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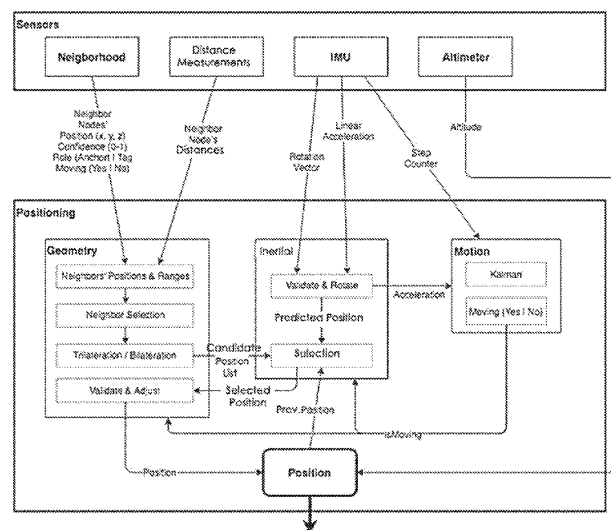


Fig. 1

(57) Abstract: The present invention mainly relates to methods for geolocation utilizing electronic distance measurement equipment. These methods select a small subset of available data that is most trustworthy, and then use simple mathematical treatment of said subset of data (preferably bilateration or trilateration) to compute one or more new Measured Position candidates, among which one may be chosen based on Confidence metrics, relative Position geometry, and the comparison with history-based Predicted Position and its respective Confidence metric. In a case where no Measured Position candidates of sufficient Confidence are available, the Predicted Position is taken as the new Position.

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