

Abstract

The invention relates to a robotic system with at least one robotic arm and a control unit, which is designed so that it can preset at least one predefined operation that can be carried out by the robotic system. In addition, the robotic system comprises at least one input device attached to the robotic arm which is designed so that the predefined operations of the robotic system can be parameterized by means of the input device. In this case, the input device is designed so that it can provide a user-directed feedback to a user of the robotic system when setting the execution of operations, the logical sequence of the operations and/or parameterizing the predefined operations for the robotic system.

Fig. 1