(12) INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

CORRECTED VERSION

(19) World Intellectual Property Organization
International Bureau

(43) International Publication Date
15 September 2005 (15.09.2005)

PCT

(10) International Publication Number
WO 2005/084542 A1

(51) International Patent Classification[7]: A61B 5/103, 1/00, A61M 25/00, G01L 1/24, 1/10

(21) International Application Number: PCT/SG2005/000063

(22) International Filing Date: 1 March 2005 (01.03.2005)

(25) Filing Language: English

(26) Publication Language: English

(30) Priority Data:
200401086-4 4 March 2004 (04.03.2004) SG

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(81) Designated States *(unless otherwise indicated, for every kind of national protection available)*: AE, AG, AL, AM, AT, AU, AZ, BA, BB, BG, BR, BW, BY, BZ, CA, CH, CN, CO, CR, CU, CZ, DE, DK, DM, DZ, EC, EE, EG, ES, FI, GB, GD, GE, GH, GM, HR, HU, ID, IL, IN, IS, JP, KE, KG, KP, KR, KZ, LC, LK, LR, LS, LT, LU, LV, MA, MD, MG, MK, MN, MW, MX, MZ, NA, NI, NO, NZ, OM, PG, PH, PL, PT, RO, RU, SC, SD, SE, SG, SK, SL, SM, SY, TJ,

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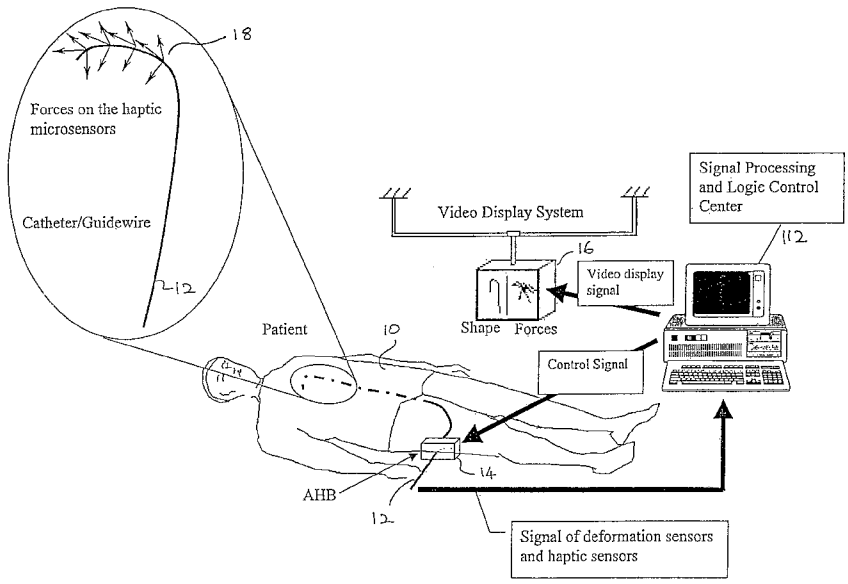
(54) Title: APPARATUS FOR MEDICAL AND/OR SIMULATION PROCEDURES



(57) Abstract: In a preferred embodiment, medical apparatus comprising a catheter (12) which operable to be inserted into a human subject (10) is disclosed herein. Haptic sensors (22, 24) and deformation sensors (26, 27) are connected to the catheter (12) and these are disposed at a plurality of locations along the length of the catheter (12). The haptic sensors measures 3D forces (18) acting on the catheter (12) at the disposed locations and these forces are provided to a haptic feedback device (14) which provides haptic feedback to, an interventional radiologist. The deformation sensors (26, 27) on the other hand, measures the deformation of the catheter (12) at the disposed locations and this information determines the shape of the catheter (12) which is represented on a display (16) for viewing by the radiologist.

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TM, TN, TR, TT, TZ, UA, UG, US, UZ, VC, VN, YU, ZA, ZM, ZW.

(84) Designated States *(unless otherwise indicated, for every kind of regional protection available)*: ARIPO (BW, GH, GM, KE, LS, MW, MZ, NA, SD, SL, SZ, TZ, UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, MD, RU, TJ, TM), European (AT, BE, BG, CH, CY, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HU, IE, IS, IT, LT, LU, MC, NL, PL, PT, RO, SE, SI, SK, TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, ML, MR, NE, SN, TD, TG).

Declaration under Rule 4.17:
— *of inventorship (Rule 4.17(iv)) for US only*

Published:
— *with international search report*

(48) Date of publication of this corrected version:
8 December 2005

(15) Information about Correction:
see PCT Gazette No. 49/2005 of 8 December 2005, Section II

For two-letter codes and other abbreviations, refer to the "Guidance Notes on Codes and Abbreviations" appearing at the beginning of each regular issue of the PCT Gazette.