

CONTROL DEVICE FOR VEHICLE TRAVELING

Abstract of the Disclosure

The autonomous LC control is started in response to receiving a start instruction of autonomous lane change (102 to 104). When the driver performs a steering intervention in a same direction as a direction of steering requested by the autonomous LC control (104 to 106), and establishment of a stop condition of lane change is not recognized, during execution of the autonomous LC control, the autonomous driving control is continued (106 to 104 to 102). When the steering intervention in the same direction is performed (104 to 106), and establishment of the stop condition is recognized, during execution of the autonomous LC control, termination of the autonomous driving control is announced (106 to 108).

[FIG. 3]