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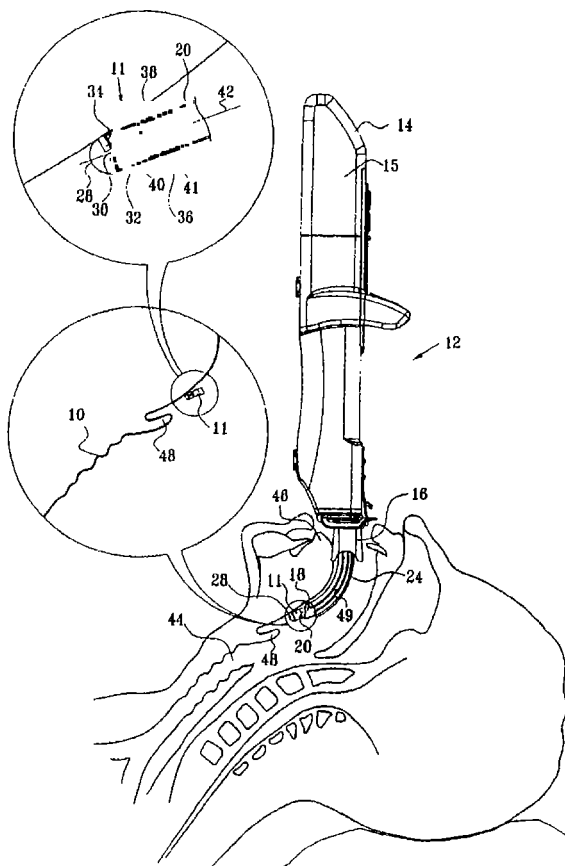
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(4) Title: APPARATUS FOR SELF-GUIDED INTUBATION

(57) Abstract: An automatically operative medical insertion device (12) and method including an insertable element (18) which is adapted to be inserted within a living organism in vivo, a surface following element (20), physically associated with the insertable element (18) and being arranged to follow a physical surface within the living organism in vivo, a driving subsystem (15) operative to at least partially automatically direct the insertable element (18) along the physical surface and a navigation subsystem (274) operative to control the driving subsystem based at least partially on a perceived location of the surface following element (20) along a reference pathway stored in the navigation subsystem (274)



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