

FORK AND CARRYING ROBOT

ABSTRACT

This application relates to a fork and a carrying robot. The fork includes a telescopic arm and a temporary storage tray. The telescopic arm includes a fixed arm
5 and a movable arm, the movable arm is connected to the fixed arm and is telescopically movable relative to the fixed arm. The temporary storage tray is mounted to the fixed arm and configured to temporarily store the goods, the temporary storage tray is configured to extend or retract relative to the fixed arm, wherein an extending direction of the temporary storage tray is consistent with an
10 extending direction of the movable arm. The movable arm is configured to push the temporary storage tray so as to cause the temporary storage tray to retract relative to the fixed arm.

Fig. 2