

Abstract

An underwater cleaning robot (20) contains a movement device (23) for moving the underwater cleaning robot (20) under water, a cleaning device (24) for cleaning an object (2, 3) located under water, a control device (25) for controlling the movement device (23) and/or the cleaning device (24) and a communication device (26, 27) for receiving and/or transmitting signals from outside the underwater cleaning robot (20) and vice versa. The communication device contains a first ultrasonic transducer (27) for receiving ultrasonic signals transmitted under water and is designed to transmit electrical signals, corresponding to the ultrasonic signals (39) received, to the control device (25).

(Fig. 2)