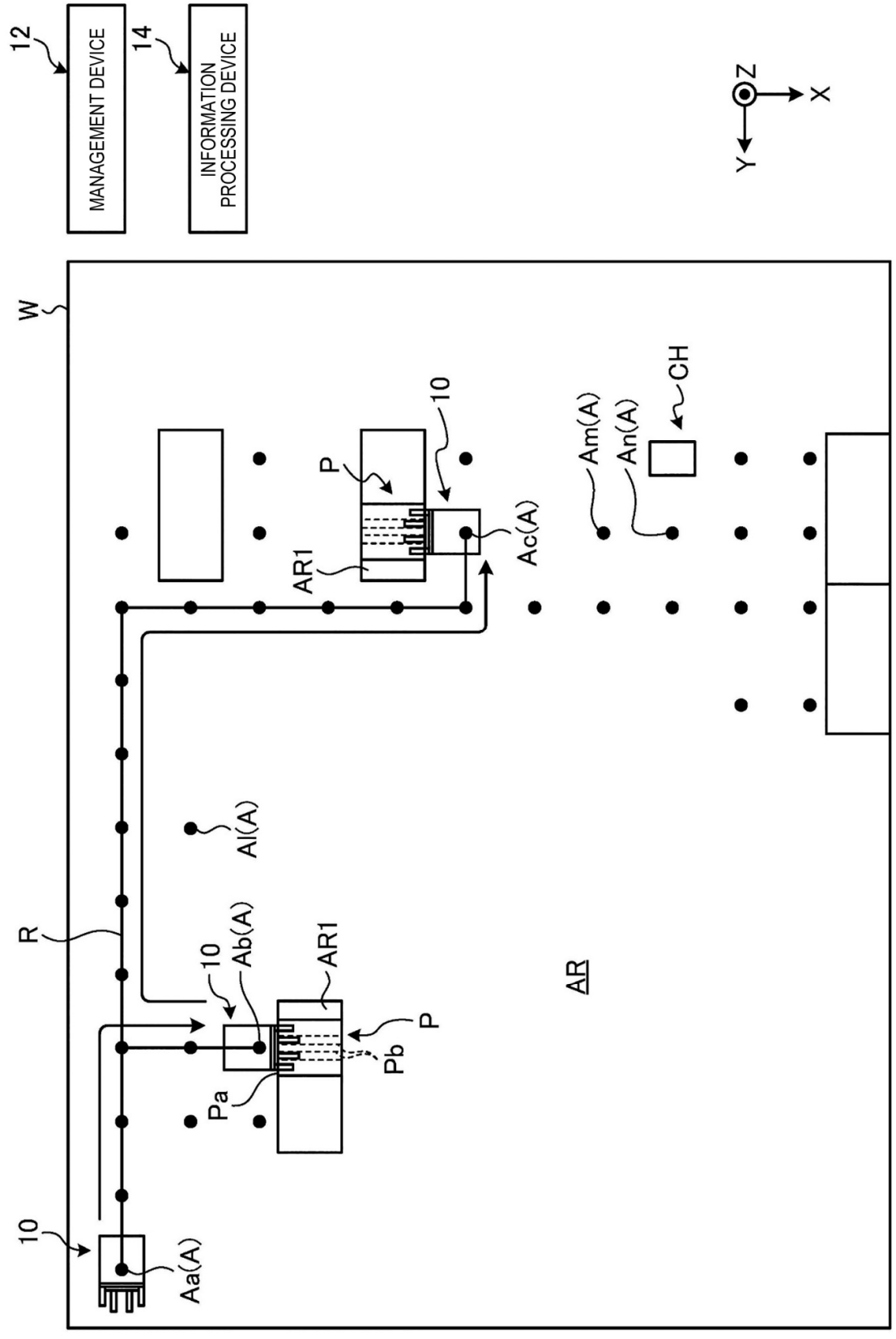

12
MANAGEMENT DEVICE
14
INFORMATION PROCESSING DEVICE
Z
X
Y
W
10
Aa(A)
R
10
Ab(A)
Pa
AR1
Pb
P
Al(A)
AR
10
P
AR1
Ac(A)
Am(A)
An(A)
CH

FIG. 1

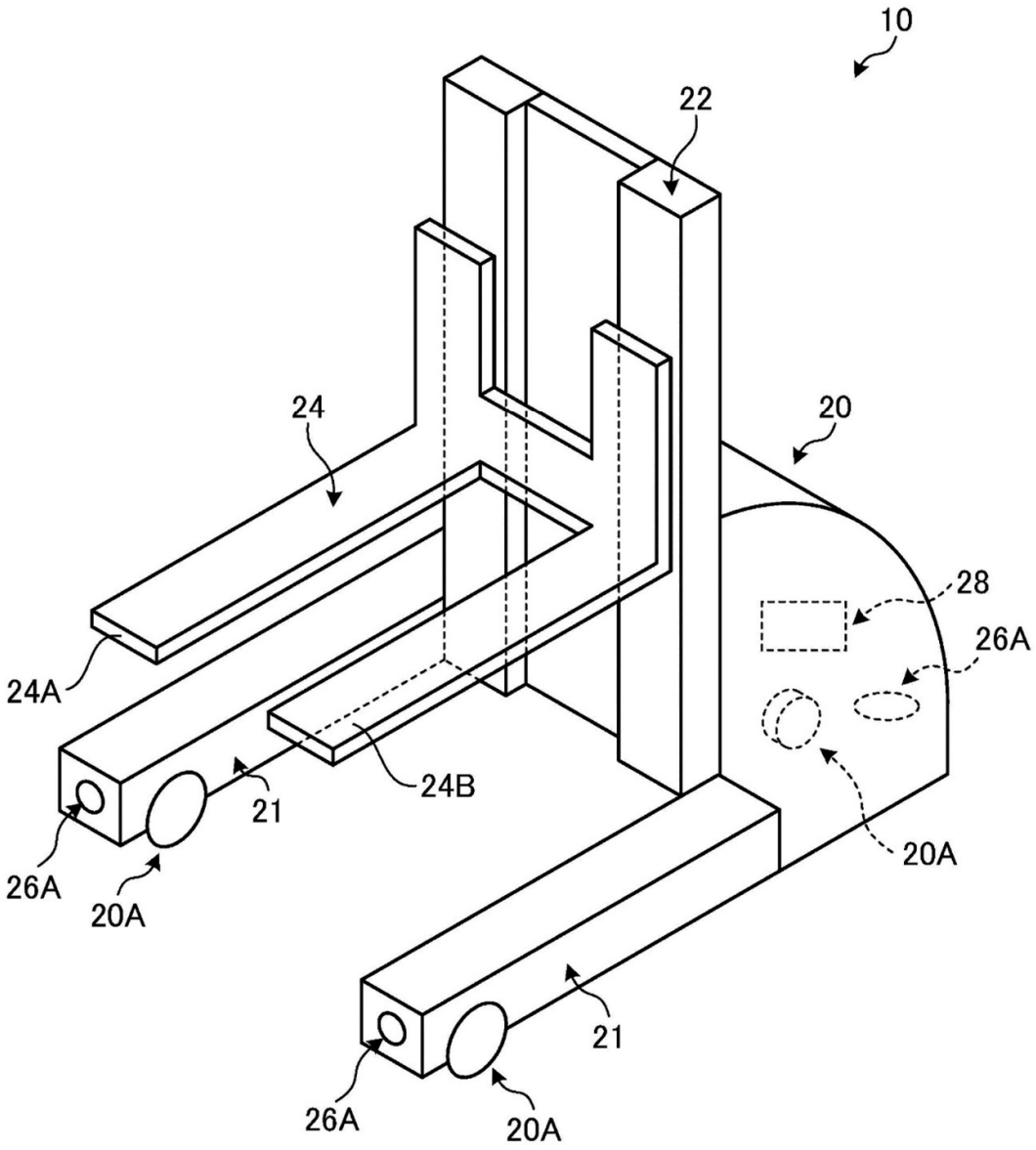


FIG. 2

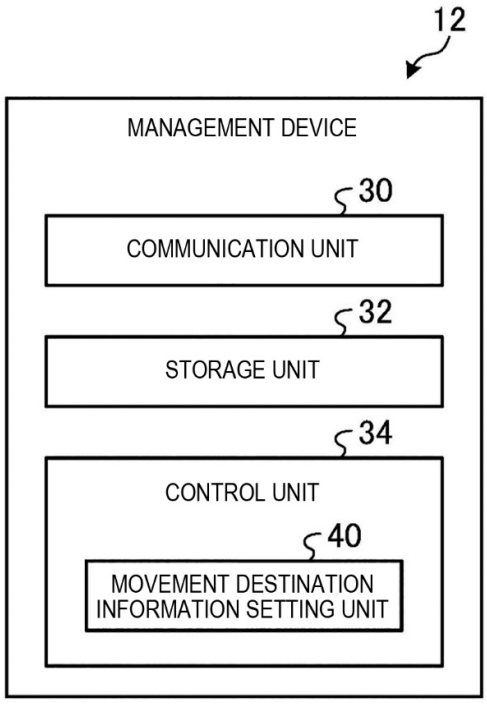

12
MANAGEMENT DEVICE
30
COMMUNICATION UNIT
32
STORAGE UNIT
34
CONTROL UNIT
40
MOVEMENT DESTINATION INFORMATION SETTING UNIT

FIG. 3

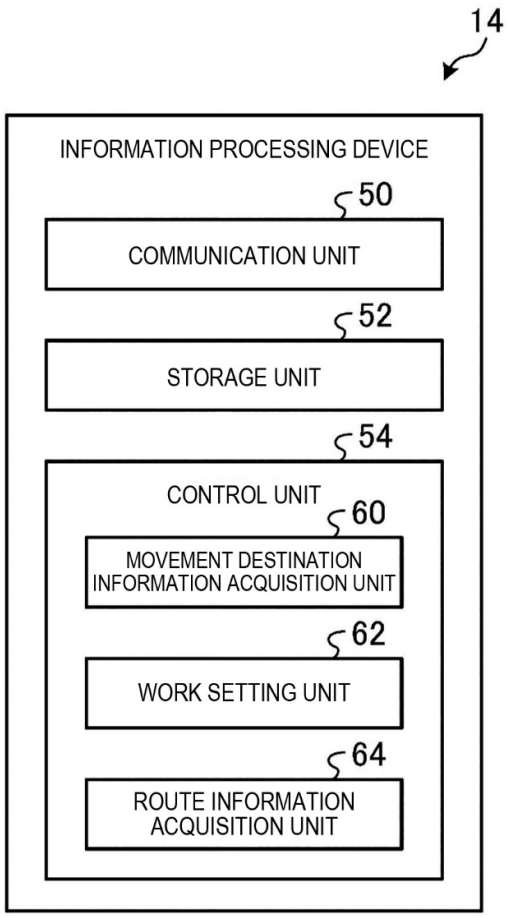

14
INFORMATION PROCESSING DEVICE
50
COMMUNICATION UNIT
52
STORAGE UNIT
54
CONTROL UNIT
60
MOVEMENT DESTINATION INFORMATION ACQUISITION UNIT
62
WORK SETTING UNIT
64
ROUTE INFORMATION ACQUISITION UNIT

FIG. 4

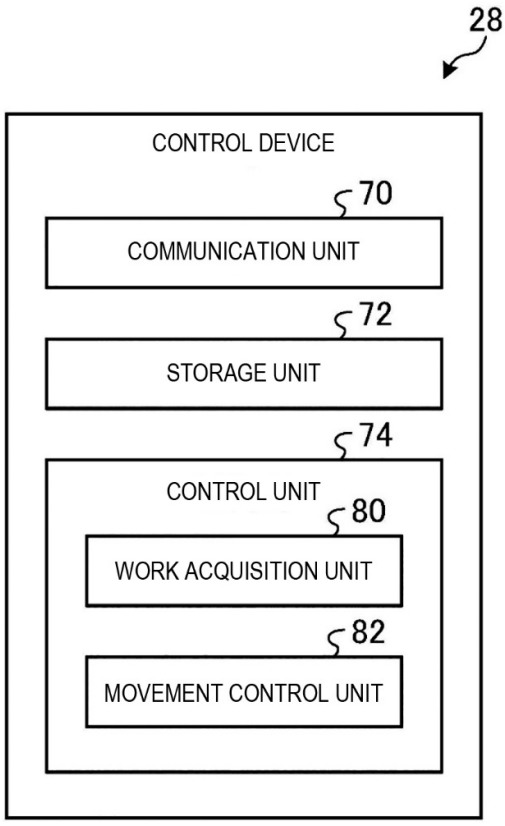

28
CONTROL DEVICE
70
COMMUNICATION UNIT
72
STORAGE UNIT
74
CONTROL UNIT
80
WORK ACQUISITION UNIT
82
MOVEMENT CONTROL UNIT

FIG. 5

PRIORITY INFORMATION	TARGET OBJECT INFORMATION	FIRST POSITION	SECOND POSITION
0001	P1	A1	A2
0002	P11	A11	A3
0003	P21	A21	A4
0004	P2	A31	A5
0005	P21	A41	A6

FIG. 6

PRIORITY INFORMATION	TARGET OBJECT INFORMATION	FIRST POSITION	SECOND POSITION	MOBILE BODY	WAYPOINT
0001	P1	A1	A2	10A	⋯,A1,⋯
0002	P11	A11	A3	10B	⋯,A11,⋯
0003	P21	A21	A4	10C	⋯,A21,⋯
0004	P2	A31	A5	10A	⋯,A31,⋯
0005	P21	A41	A6	10B	⋯,A41,⋯

FIG. 7

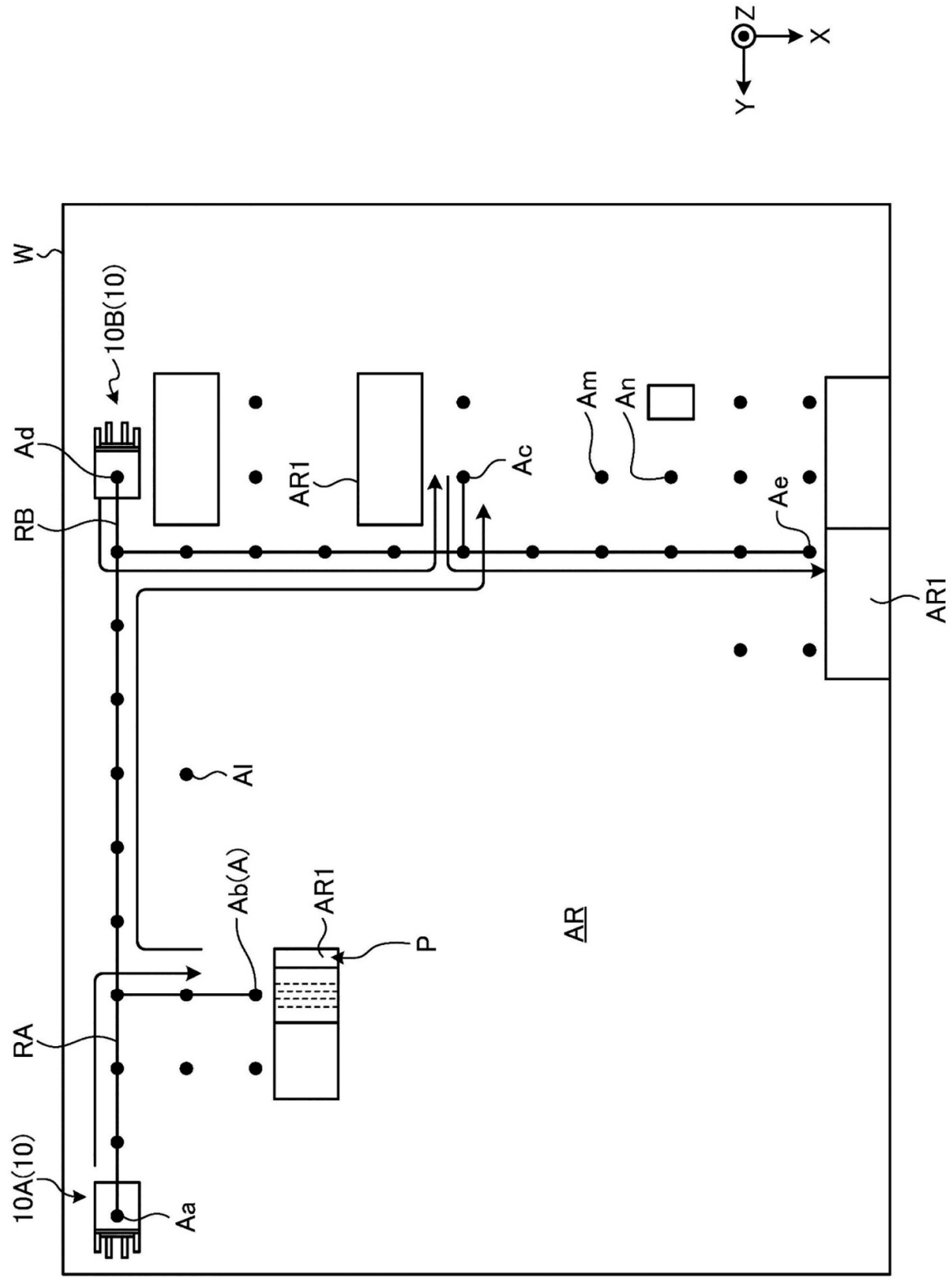


FIG. 8

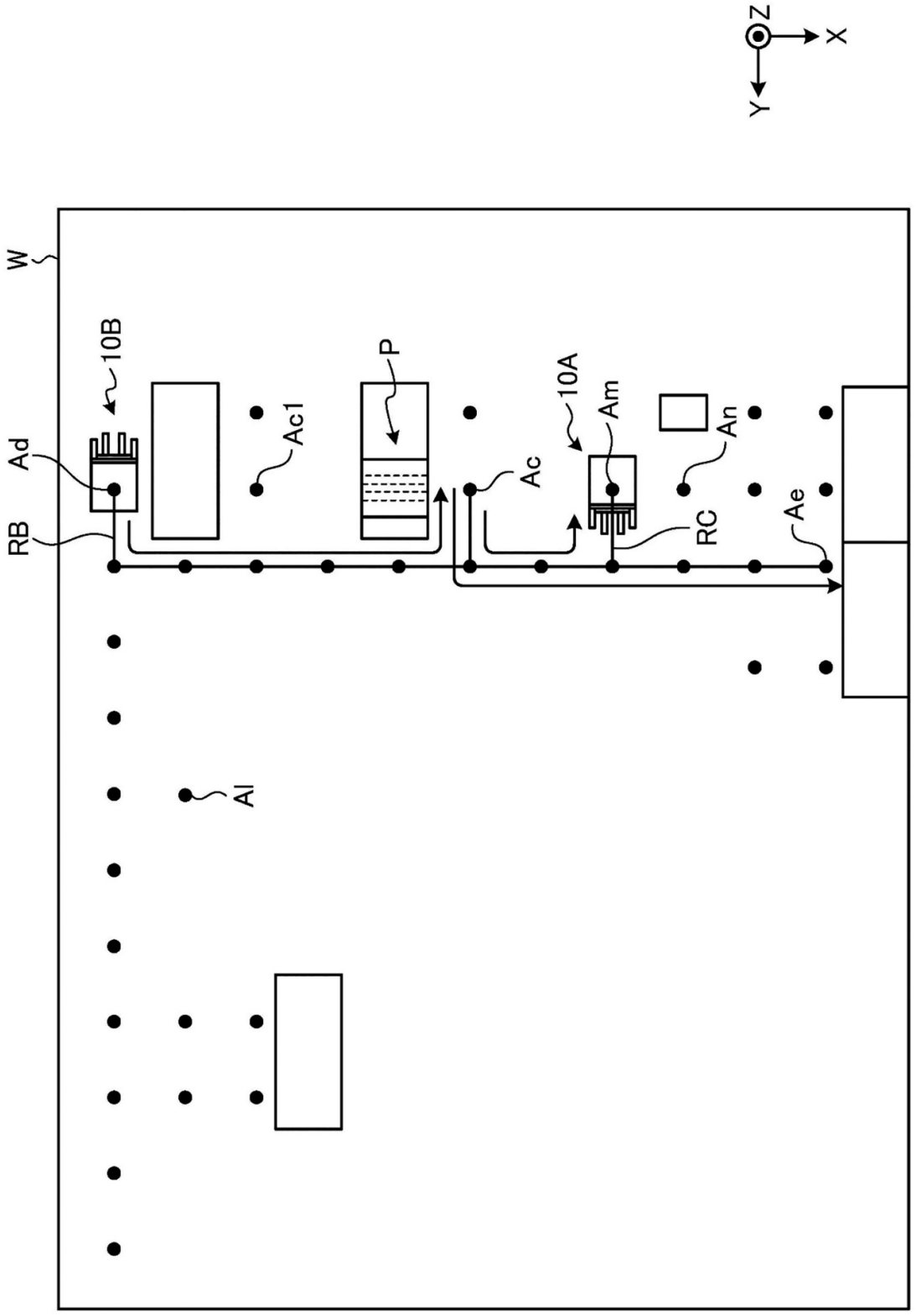


FIG. 9

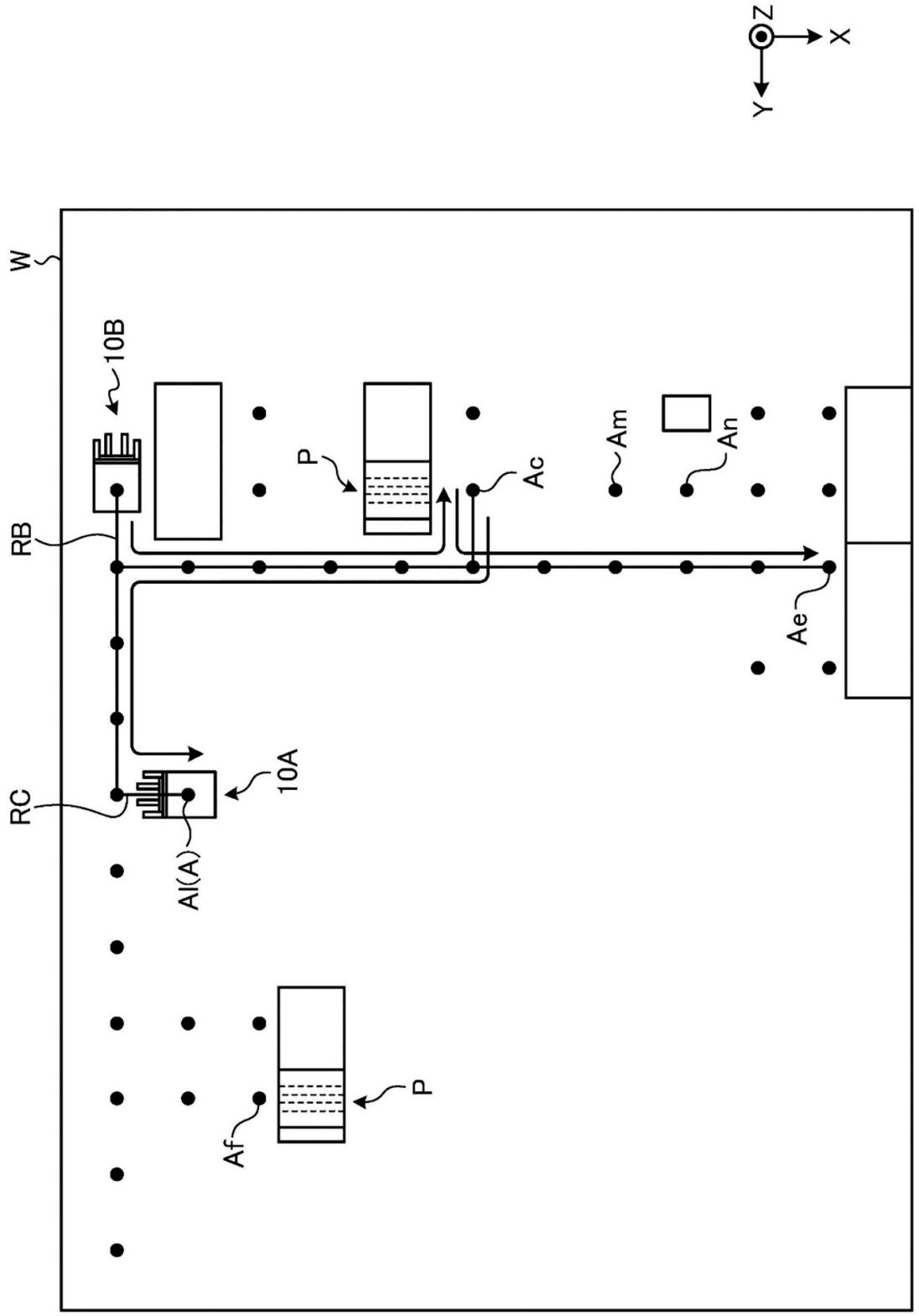


FIG. 10

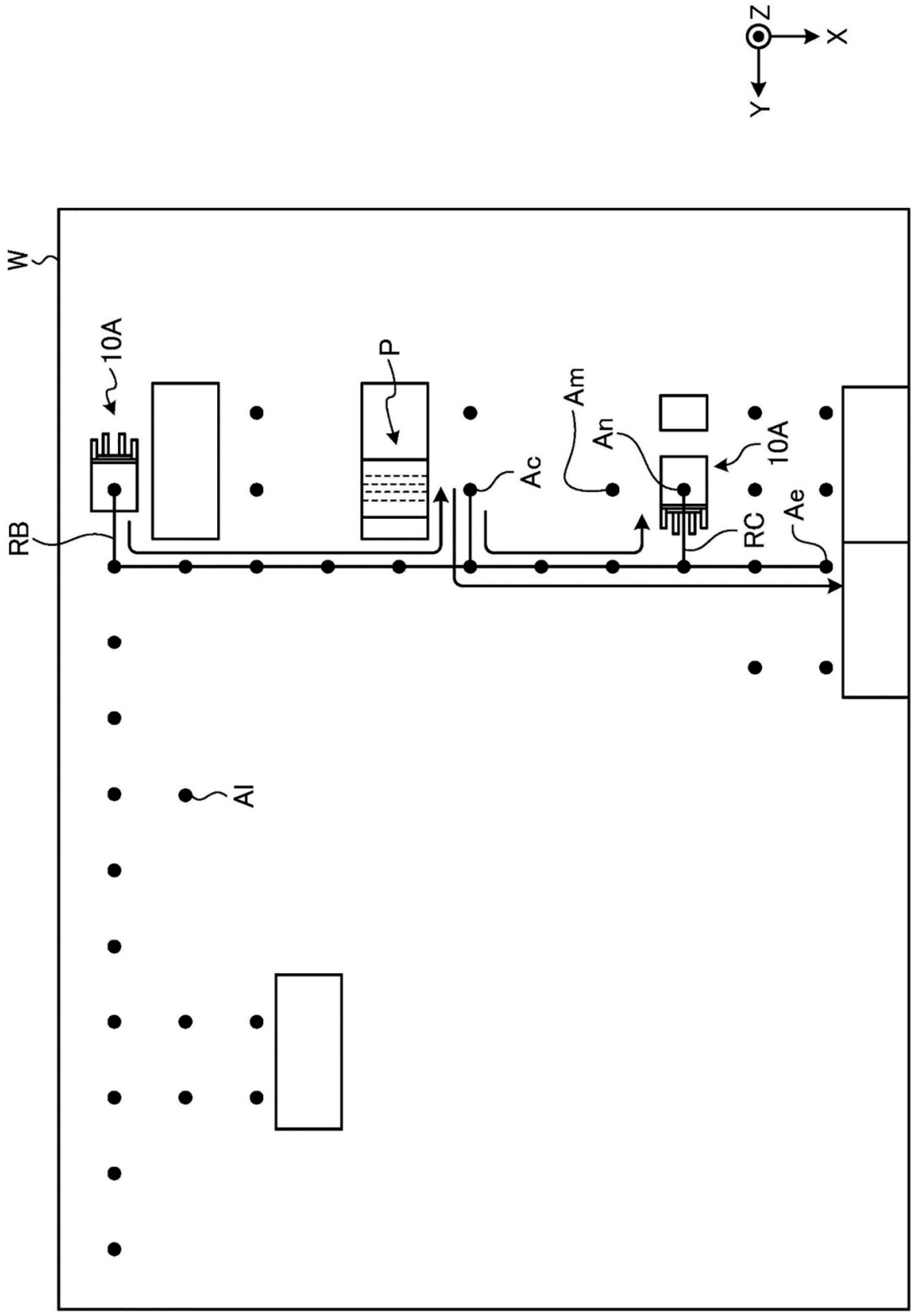


FIG. 11

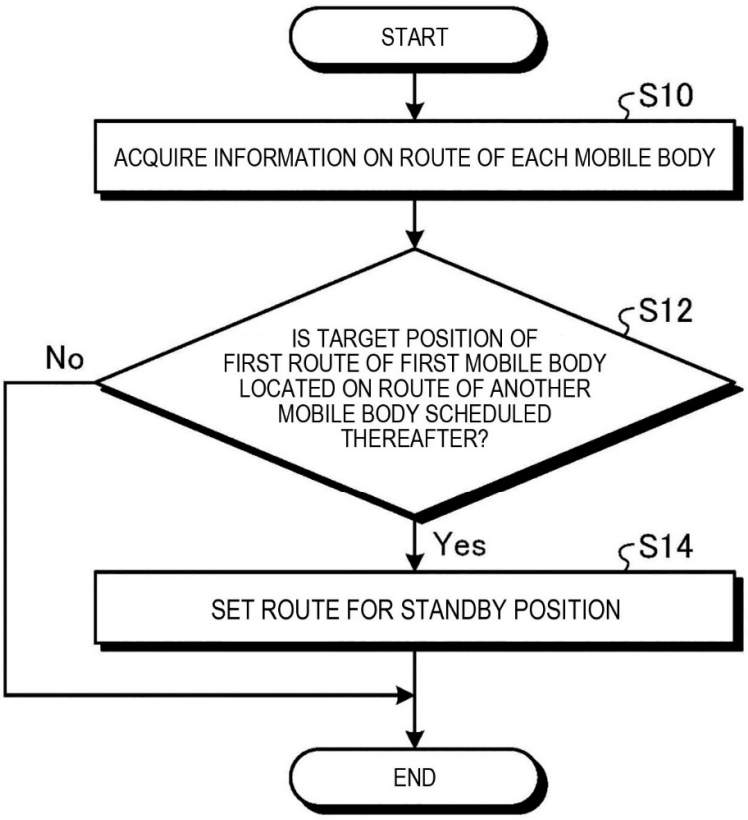

START
S10
ACQUIRE INFORMATION ON ROUTE OF EACH MOBILE BODY
S12
IS TARGET POSITION OF FIRST ROUTE OF FIRST MOBILE BODY LOCATED ON ROUTE OF ANOTHER MOBILE BODY SCHEDULED THEREAFTER?
No
Yes
S14
SET ROUTE FOR STANDBY POSITION
END

FIG. 12