



- (51) **International Patent Classification:**
B25J 15/12 (2006.01) *B25J 9/10* (2006.01)
- (21) **International Application Number:**
PCT/SG2024/050593
- (22) **International Filing Date:**
17 September 2024 (17.09.2024)
- (25) **Filing Language:** English
- (26) **Publication Language:** English
- (30) **Priority Data:**
10202302998W 23 October 2023 (23.10.2023) SG
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- (81) **Designated States** (*unless otherwise indicated, for every kind of national protection available*): AE, AG, AL, AM, AO, AT, AU, AZ, BA, BB, BG, BH, BN, BR, BW, BY, BZ, CA, CH, CL, CN, CO, CR, CU, CV, CZ, DE, DJ, DK, DM, DO, DZ, EC, EE, EG, ES, FI, GB, GD, GE, GH, GM, GT, HN, HR, HU, ID, IL, IN, IQ, IR, IS, IT, JM, JO, JP, KE, KG, KH, KN, KP, KR, KW, KZ, LA, LC, LK, LR, LS, LU, LY, MA, MD, MG, MK, MN, MU, MW, MX, MY, MZ, NA, NG, NI, NO, NZ, OM, PA, PE, PG, PH, PL, PT, QA, RO, RS, RU, RW, SA, SC, SD, SE, SG, SK, SL, ST, SV, SY, TH, TJ, TM, TN, TR, TT, TZ, UA, UG, US, UZ, VC, VN, WS, ZA, ZM, ZW.

- (84) **Designated States** (*unless otherwise indicated, for every kind of regional protection available*): ARIPO (BW, CV, GH, GM, KE, LR, LS, MW, MZ, NA, RW, SC, SD, SL, ST, SZ, TZ, UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, RU, TJ, TM), European (AL, AT, BE, BG, CH, CY, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HR, HU, IE, IS, IT, LT, LU, LV, MC, ME, MK, MT, NL, NO, PL, PT, RO, RS, SE, SI, SK, SM, TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, KM, ML, MR, NE, SN, TD, TG).

(54) **Title:** GRIPPER AND GRIPPER SYSTEM

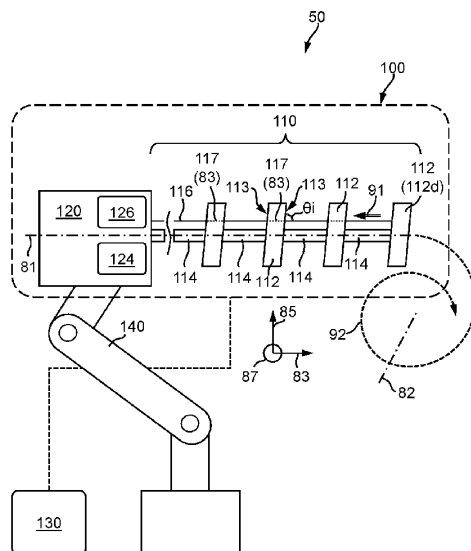


FIG. 1

- (57) **Abstract:** Disclosed herein is a gripper and a gripper system. The gripper comprises: a housing; a finger body movable relative to the housing along a finger axis, the finger body comprising: actuating members, each defining: a pair of contact surfaces disposed opposing each other and a path formed passing through the pair of contact surfaces; connecting members, each movably coupled between a respective pair of the actuating members; and an elongated member passing through the respective path of selected ones of the plurality of actuating members to define a respective first axis, the elongated member being fixedly coupled to a distal one of the actuating member, wherein for each selected ones of the actuating members, at least one of the pair of contact surfaces forms a first tilt in relative to the respective first axis, the first tilt being characterized by: in relative to the first axis, forming a first oblique angle about a respective second axis and forming a second oblique angle about a respective third axis.

Published:

— with international search report (Art. 21(3))