

ABSTRACT

The present invention relates to the field of artificial intelligence, and discloses a three-way calling terminal for a mobile human-machine coordination calling robot. Technical solutions of the present invention include: a first speech interface, configured to transfer call audio between a
5 call object and a back-end processing module; a CODEC1 module, configured to encode and decode the call audio between the call object and the back-end processing module; a second speech interface, configured to transfer call audio between the human agent and the call object; a CODEC2 module, configured to encode and decode the call audio between the human agent and the call object; a call control module, configured to process a control signal, and automatically
10 make, answer, and hang up a call; a data processing submodule, configured to process speech data and perform data transfer between the data processing submodule and the back-end processing module; and a networking submodule, configured to be connected to the back-end processing module. The three-way calling terminal can be decoupled from a communications system, and therefore is easy for deployment and is convenient for switching, having movability,
15 so that the three-way calling terminal can be conveniently placed in various places.