

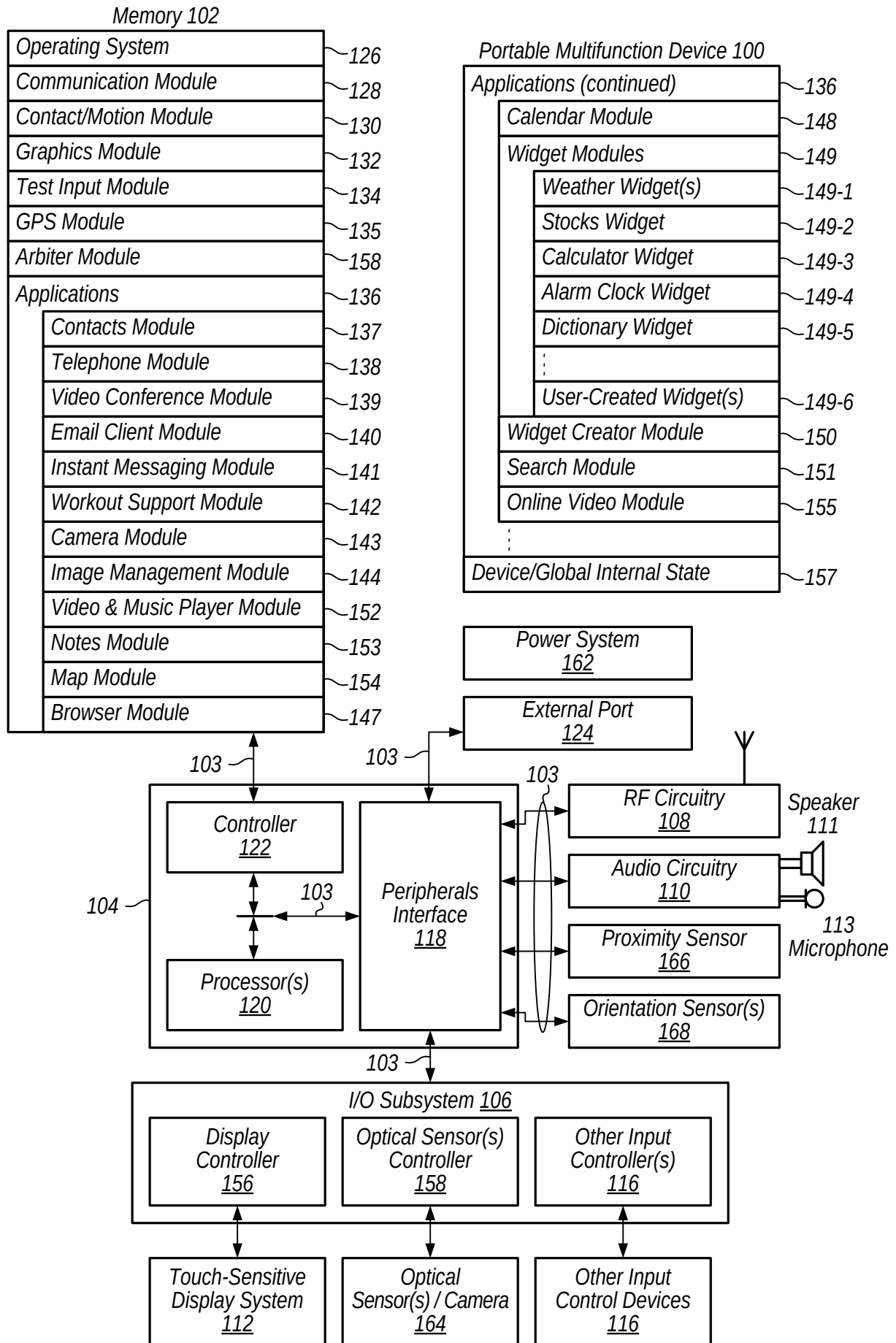


FIG. 1

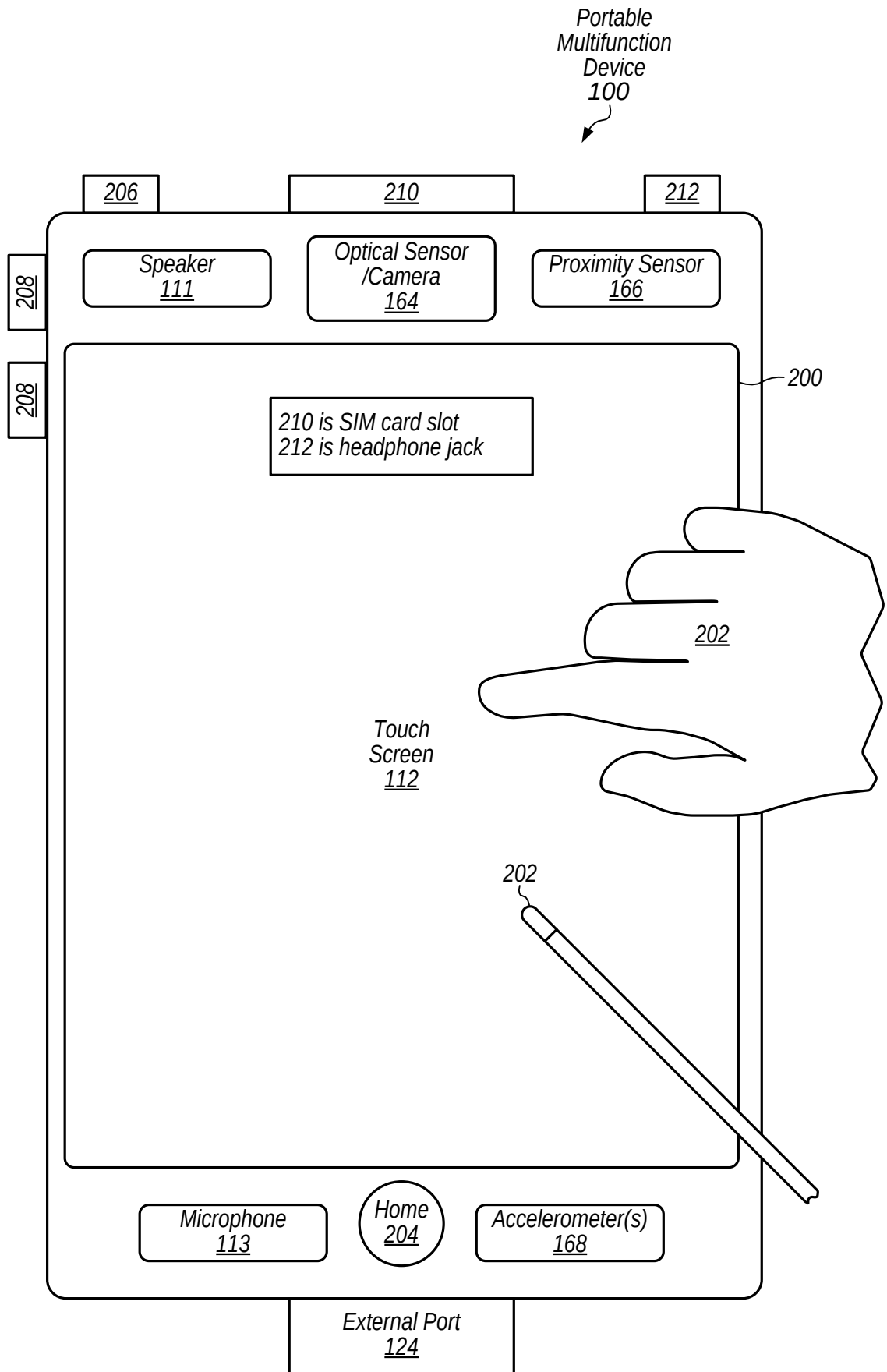


FIG. 2

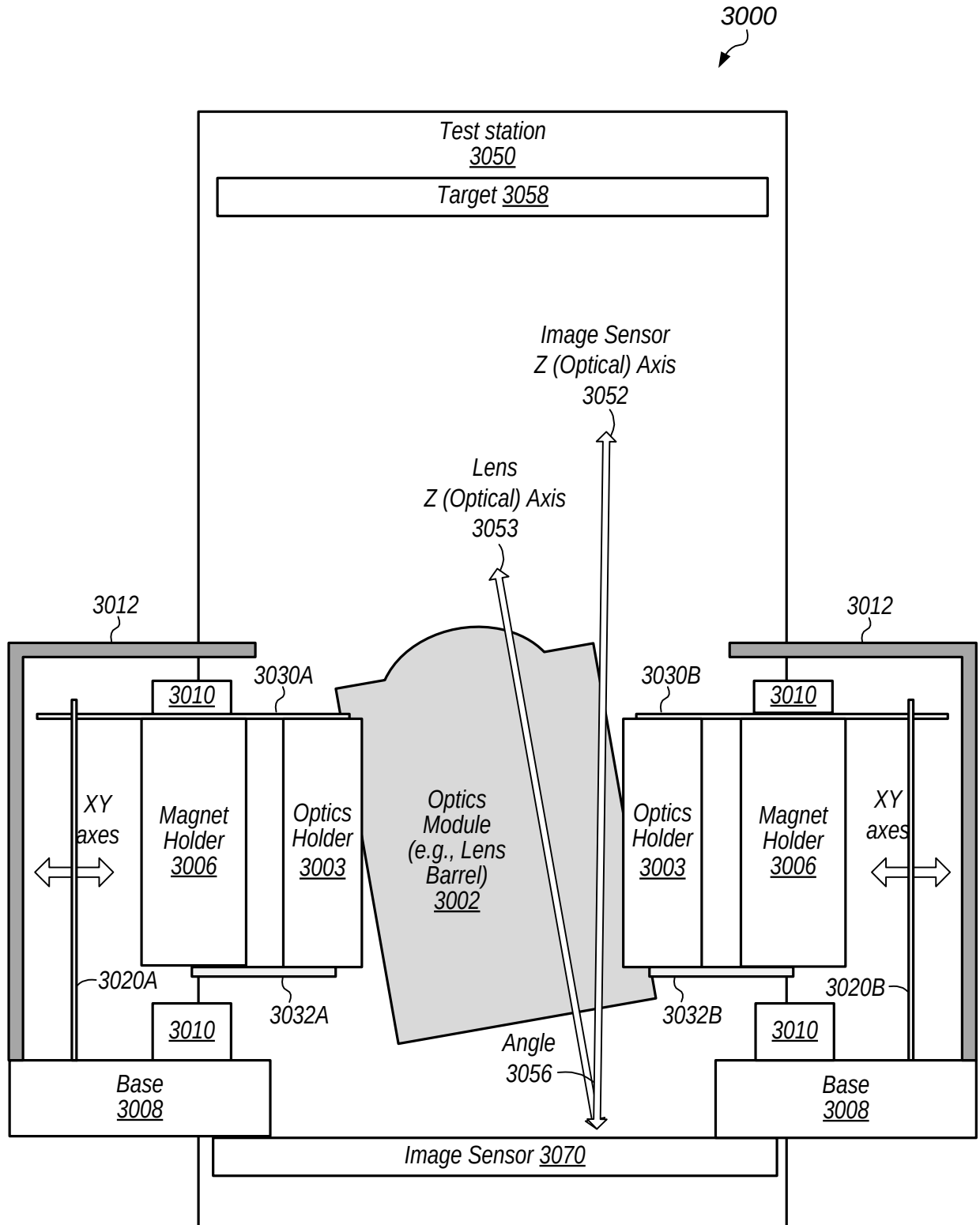


FIG. 3

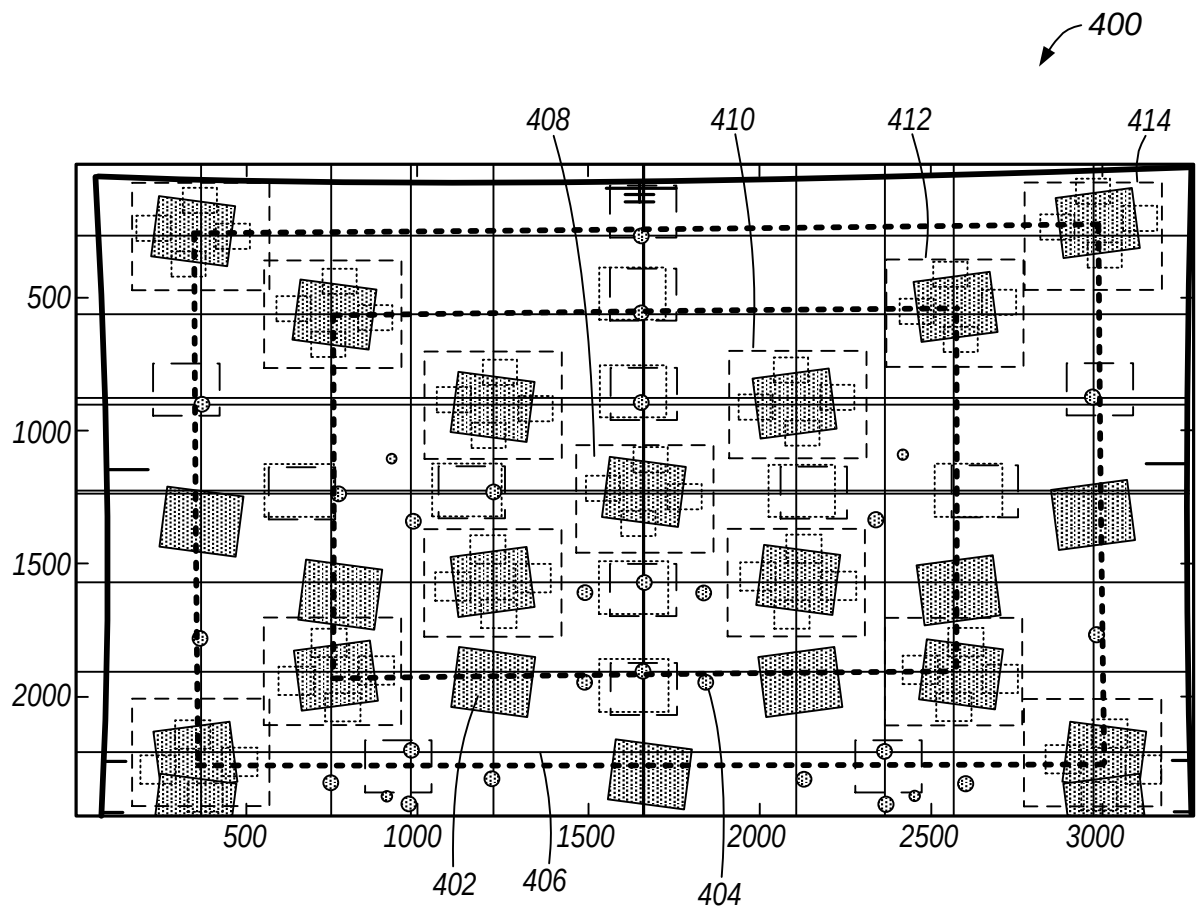


FIG. 4

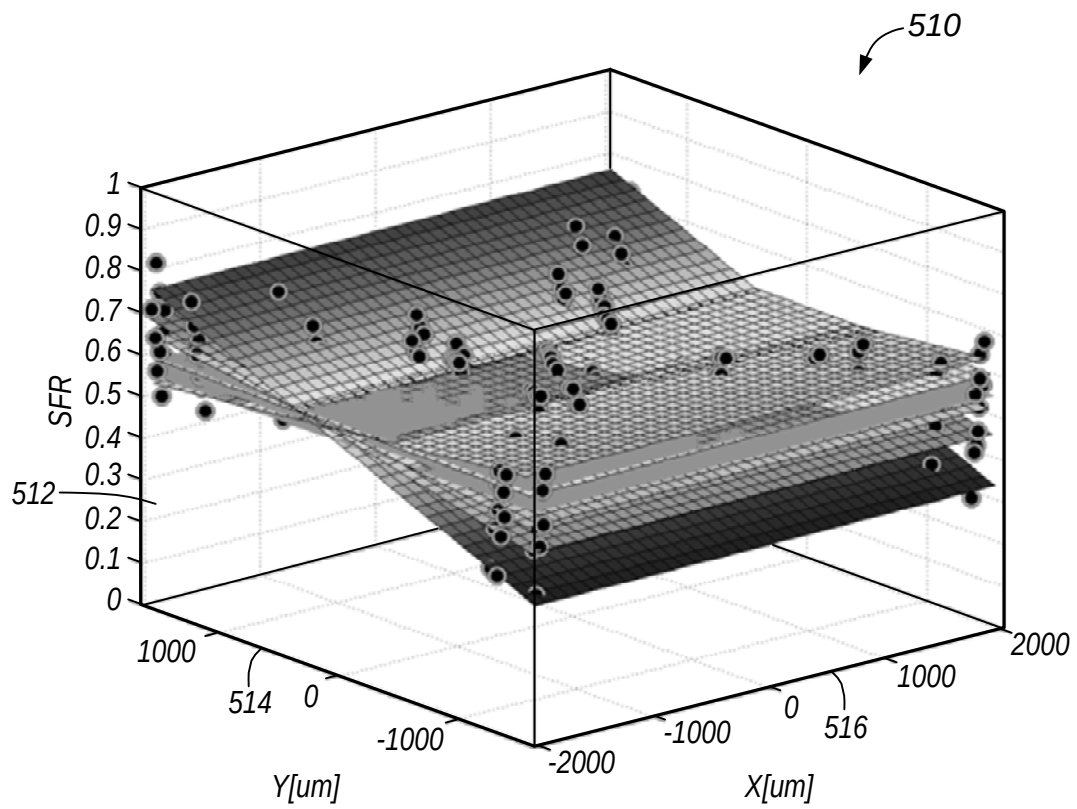
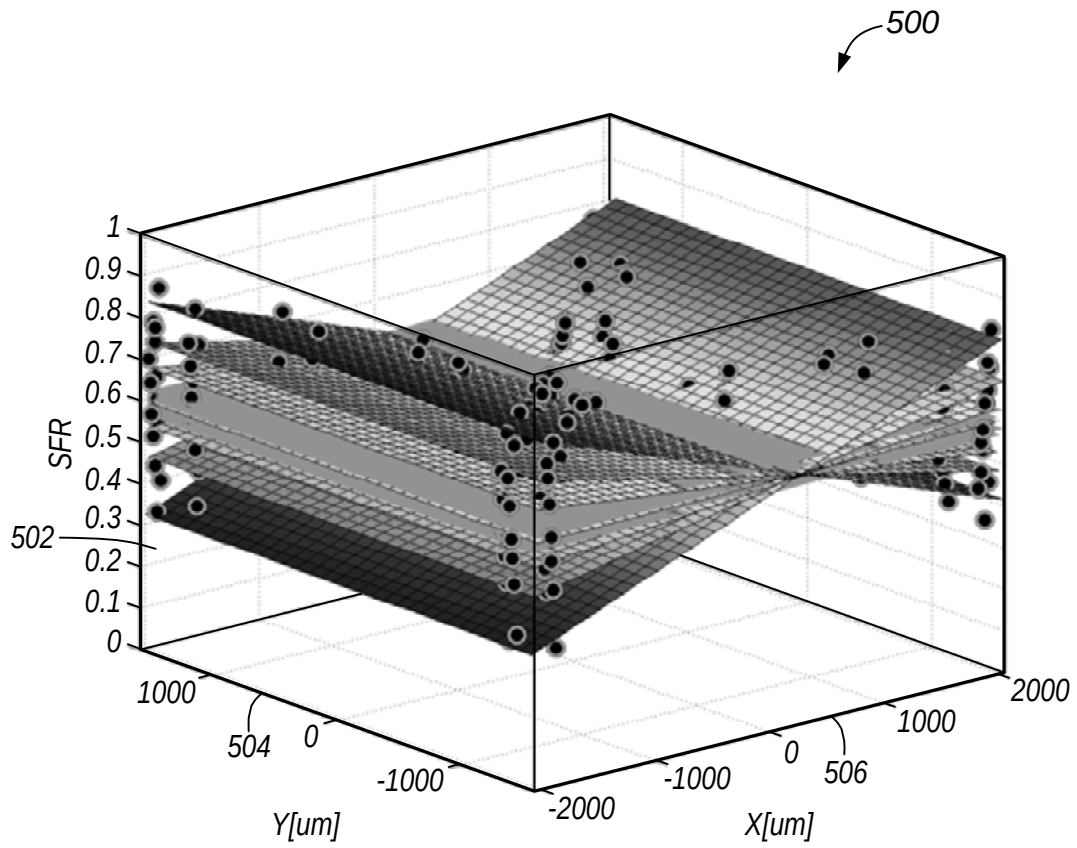


FIG. 5

R_x : x-rotation (roll)			R_y : y-rotation (pitch)		
1	0	0	$\cos(\theta_y)$	0	$\sin(\theta_y)$
0	$\cos(\theta_x)$	$-\sin(\theta_x)$	0	1	0
0	$\sin(\theta_x)$	$\cos(\theta_x)$	$-\sin(\theta_y)$	0	$\cos(\theta_y)$

602

604

FIG. 6

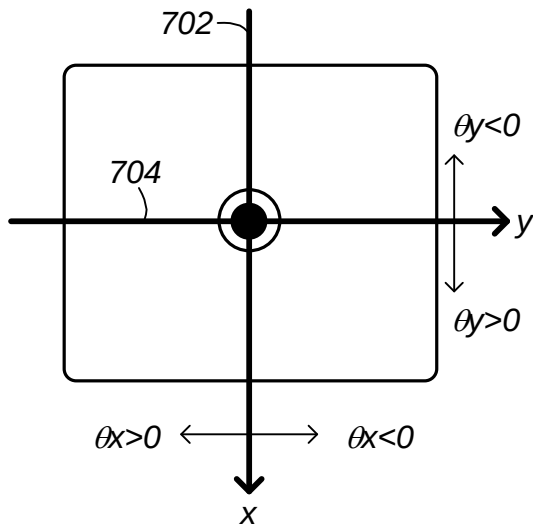


FIG. 7A

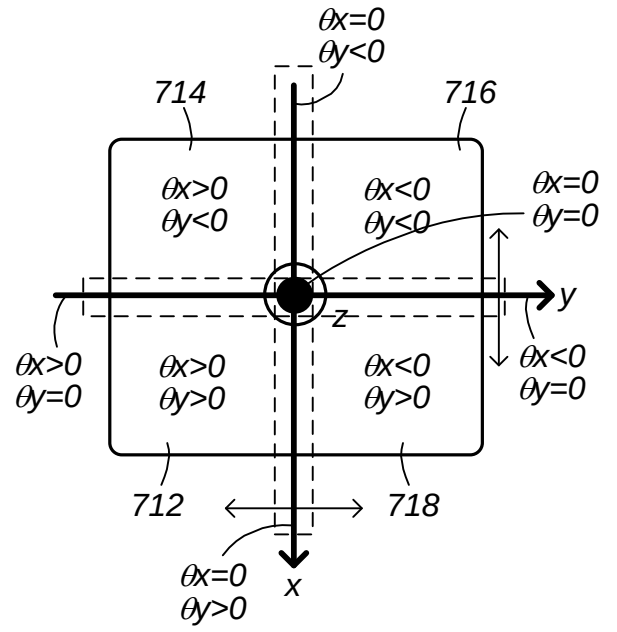


FIG. 7B

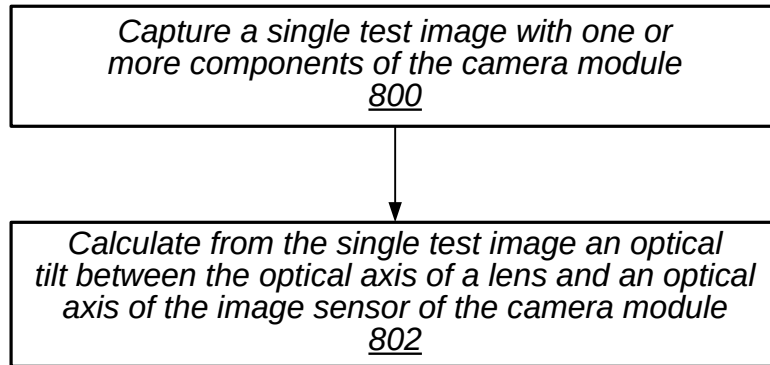


FIG. 8

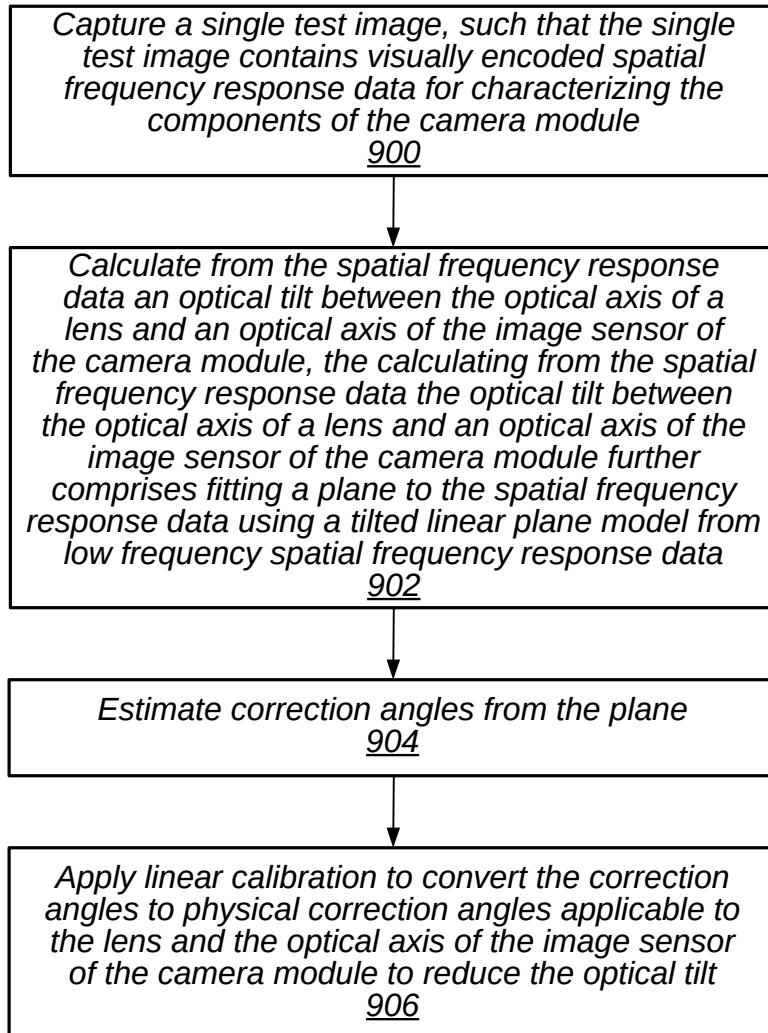


FIG. 9

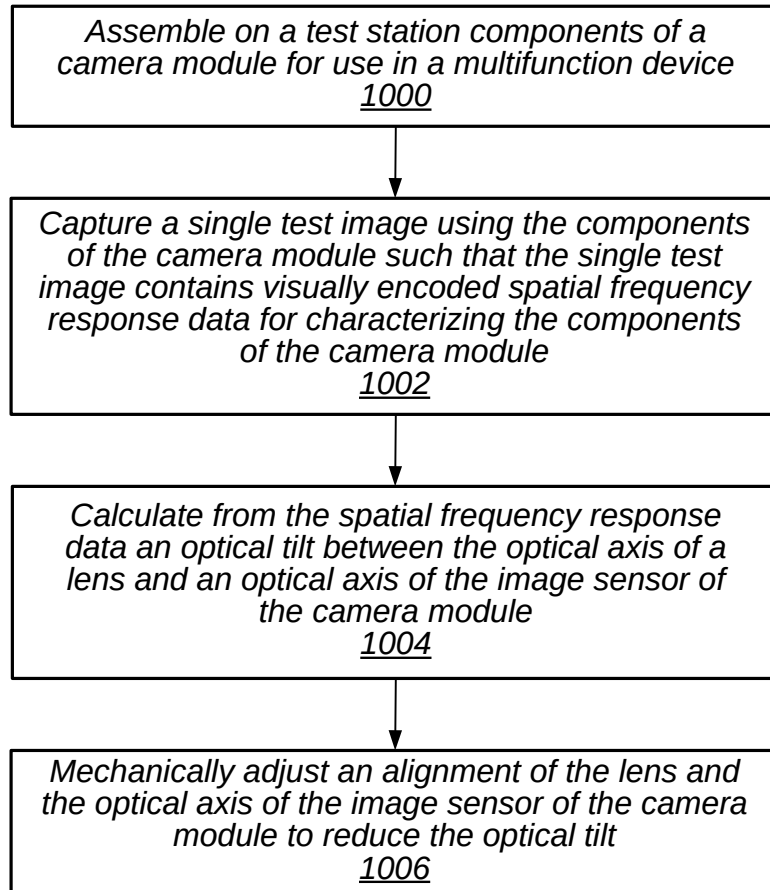


FIG. 10

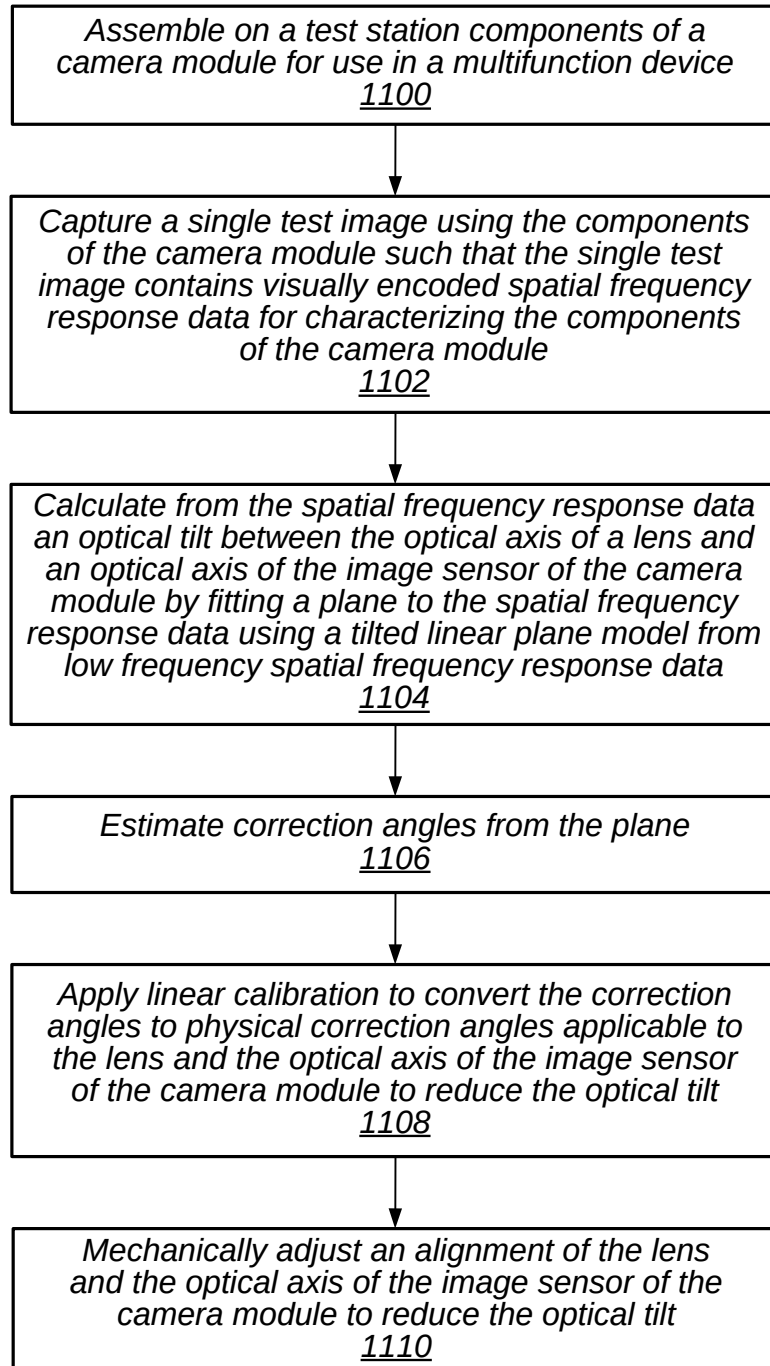


FIG. 11

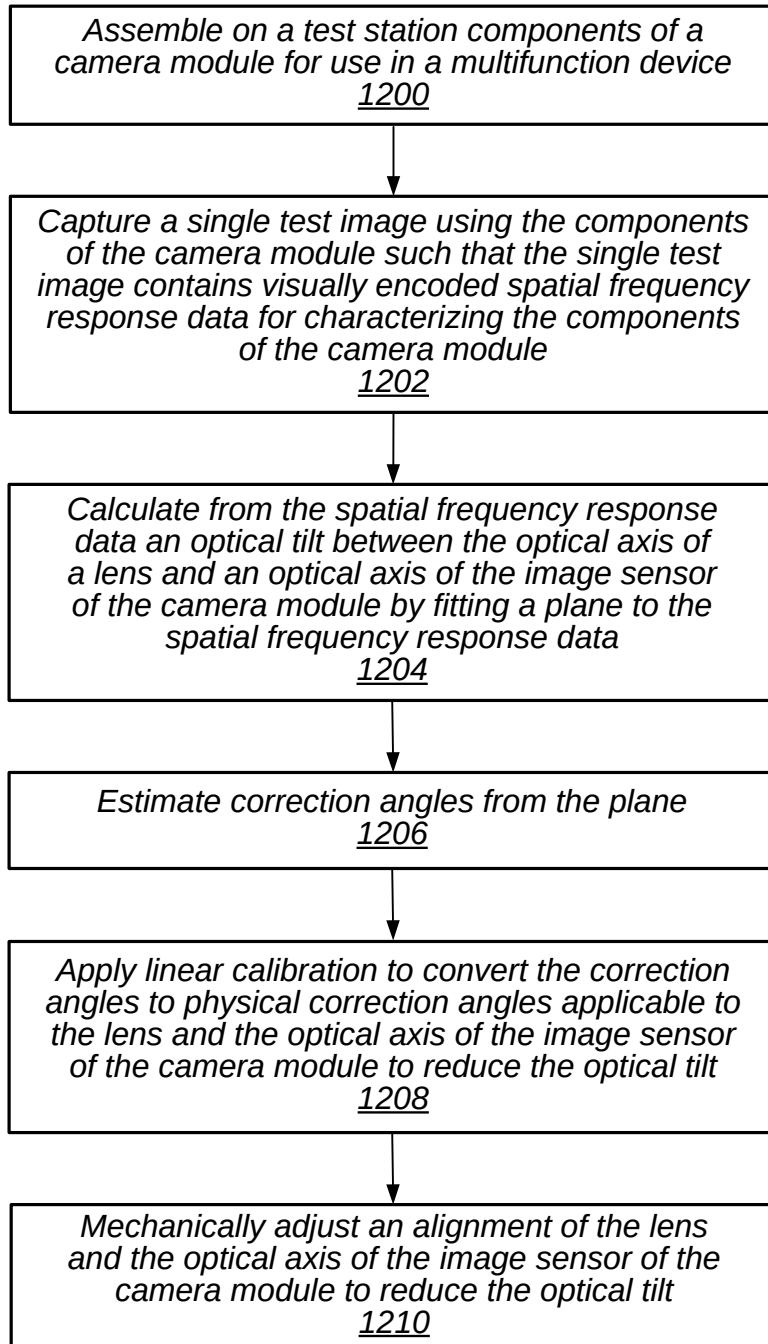


FIG. 12

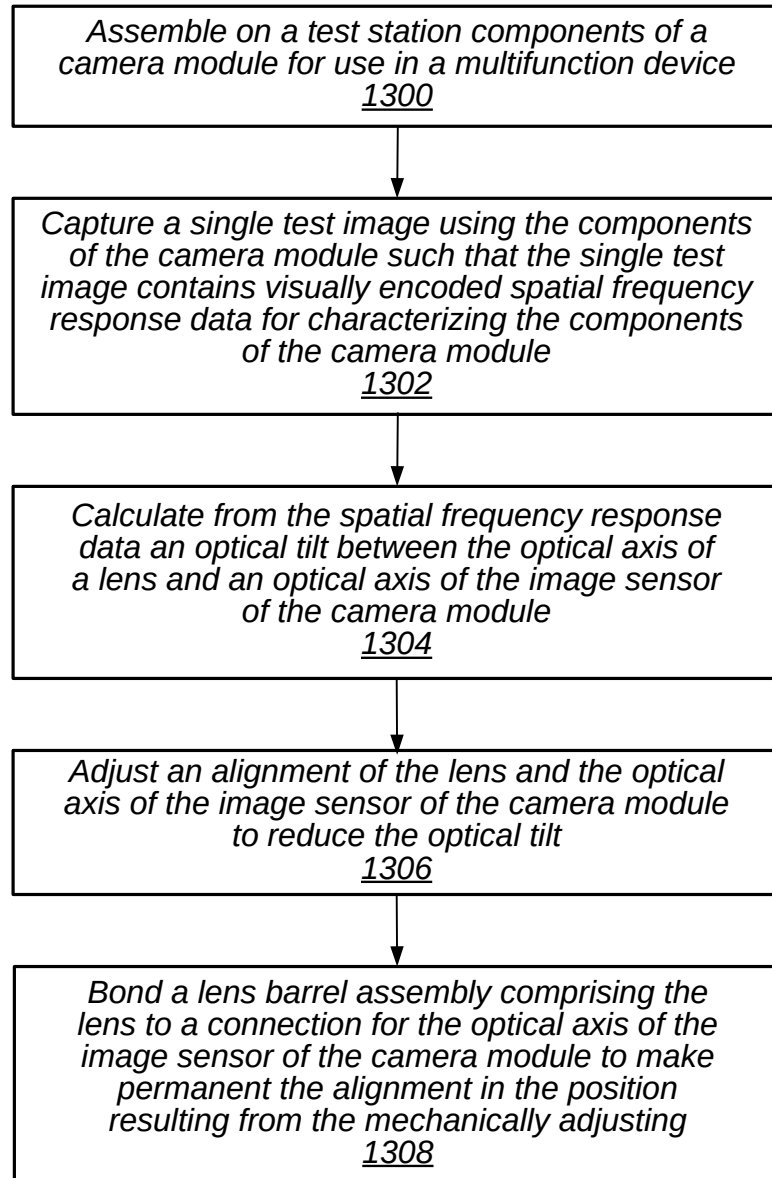


FIG. 13

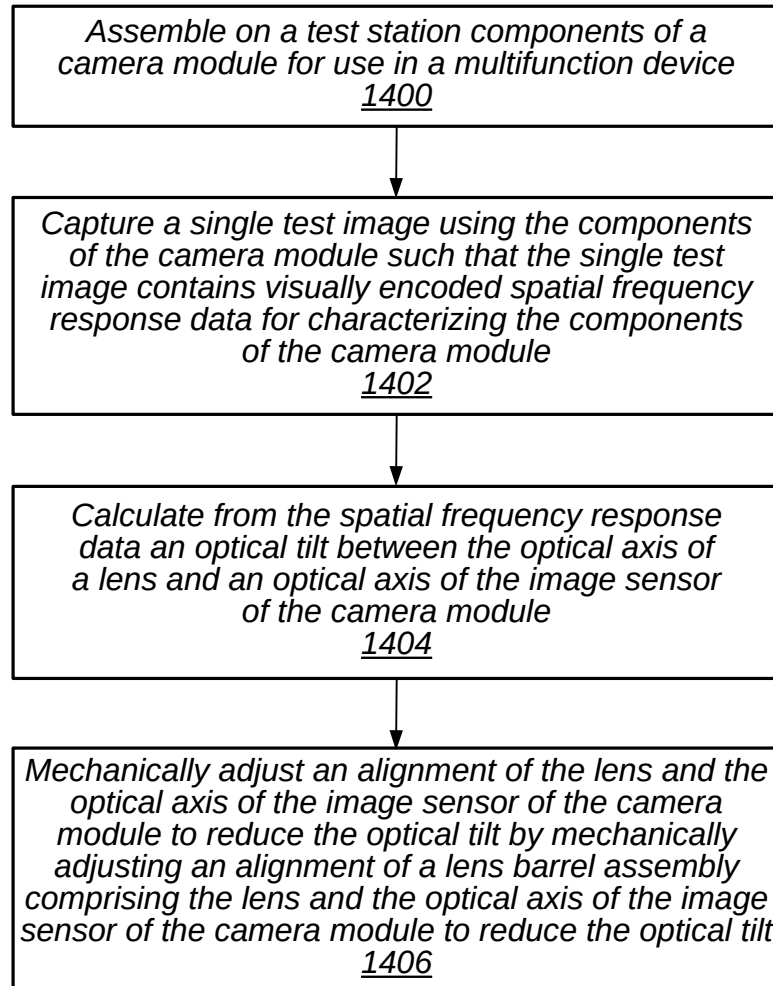


FIG. 14

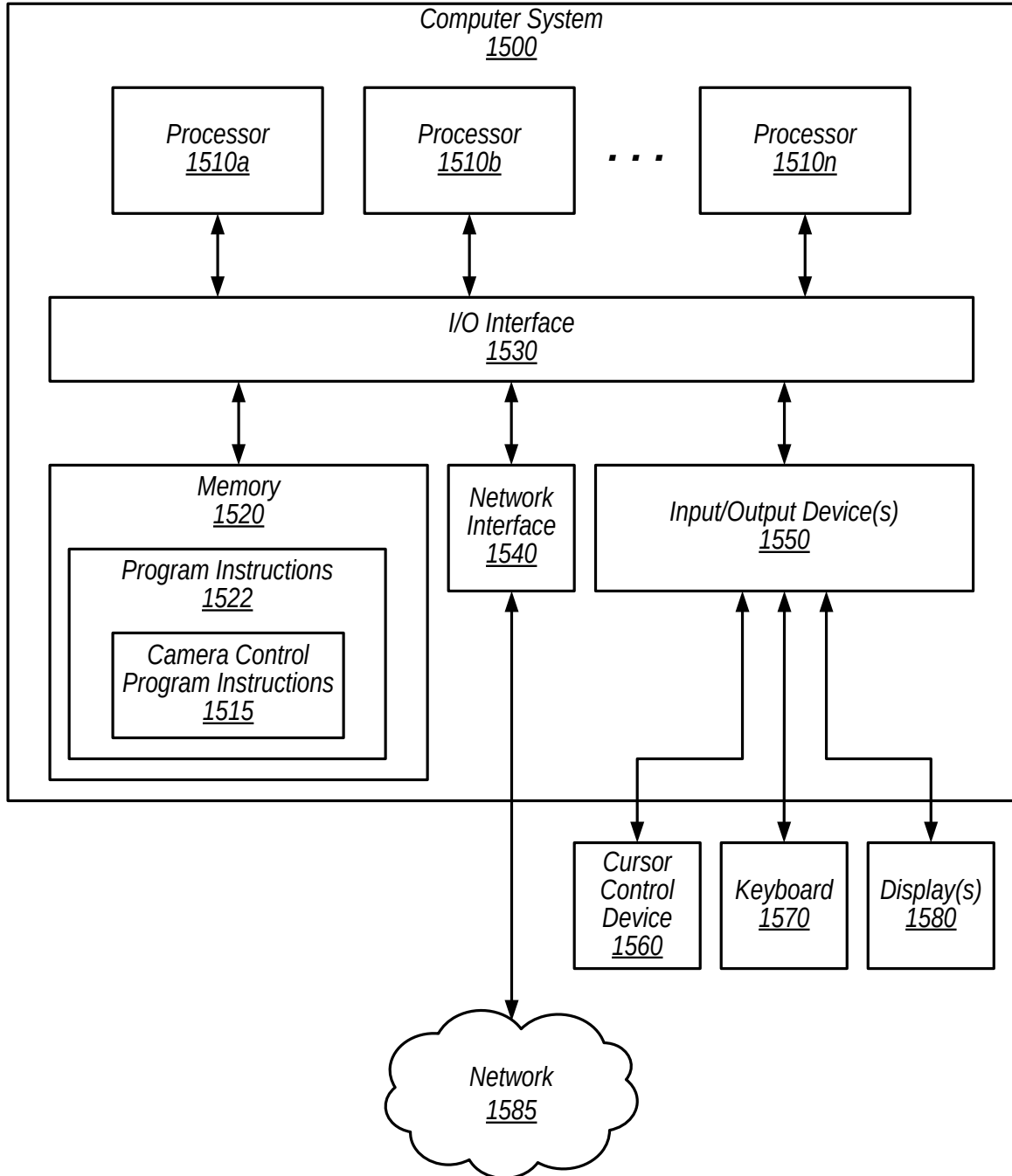


FIG. 15