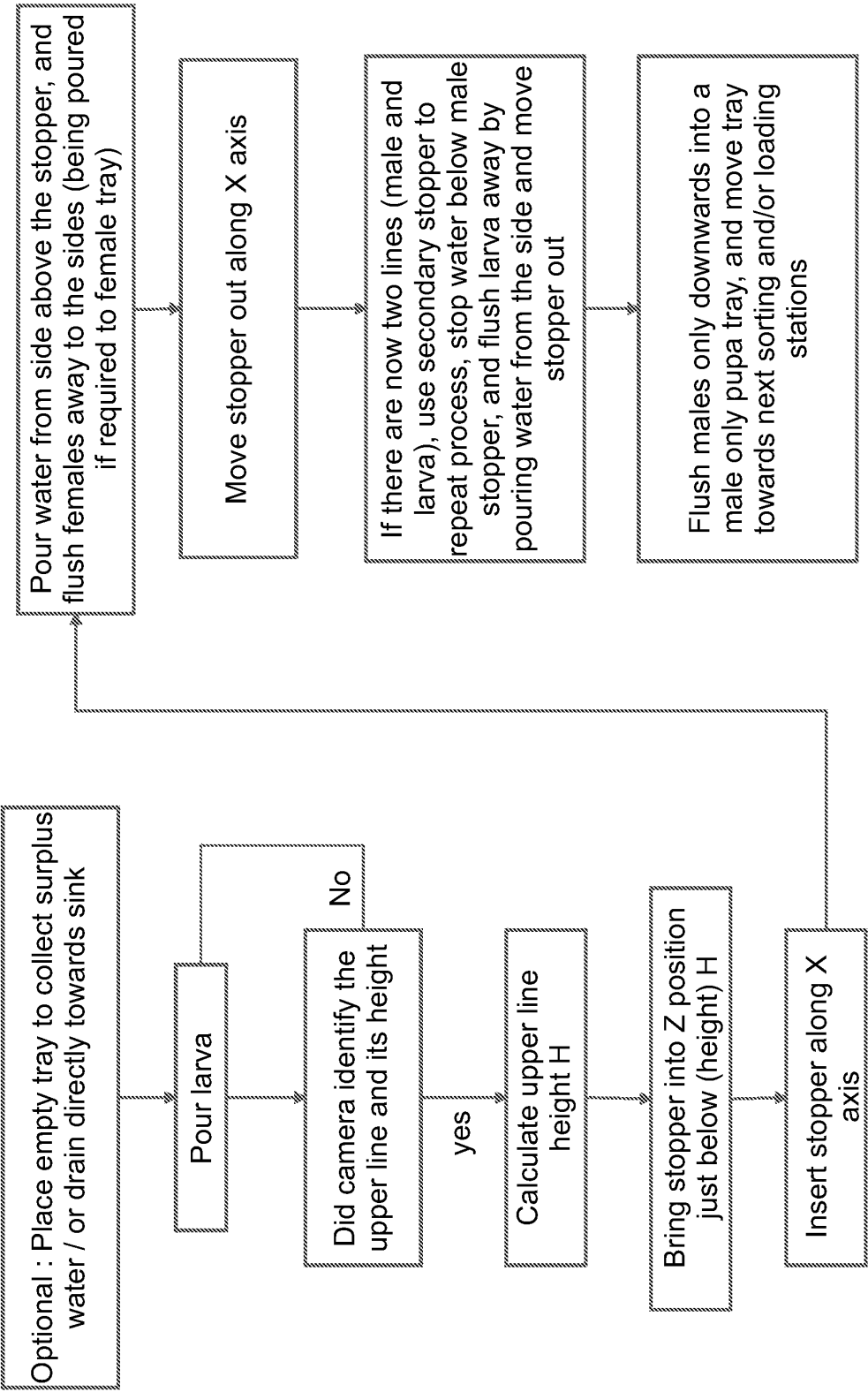
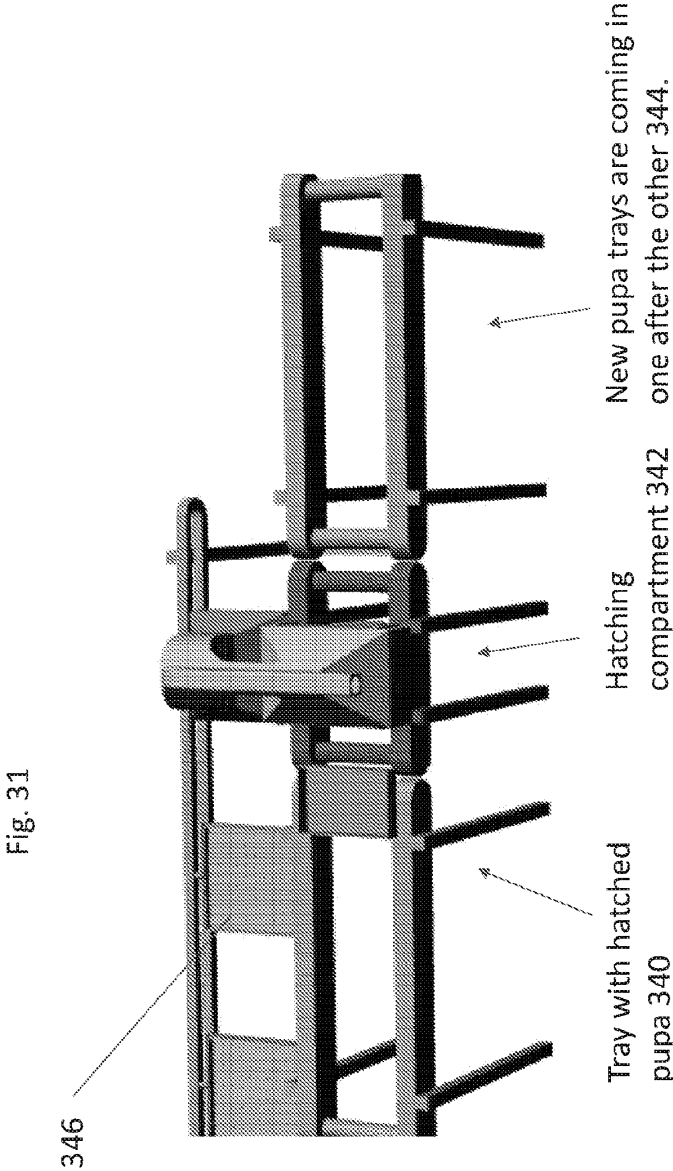


Fig. 29

Fig. 30





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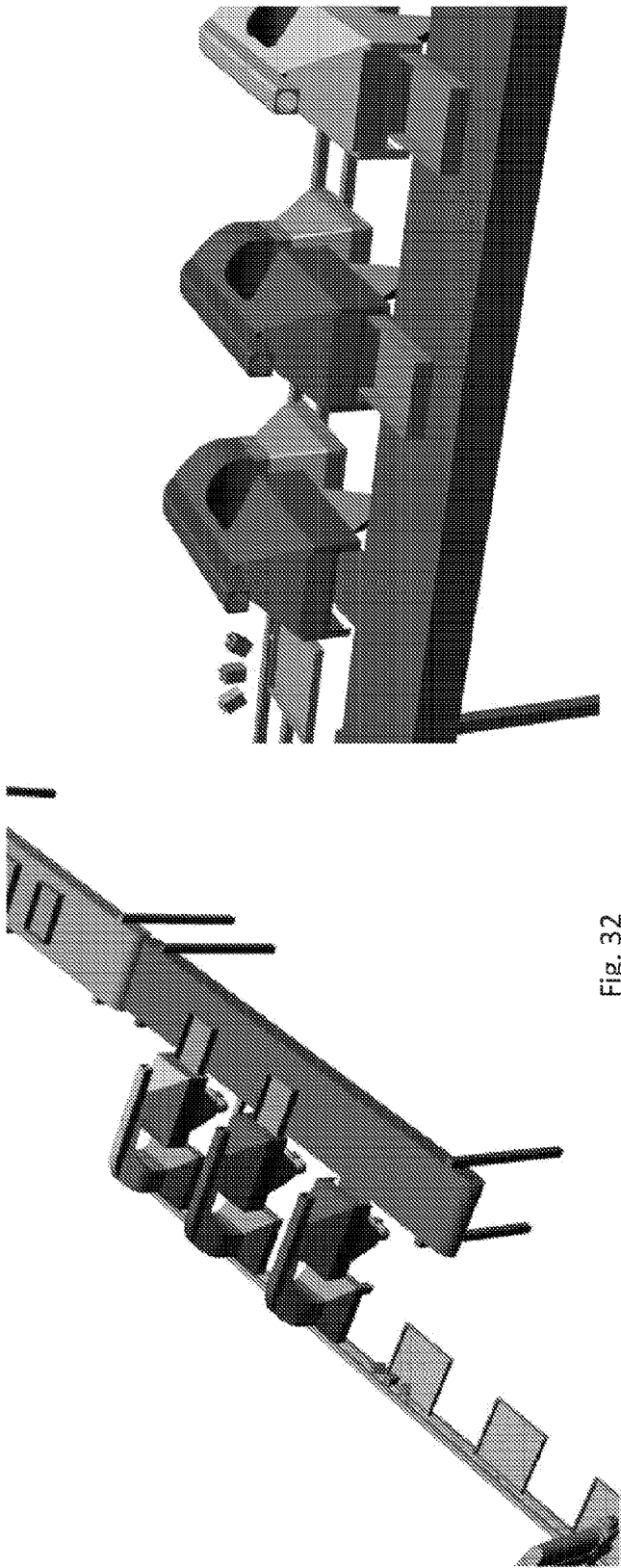
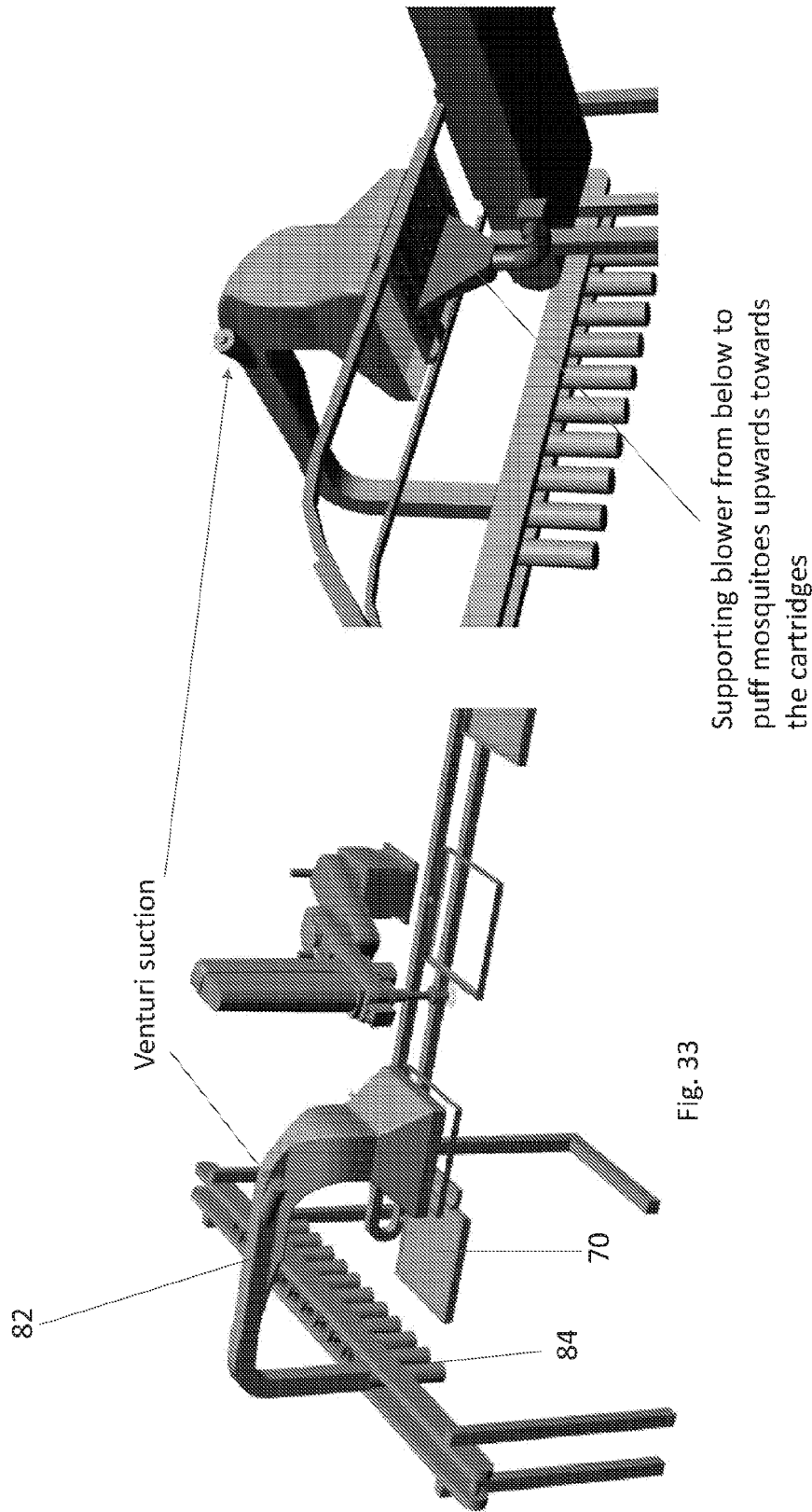


Fig. 32



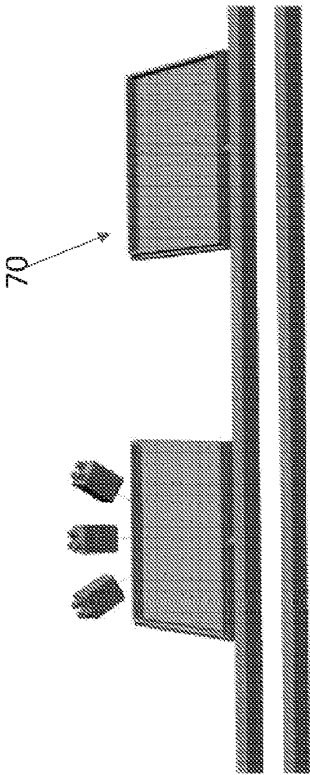
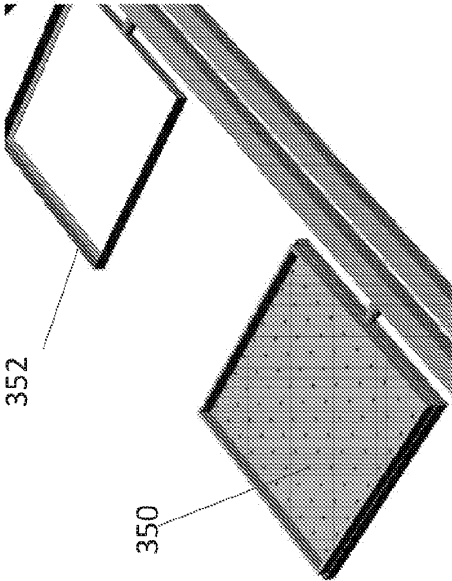
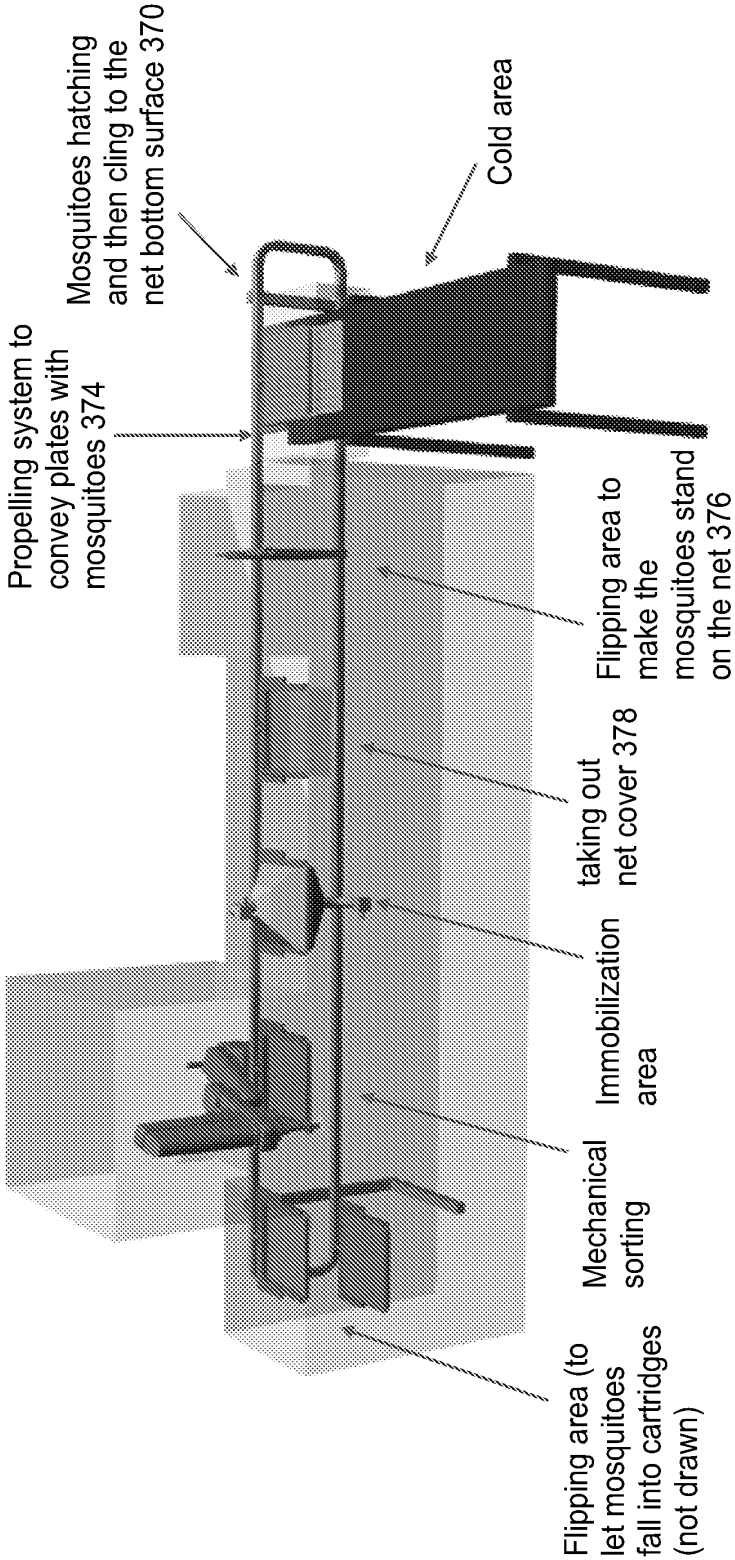
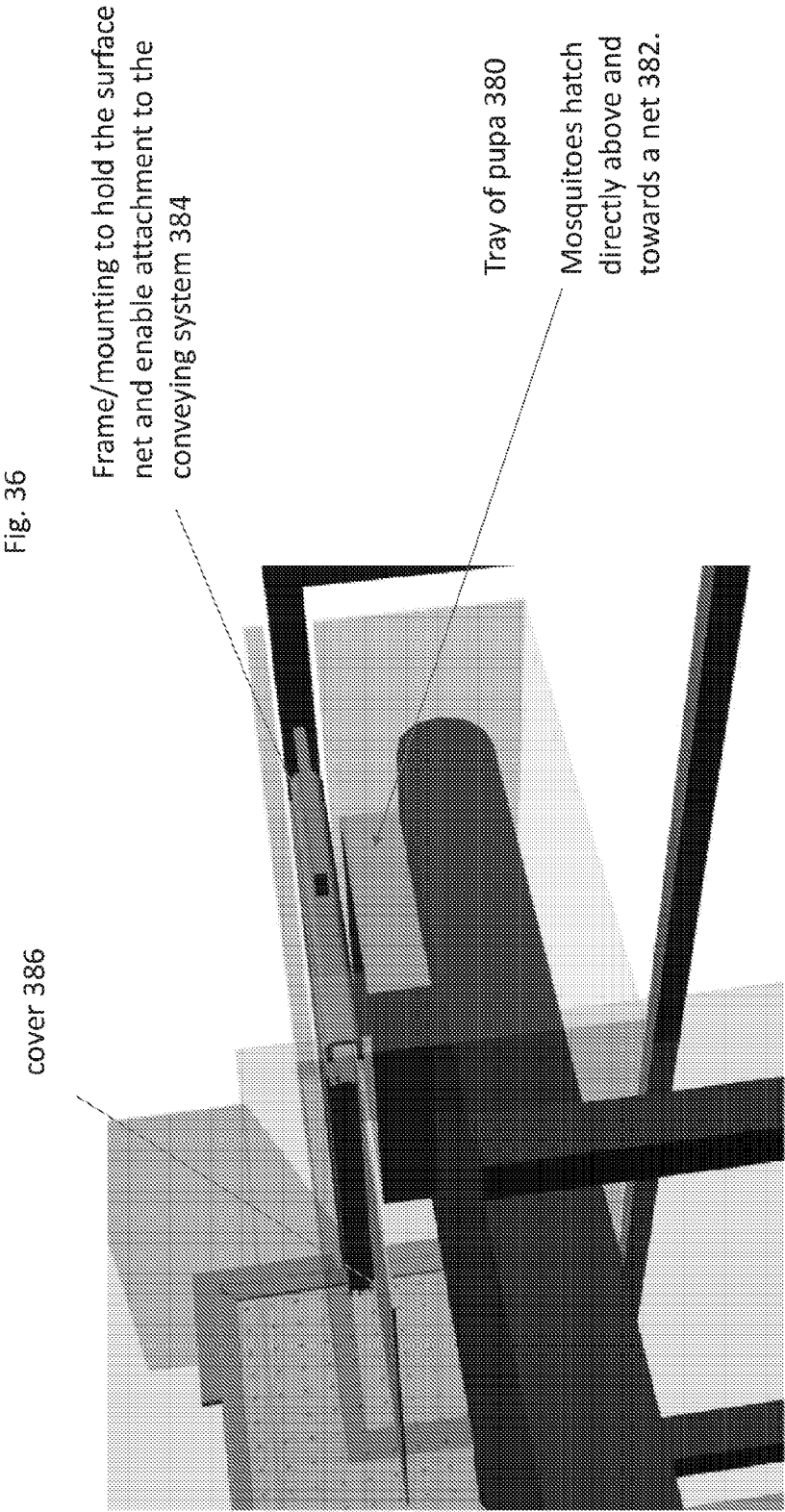


Fig. 34

Fig. 35





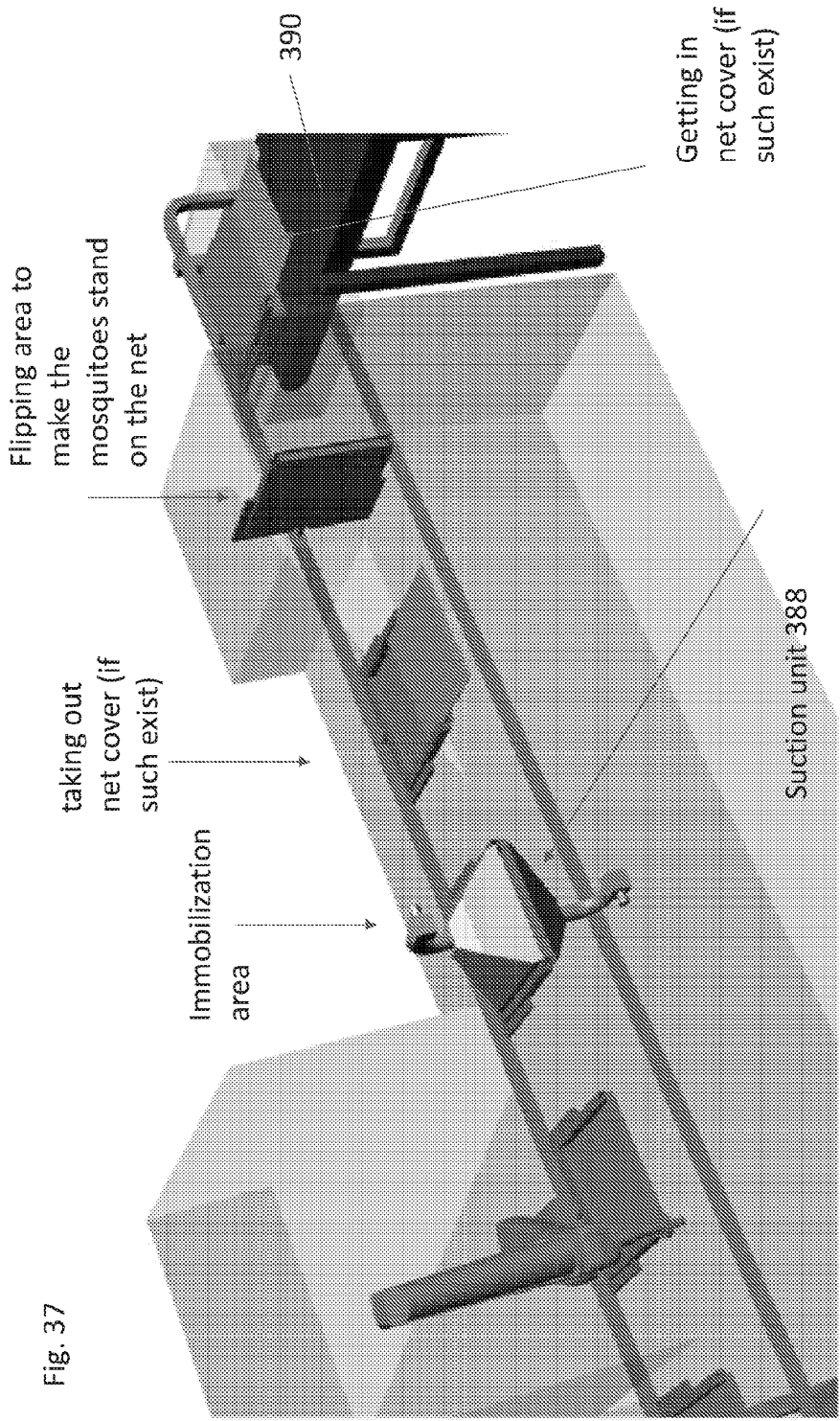


Fig. 38

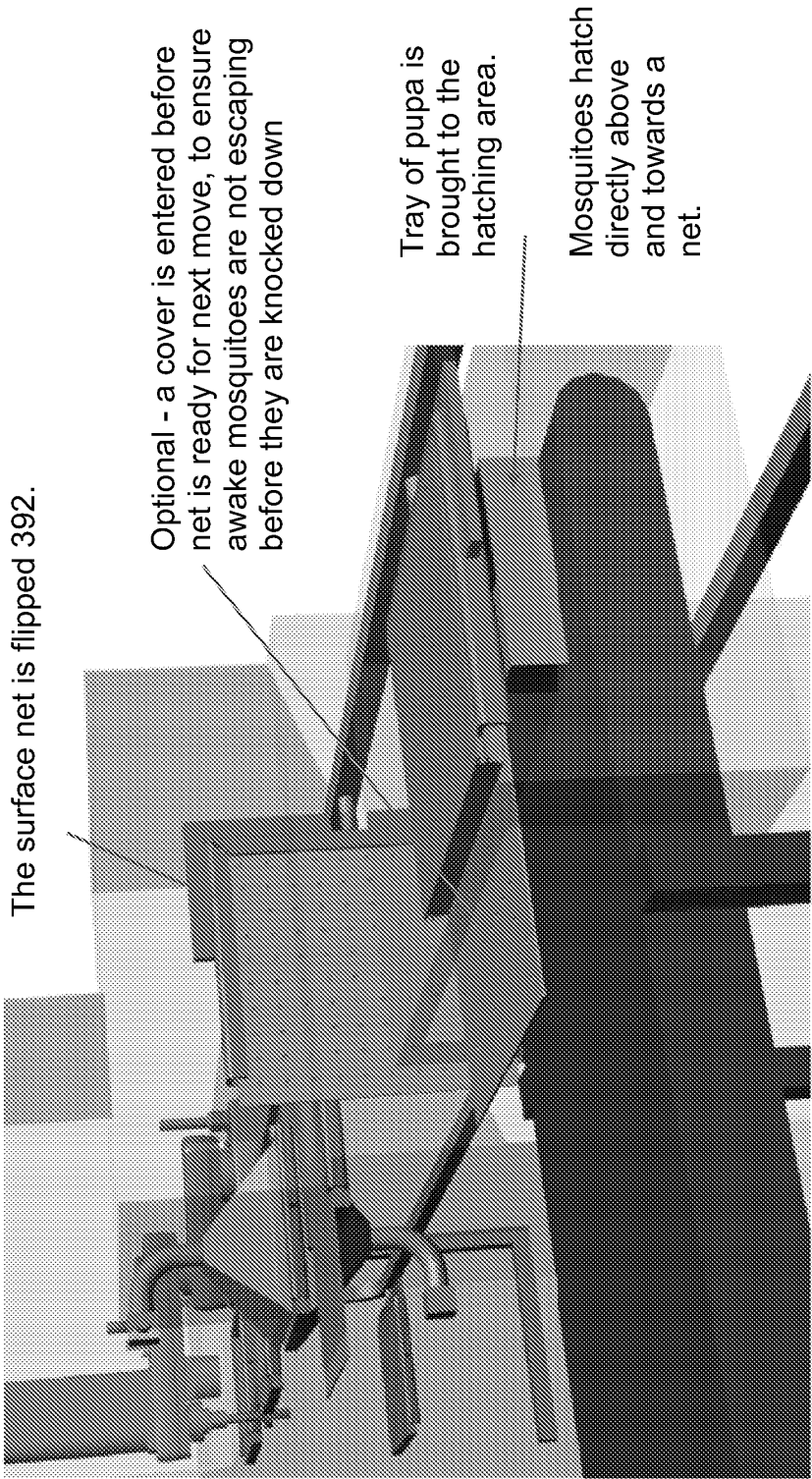


Fig. 39

