

ABSTRACT

Aspects concern a method for gathering image training data for training a machine learning model to detect features for vehicle navigation or vehicle control, comprising mounting a camera onto a vehicle or the driver of a vehicle, determining a location of the vehicle, determining a relevancy of the determined location for map data generation or vehicle control and recording a video with the camera if the determined relevancy is above a predetermined threshold and recording single images if the determined relevancy is below the predetermined threshold.

FIG. 4