embodiment with reference to the attached figures which schematically show:

- figure 1, the structure of the moving system in its entirety according to the present invention;
- figure 2 the structure of the manipulator from a front perspective view according to the present invention;
- figure 3 the structure of the manipulator from a rear perspective view according to the present invention.

With reference to the above mentioned figures, the moving system according to the present invention comprises at least a manipulator ~~2~~ 3, adapted to grip and orient the objects in the desired positions, associated to an overhead-travelling-crane mechanism ~~3~~ 2, adapted to move this manipulator in a storehouse where the objects are placed. The manipulator is automatically controlled by an operator through an electronic processing unit associated to it.

The objects are preferably elongated objects and in a preferred embodiment are projectiles, arranged in a storehouse which must be made available for a firearm magazine. The arm is usually arranged above the storehouse, for instance it occurs in a hold of a ship.

However, more generally, the system according to the present invention, could be used, with suitable changes, in any field wherein the handling of particular objects is necessary.