

Encoding and Decoding of Pulse Positions of Tracks of an Audio Signal

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Specification

The present invention relates to the field of audio processing and audio coding, in particular to encoding and decoding of pulse positions of tracks in an audio signal.

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Audio processing and/or coding has advanced in many ways. In audio coding, linear predictive coders play an important role. When encoding an audio signal, e.g. an audio signal comprising speech, linear predictive encoders usually encode a representation of the spectral envelope of the audio signal. To this end, linear predictive encoders may determine predictive filter coefficients to represent the spectral envelope of sound in encoded form. The filter coefficients may then be used by a linear predictive decoder to decode the encoded audio signal by generating a synthesized audio signal using the predictive filter coefficients.

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Important examples for linear predictive coders are ACELP coders (ACELP = Algebraic Code-Excited Linear Prediction coders). ACELP coders are widely used, for example, in USAC (USAC = Unified Speech and Audio Coding) and may have further application fields, for example in LD-USAC (Low Delay Unified Speech and Audio Coding).

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ACELP encoders usually encode an audio signal by determining predictive filter coefficients. To achieve better encoding, ACELP encoders determine a residual signal, also referred to as target signal, based on the audio signal to be encoded, and based on the already determined predictive filter coefficients. The residual signal may, for example, be a difference signal representing a difference between the audio signal to be encoded and the signal portions that are encoded by the predictive filter coefficients, and, possibly, by adaptive filter coefficients resulting from a pitch analysis. The ACELP encoder then aims to encode the residual signal. For this, the encoder encodes algebraic codebook parameters, which are used to encode the residual signal.

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To encode the residual signal, algebraic codebooks are used. Usually, algebraic codebooks comprise a plurality of tracks, for example, four tracks each comprising 16 track positions. In such a configuration, a total of $4 \cdot 16 = 64$ sample positions can be represented by a

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respective algebraic codebook, for example, corresponding to the number of samples of a subframe of the audio signal to be encoded.

5 The tracks of the codebook may be interleaved such that track 0 of the codebook may represent samples 0, 4, 8, ..., 60 of the subframe, such that track 1 of the codebook may represent samples 1, 5, 9, ..., 61 of the subframe, such that track 2 of the codebook may represent samples 2, 6, 10, ..., 62 of the subframe, and such that track 3 of the codebook may represent samples 3, 7, 11, ..., 63 of the subframe. Each track may have a fixed number of pulses. Or, the number of pulses per track may vary, e.g. depending on other
10 conditions. A pulse may, for example, be positive or negative, e.g. may be represented by +1 (positive pulse) or 0 (negative pulse).

For encoding the residual signal, when encoding, a codebook configuration may be chosen, that best represents the remaining signal portions of the residual signal. For this, the
15 available pulses may be positioned at suitable track positions that reflect best the signal portions to be encoded. Moreover, it may be specified, whether a corresponding pulse is positive or negative.

On a decoder side, an ACELP decoder would at first decode the algebraic codebook
20 parameters. The ACELP decoder may also decode the adaptive codebook parameters. To determine the algebraic codebook parameters, the ACELP decoder may determine the plurality of pulse positions for each track of an algebraic codebook. Moreover, the ACELP decoder may also decode, whether a pulse at a track position is a positive or a negative pulse. Furthermore, the ACELP decoder may also decode the adaptive codebook
25 parameters. Based on this information, the ACELP decoder usually generates an excitation signal. The ACELP decoder then applies the predictive filter coefficients on the excitation signal to generate a synthesized audio signal to obtain the decoded audio signal.

In ACELP, pulses on a track are generally encoded as follows. If the track is of length 16
30 and if the number of pulses on this track is one, then we can encode the pulse position by its position (4 bits) and sign (1 bit), totaling 5 bits. If the track is of length 16 and the number of pulses is two, then the first pulse is encoded by its position (4 bits) and sign (1 bit). For the second pulse we need to encode the position only (4 bits), since we can choose that the sign of the second pulse is positive if it is to the left of the first pulse, negative if it
35 is to the right of the first pulse and the same sign as the first pulse if it is at the same position as the first pulse. In total, we therefore need 9 bits to encode 2 pulses. In comparison to encoding the pulse positions separately, by 5 bits each, we thus save 1 bit for every pair of pulses.

Encoding a larger number of pulses than 2, we can encode pulses pair-wise and if the number of pulses is odd, encode the last pulse separately. Then, for example, for a track of 5 pulses, we would need $9+9+5 = 23$ bits. If we have 4 tracks, then $4 \times 23 = 92$ bits would
5 be required for encoding a subframe of length 64 with 4 tracks and 5 pulses per track. However, it would be very appreciated, if the number of bits could furthermore be reduced.

It would be very appreciated, if an apparatus for encoding and a respective apparatus for decoding with improved encoding or decoding concepts would be provided, which have
10 means to encode or decode pulse information in an improved way using fewer bits for pulse information representation, as this would, for example, reduce the transmission rate for transmitting a respectively encoded audio signal, and as furthermore, this would, for example, reduce the storage needed to store a respectively encoded audio signal.

15 It is therefore an object of the present invention to provide improved concepts for encoding and decoding of pulses of tracks of an audio signal. The objects of the present invention are achieved by an apparatus for decoding according to claim 1, an apparatus for encoding according to claim 9, a method for decoding according to claim 13 a method for encoding according to claim 14, and a computer program according to claim 15.

20 According to embodiments, it is assumed that one state number is available for an apparatus for decoding. It is furthermore assumed that a track positions number, indicating the total number of track positions of at least one of the tracks associated with the encoded audio signal, and a total pulses number, indicating the number of pulses of at least one of
25 the tracks, is available for a decoding apparatus of the present invention. Preferably, the track positions number and the total pulses number is available for each track associated with an encoded audio signal.

For example, having 4 tracks with 5 pulses, each can attain roughly 6.6×10^{21} states,
30 which can, according to embodiments, be encoded by 73 bits, which is approximately 21% more efficient than the encoding of the above-described state-of-the-art encoder using 92 bits.

At first, a concept is provided how to encode a plurality of pulse positions of a track of an
35 audio signal in an efficient way. In the following, the concept is extended to allow to encode not only the position of the pulses of a track, but also whether the pulse is positive or negative. Furthermore, the concept is then extended to allow to encode pulse

information for a plurality of tracks in an efficient manner. The concepts are correspondingly applicable on a decoder side.

5 In addition, the embodiments are, moreover, based on the finding, that, if the encoding strategy uses a pre-determined number of bits, such that any configuration with the same number of pulses on each track requires the same number of bits. If the number of bits available is fixed, it is then possible directly to choose how many pulses can be encoded with the given amount of bits thus enabling encoding with a pre-determined quality. Moreover, with this approach, it is not necessary to try different amounts of pulses until the
10 desired bit-rate is achieved, but we can directly choose the right amount of pulses, thereby reducing complexity.

Based on the above assumptions, the plurality of pulse positions of a track of an audio signal frame may be encoded and/or decoded.

15 While the present invention can be employed for encoding or decoding any kind of audio signals, for example, speech signals or music signals, the present invention is particularly useful for encoding or decoding speech signals.

20 In another embodiment, the pulse information decoder is furthermore adapted to decode a plurality of pulse signs using the track positions number, the total pulses number and the state number, wherein each one of the pulse signs indicates a sign of one of the plurality of pulses. The signal decoder may be adapted to decode the encoded audio signal by generating a synthesized audio signal furthermore using the plurality of pulse signs.

25 According to a further embodiment, wherein the one or more tracks may comprise at least a last track and one or more other tracks, the pulse information decoder may be adapted to generate a first substate number and a second substate number from the state number. The pulse information decoder may be configured to decode a first group of the pulse positions based on the first substate number, and the pulse information decoder may furthermore be
30 configured to decode a second group of the pulse positions based on the second substate number. The second group of the pulse positions may only consist of pulse positions indicating track positions of the last track. The first group of the pulse positions only consists of pulse positions indicating track positions of the one or more other tracks.

35 According to another embodiment, the pulse information decoder may be configured to separate the state number into the first substate number and the second substate number by dividing the state number by $f(p_k, N)$ to obtain an integer part and a remainder as a division

result, wherein the integer part is the first substate number and wherein the remainder is the second substate number, wherein p_k indicates for each one of the one or more tracks the number of pulses, and wherein N indicates for each one of the one or more tracks the number of track positions. Here, $f(p_k, N)$ is a function that returns the number of states that
5 can be achieved in a track of length N with p_k pulses.

In another embodiment, the pulse information decoder may be adapted to conduct a test comparing the state number or an updated state number with a threshold value.

10 The pulse information decoder may be adapted to conduct the test by comparing, whether the state number or an updated state number is greater than, greater than or equal to, smaller than, or smaller than or equal to the threshold value, and wherein the analyzing unit is furthermore adapted to update the state number or an updated state number depending on the result of the test.

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In an embodiment, the pulse information decoder may be configured to compare the state number or the updated state number with the threshold value for each track position of one of the plurality of tracks.

20 According to an embodiment, the pulse information decoder may be configured to divide one of the tracks into a first track partition, comprising at least one track position of the plurality of track positions, and into a second track partition, comprising the remaining other track positions of the plurality of track positions. The pulse information decoder may be configured to generate a first substate number and a second substate number based on
25 the state number. Moreover, the pulse information decoder may be configured to decode a first group of pulse positions associated with the first track partition based on the first substate number. Furthermore, the pulse information decoder may be configured to decode a second group of pulse positions associated with the second track partition based on the second substate number.

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According to an embodiment, an apparatus for encoding an audio signal is provided. The apparatus comprises a signal processor adapted to determine a plurality of predictive filter coefficients being associated with the audio signal, for generating a residual signal based on the audio signal and the plurality of predictive filter coefficients. Moreover, the
35 apparatus comprises a pulse information encoder adapted to encode a plurality of pulse positions relating to one or more tracks to encode the audio signal, the one or more tracks being associated with the residual signal. Each one of the tracks has a plurality of track positions and a plurality of pulses. Each one of the pulse positions indicates one of the

track positions of one of the tracks to indicate a position of one of the pulses of the track. The pulse information encoder is configured to encode the plurality of pulse positions by generating a state number, such that the pulse positions can be decoded only based on the state number, a track positions number indicating a total number of the track positions of at least one of the tracks, and a total pulses number indicating a total number of the pulses of at least one of the tracks.

According to another embodiment, the pulse information encoder may be adapted to encode a plurality of pulse signs, wherein each one of the pulse signs indicates a sign of one of the plurality of pulses. The pulse information encoder may furthermore be configured to encode the plurality of pulse signs by generating the state number, such that the pulse signs can be decoded only based on the state number, the track positions number indicating a total number of the track positions of at least one of the tracks, and the total pulses number.

In an embodiment, the pulse information encoder is adapted to add an integer value to an intermediate number for each pulse at a track position for each track position of one of the tracks, to obtain the state number.

According to another embodiment, the pulse information encoder may be configured to divide one of the tracks into a first track partition, comprising at least one track position of the plurality of track positions, and into a second track partition, comprising the remaining other track positions of the plurality of track positions. Moreover, the pulse information encoder may be configured to encode a first substate number associated with the first partition. Furthermore, the pulse information encoder may be configured to encode a second substate number associated with the second partition. Moreover, the pulse information encoder may be configured to combine the first substate number and the second substate number to obtain the state number.

In the following, embodiments of the present invention are described in more detail with respect to the figures, wherein:

Fig. 1 illustrates an apparatus for decoding an encoded audio signal according to an embodiment,

Fig. 2 illustrates an apparatus for encoding an audio signal according to an embodiment,

Fig. 3 illustrates all possible configurations, for a track having two unsigned pulses and three track positions,

5 Fig. 4 illustrates all possible configurations, for a track having one signed pulse and two track positions,

Fig. 5 illustrates all possible configurations, for a track having two signed pulses and two track positions,

10 Fig. 6 is a flow chart illustrating an embodiment, depicting the processing steps conducted by a pulse information decoder according to an embodiment, and

Fig. 7 is a flow chart illustrating an embodiment, the flow chart depicting the processing steps conducted by a pulse information encoder according to an
15 embodiment.

Fig. 1 illustrates an apparatus for decoding an encoded audio signal, wherein one or more tracks are associated with the encoded audio signal, each one of the tracks having a plurality of track positions and a plurality of pulses.

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The apparatus comprises a pulse information decoder 110 and a signal decoder 120. The pulse information decoder 110 is adapted to decode a plurality of pulse positions. Each one of the pulse positions indicates one of the track positions of one of the tracks to indicate a position of one of the pulses of the track.

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The pulse information decoder 110 is configured to decode the plurality of pulse positions by using a track positions number indicating a total number of the track positions of at least one of the tracks, a total pulses number indicating a total number of the pulses of at least one of the tracks, and one state number.

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The signal decoder 120 is adapted to decode the encoded audio signal by generating a synthesized audio signal using the plurality of pulse positions and a plurality of predictive filter coefficients being associated with the encoded audio signal.

35 The state number is a number that may have been encoded by an encoder according the embodiments that will be described below. The state number, e.g. comprises information about a plurality of pulse positions in a compact representation, e.g. a representation that

requires few bits, and that can be decoded, when the information about the track positions number and the total pulses number is available at the decoder.

5 In an embodiment, the track positions number and/or the total pulses number of one or of each track of the audio signal may be available at the decoder, because the track positions number and/or the total pulses number is a static value that doesn't change and is known by the receiver. For example, the track positions number may always be 16 for each track and the total pulses number may always be 4.

10 In another embodiment, the track positions number and/or the total pulses number of one or of each track of the audio signal may be explicitly transmitted to the apparatus for decoding, e.g. by the apparatus for encoding.

15 In a further embodiment, the decoder may determine the track positions number and/or the total pulses number of one or of each track of the audio signal by analyzing other parameters that do not explicitly state the track positions number and/or the total pulses number, but from which the track positions number and/or the total pulses number can be derived.

20 In other embodiments, the decoder may analyze other data available to derive the track positions number and/or the total pulses number of one or of each track of the audio signal.

In further embodiment, the pulse information decoder may be adapted to also decode, whether a pulse is a positive pulse or a negative pulse.

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In another embodiment, the pulse information decoder may furthermore be adapted to decode pulse information which comprises information about pulses for a plurality of tracks. Pulse information may, for example, be information about the position of the pulses in a track and/or information whether a pulse is a positive pulse or a negative pulse.

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Fig. 2 illustrates an apparatus for encoding an audio signal, comprising a signal processor 210 and a pulse information encoder 220.

35 The signal processor 210 is adapted to determine a plurality of predictive filter coefficients being associated with the audio signal, for generating a residual signal based on the audio signal and the plurality of predictive filter coefficients.

The pulse information encoder 220 is adapted to encode a plurality of pulse positions relating to one or more tracks to encode the audio signal. The one or more tracks are associated with the residual signal generated by the signal processor 210. Each one of the tracks has a plurality of track positions and a plurality of pulses. Moreover, each one of the pulse positions indicates one of the track positions of one of the tracks to indicate a position of one of the pulses of the track.

The pulse information encoder 220 is configured to encode the plurality of pulse positions by generating a state number, such that the pulse positions can be decoded only based on the state number, a track positions number indicating a total number of the track positions of at least one of the tracks, and a total pulses number indicating a total number of the pulses of at least one of the tracks.

In the following, the basic concepts of embodiments of the present invention relating to the encoding of the pulse positions and possibly pulse sign (positive pulse or negative pulse) by generating a state number are presented.

The encoding principles of embodiments of the present invention are based on the finding that if a state enumeration of all possible configurations of k pulses in a track with n track positions is considered, it is sufficient to encode the actual state of the pulses of a track. Encoding such a state by as little bits as possible provides the desirable compact encoding. By this, a concept of state enumeration is presented, wherein each constellation of pulse positions, and possibly also pulse signs, represents one state and each state is uniquely enumerated.

Fig. 3 illustrates this for a simple case, where all possible configurations are depicted, when a track having two pulses and three track positions is considered. Two pulses may be located at the same track position. In the example of Fig. 3, the sign of the pulses (e.g. whether the pulse is positive or negative) is not considered, e.g. in such an example, all pulses may, for example, be considered to be positive.

In Fig. 3, all possible states for two undirected pulses located in a track with three track positions (in Fig. 3: track positions 1, 2 and 3) are illustrated. There are only six different possible states (in Fig. 3 enumerated from 0 to 5) that describe, how the pulses may be distributed in the track. By this, it is sufficient to use a state number in the range 0 to 5 to describe the actual configuration present. For example, if the state number in the example of Fig. 3 has the value (4), and if the decoder is aware of the encoding scheme, the decoder can conclude that state number = 4 means, that the track has one pulse at track position 0

and another pulse at track position 2. By this, in the example of Fig. 3, three bits are sufficient to encode the state number to identify one of the six different states of the example of Fig. 3.

- 5 Fig. 4 illustrates a case depicting all possible states for one directed pulse located in a track with two track positions (in Fig. 4: track positions 1 and 2). In Fig. 4, the sign of the pulses (e.g. whether the pulse is positive or negative) is considered. There are four different possible states (in Fig. 4 enumerated from 0 to 3) that describe, how the pulse may be distributed in track and also its sign (positive or negative). It is sufficient to use a state number in the range 0 to 3 to describe the actual configuration present. For example, if the state number in the example of Fig. 4 has the value (2), and if the decoder is aware of the encoding scheme, the decoder can conclude that state number = 2 means, that the track has one pulse at track position 1, and that the pulse is a positive pulse.
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- 15 Fig. 5 illustrates a still further case, where all possible configurations are depicted, when a track having two pulses and two track positions is considered. Pulses may be located at the same track position. In the example shown in Fig. 5, the sign of the pulses (e.g. whether the pulse is positive or negative) is considered. It is assumed that pulses at the same track position have the same sign (e.g. the tracks at the same track position are either all positive or are all negative).
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In Fig. 5, all possible states for two signed pulses (e.g. pulses that are either positive or negative) located in a track with two track positions (in Fig. 5: track positions 1 and 2) are illustrated. There are only eight different possible states (in Fig. 5 enumerated from 0 to 7) that describe, how the pulses may be distributed in the track. By this, it is sufficient to use a state number in the range 0 to 7 to describe the actual configuration. For example, if the state number in the example of Fig. 5 has the value (3), and if the decoder is aware of the encoding scheme, the decoder can conclude that state number = 3 means, that the track has one pulse at track position 0 which is positive and another pulse at track position 1 which is negative. By this, in the example of Fig. 5, three bits are sufficient to encode the state number to identify one of the eight different states of the example of Fig. 5.

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In ACELP, the residual signal may be encoded by a fixed number of signed pulses. As described above, the pulses may, for example, be distributed in four interlacing tracks, such that track 0 contains positions $\text{mod}(n,4)=0$, track=1 contains positions $\text{mod}(n,4)=1$, and so on. Each track may have a predefined number of signed unit pulses, which may overlap, but when they overlap, the pulses have the same sign.

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By encoding pulses, a mapping from the pulse positions and their signs, into a representation that uses the smallest possible amount of bits should be achieved. In addition, the pulse coding should have a bit consumption that is fixed, that is, any pulse constellation has the same number of bits.

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Each track is first independently encoded and then the states of each track are combined to one number, which represents the state of the whole subframe. This approach gives the mathematically optimal bit-consumption, given that all states have equal probability, and the bit consumption is fixed.

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The concept of state enumeration may also be explained using a compact representation of the different state constellations:

Let the residual signal, which we want to code, be x_n . Assuming that four interleaved tracks, e.g. of an algebraic codebook, are considered, then the first track has samples $x_0, x_4, x_8 \dots x_{N-4}$, the second track has samples $x_1, x_5, x_9 \dots x_{N-3}$, etc. Suppose, the first track is quantized with one signed unit pulse and that $T=8$, whereby the length of the track is 2 ($T = \text{length (samples) of the residual signal to be encoded}$). If $T=8$, and if 4 tracks are used to encode the residual signal, each one of the 4 tracks has 2 track positions. For example, the first track may be considered, that has two track positions x_0 and x_4 . The pulse of the first track can then appear in any of the following constellations:

x_0	+1	-1	0	0
x_4	0	0	+1	-1

There are four different states for this configuration.

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Similarly, if there would be two pulses in the first track, the first track having two track positions x_0 and x_4 , the pulses could then be assigned in the following constellations:

x_0	+2	-2	+1	+1	-1	-1	0	0
x_4	0	0	+1	-1	+1	-1	+2	-2

30 Thereby this configuration has 8 states.

If the length of the residual signal is extended to $T=12$, then each of the 4 tracks has 3 track positions. The first track gets one more sample and has now track positions x_0 , x_4 and x_8 , such that we have:

x_0, x_4	2 pulses 8 states	1 pulse 4 states	1 pulse 4 states	0 pulses 1 state	0 pulses 1 state
x_8	0	+1	-1	+2	-2

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The above table means that there are 8 different states for x_0 and x_4 , if $x_8 = 0$ (x_8 has no pulse); 4 different states for x_0 and x_4 , if $x_8 = 1$ (x_8 has a positive pulse); 4 different states for x_0 and x_4 , if $x_8 = -1$ (x_8 has a negative pulse); 1 state for x_0 and x_4 , if $x_8 = 2$ (x_8 has two positive pulses); and 1 state for x_0 and x_4 , if $x_8 = -2$ (x_8 has two negative pulses).

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Here, the number of states for the first row has been obtained from the two previous tables. By addition of the number of states in the first row, we see that this configuration has 18 states.

15 In the $T=12$ example, 5 bits are sufficient to encode all the 18 different possible states. The encoder then, for example, selects the state number from the range $[0, \dots, 17]$ to specify one of the 18 configurations. If the decoder is aware of the encoding scheme, e.g. if it is aware, which state number represents which configuration, it can decode the pulse positions and pulse signs for a track.

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Below, suitable encoding methods and corresponding decoding methods according to embodiments will be provided. According to embodiments, an apparatus for encoding is provided which is configured to execute one of the encoding methods presented below. Moreover, according to further embodiments, an apparatus for decoding is provided which

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In embodiments, to generate the state number or to decode the state number, the number of possible configurations for N track positions having p pulses may be calculated.

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Pulses may be signed, and a recursive formula may be employed, which calculates the number of states $f(p, N)$ for a track having N track positions and p signed pulses (the pulses may be positive or negative, but pulses at the same track position have the same sign), wherein the recursive formula $f(p, N)$ is defined by:

Formula 1:

$$f(p, N) = \sum_{k=0}^p f(k, N-1) f(p-k, 1)$$

5 The initial conditions are

$$f(p, 1) = \begin{cases} 2 & \text{for } p \geq 1 \\ 1 & \text{for } p = 0 \end{cases} \quad \text{and} \quad f(p, 0) = 0$$

since a single position with one or more pulses requires one bit (two states) for the sign.

10 The recursion formula is for summation of all different constellations.

Namely, given p pulses, the current position can have $q_N = 0$ to p pulses, whereby the remaining $N-1$ positions have $p - q_N$ pulses. The number of states at the current position and the remaining $N-1$ positions are multiplied to obtain the number of states with these combinations of pulses and combinations are summed to obtain the total number of states.

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In embodiments, the recursive function may be calculated by an iterative algorithm, wherein the recursion is replaced by iteration.

20 As the evaluation of $f(p, N)$ is numerically relatively complex for real time applications, according to some embodiments, a table look-up may be employed to calculate $f(p, N)$. According to some embodiments, the table may have been computed off-line.

In the following, further concepts are provided for encoding and decoding the state number:

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Let $f(p, N)$ denote the number of possible configurations for a track having N track positions and p signed pulses.

30 The pulse information encoder can now analyze the track: If the first position in the track does not have a pulse, then the remaining $N-1$ positions have p signed pulses, and to describe this constellation, we need only $f(p, N-1)$ states.

Otherwise, if the first position has one or more pulses, the pulse information encoder can define that the overall state is greater than $f(p, N-1)$.

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Then, at the pulse information decoder, the pulse information decoder, can, for example, start with the last position and compare the state with a threshold value, e.g. with $f(p, N-1)$. If it is greater, then the pulse information decoder can determine that the last position has at least one pulse. The pulse information decoder can then update the state to
 5 obtain an updated state number by subtracting $f(p, N-1)$ from the state and reduce the number of remaining pulses by one.

Otherwise, if there is no pulse at the last position, the pulse information decoder can reduce the number of remaining positions by one. Repeating this procedure until there are no
 10 pulses left, would provide the unsigned positions of pulses.

To also take the signs of the pulses into account, the pulse information encoder may encode the pulses in the lowest bit of the state. In an alternative embodiment, the pulse information encoder may encode the sign in the highest remaining bit of the state. It is
 15 preferred, however, to encode the pulse sign in the lowest bit, as this is easier to handle with respect to integer computations.

If, in the pulse information decoder, the first pulse of a given position is found, the sign of the pulse is determined by the last bit. Then, the remaining state is shifted one step right to
 20 obtain an updated state number.

In an embodiment, a pulse information decoder is configured to apply the following decoding algorithm. In this decoding algorithm, in a step-by-step approach, for each track position, e.g. one after the other, the state number or the updated state number is compared
 25 with a threshold value, e.g. with $f(p, k-1)$.

According to an embodiment, a pulse information decoder algorithm is provided:

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  30   For each position in track,  $k=N$  to 1
        While state  $s \geq f(p, k-1)$ 
            Put a pulse at  $k$ 
            Set  $s := s - f(p, k-1)$ 
            If this is the first pulse at  $k$ 
                If lowest bit of  $s$  is set, set sign to minus
                Otherwise, set sign to plus
            Shift state right one step  $s := s/2$ 
            Reduce the number of remaining pulses  $p := p-1$ 
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Regarding the pulse information, according to an embodiment, a pulse information encoder is configured to apply the following encoding algorithm. The pulse information encoder does the same steps as the pulse information decoder, but in reverse order.

- 5 According to an embodiment, a pulse information encoder algorithm is provided:

Set number of found pulses to zero, $p:=0$ and state to zero, $s:=0$

For each position in track, $k=1$ to N

For each pulse at this position

- 10 If the current pulse is the last one on this position

Shift state left one step $s := s * 2$

If sign is minus, set the lowest bit to one, $s := s + 1$

Otherwise set the lowest bit to zero (i.e. do nothing)

Update the state $s := s + f(p, k-1)$

- 15 Increase the number of found pulses $p:=p+1$

- 20 Encoding the state number by using this algorithm, the pulse information encoder adds an integer value to an intermediate number (e.g. an intermediate state number), e.g. the state number before the algorithm is completed, for each pulse at a track position for each track position of one of the tracks, to obtain (the value of) the state number.

- 25 The approach for encoding and decoding of pulse information, e.g. pulse positions and pulse signs, may be referred to as “step-by-step encoding” and “step-by-step decoding”, as the track positions are considered by the encoding and decoding methods one after the other, step-by-step.

Fig. 6 is a flow chart illustrating an embodiment, depicting the processing steps conducted by a pulse information decoder according to an embodiment.

- 30 In step 610 the current track position k is set to N . Here, N represents the number of track positions of a track, wherein the track positions are enumerated from 1 to N .

- 35 In step 620, it is tested, whether k is greater than or equal to 1, i.e. whether track positions remain that have not been considered. If k is not greater than or equal to 1, all track positions have been considered and the process ends.

Otherwise it is tested in step 630, whether the state is greater than or equal to $f(p, k-1)$. If this is the case, at least one pulse is present at position k . If this is not the case, no (further)

pulse is present at track position k and the process continues at 640, where k is reduced by 1, such that the next track position will be considered.

If, however, the state is greater than or equal to $f(p, k-1)$, the process continues with step 5 642, a pulse is put at track position k , and then, in step 644, the state is updated by reducing the state by $f(p, k-1)$. Then, in step 650, it is tested, whether the current pulse is the first discovered pulse at track position k . If this is not the case, the number of remaining pulses is reduced by 1 in step 680, and the process continues in step 630.

10 If, however this is the first discovered pulse at track position k , the process continues with step 660, where it is tested, whether the lowest bit of s is set. If this is the case, the sign of the pulses at this track position is set to minus (step 662), otherwise, the sign of the pulses at this track position is set to plus (step 664). In both cases, the state is then shifted one step right in step 670 ($s := s/2$). Then, also, the number of remaining pulses is reduced by one 15 (step 680) and the process continues at step 630.

Fig. 7 is a flow chart illustrating an embodiment, the flow chart depicting the processing steps conducted by a pulse information encoder according to an embodiment.

20 In step 710, the number of found pulses p is set to 0, the state s is set to 0 and the considered track position k is set to 1.

In step 720, it is tested, whether k is smaller than or equal to N , i.e. whether track positions remain that have not been considered (here, N means: number of track positions of a 25 track). If k is not smaller than or equal to N , all track positions have been considered and the process ends.

Otherwise it is tested in step 730, whether at least one pulse is present at position k . If this is not the case, the process continues at 740, where k is increased by 1, such that the next 30 track position will be considered.

However, if at least one pulse is present at track position k , it is tested in step 750, whether the currently considered pulse is the last pulse at track position k . If this is not the case, then, in step 770, the state s is updated by adding $f(p, k-1)$ to the state s , the number of 35 found pulses p is increased by 1, and the process continues with step 780.

If the currently considered pulse is the last pulse at track position k , then after step 750, the process continues with step 755 and the state is shifted one step left ($s := s * 2$). Then, it is

tested in step 760, whether the sign of the pulse is minus. If this is the case, the lowest bit of s is set to 1 (step 762); otherwise, the lowest bit of s is set to 0 (or nothing is done) (step 764). Then, in both cases, step 770 is conducted, where the state s is updated by adding $f(p, k-1)$ to the state s , the number of found pulses p is increased by 1, and the process
5 continues with step 780.

In step 780, it is tested, whether there is another pulse at position k . If this is the case, the process continues with step 750; otherwise, the process continues with step 740.

10 In the following, a concept is provided for generating a joint state number encoding the state of a plurality of tracks.

Unfortunately, in many cases the range of possible states of a single track is not a multiple of 2 and the binary representation of each state is thus inefficient. For example, if the
15 number of possible states is 5, then we need 3 bits to represent it with a binary number. However, if we have four tracks, each with 5 states, then we have $5 \times 5 \times 5 \times 5 = 625$ states for the whole sub-frame which can be represented by 10 bits (instead of $4 \times 3 = 12$ bits). This corresponds to 2.5 bits per track instead of 3 and we thus obtain a 0.5 bit saving per track or equivalently, 2 bits per subframe (20% of total bit consumption). It is therefore
20 important to combine the states of each track to one joint state, since by this, the inefficiency of the binary representation can be reduced. Note that the same approach could be used to any numbers that are transmitted. For example, since each sub-frame may have a state representing the positions of the pulses, and each frame may, for example, have four sub-frames, these states could be combined to one joint state number.

25 Given that a sub-frame has, for example, 4 tracks, the bit consumption can be reduced to improve efficiency by jointly encoding the states of each track. For example, given that each track has p_k pulses and each track is of length N , e.g. has N track positions, then the state of each track is in the range 0 to $f(p_k, N) - 1$. The states of each track s_k can then be
30 combined to a joint state s of the subframe with the formula (assuming we have 4 tracks per sub-frame)

Formula 2:

35
$$s = \llbracket s_0 f(p_0, N) + s_1 \rrbracket f(p_1, N) + s_2 \rrbracket f(p_2, N) + s_3.$$

The states of each track can then be determined in the decoder by dividing the joint state by $f(p_k, N)$, whereby the remainder is the state of the last track and the integer part is the joint state of the remaining tracks. If the number of tracks is other than 4, we can readily add or reduce the number of terms in the above equation appropriately.

5

Note, that when the number of pulses per track is large, then the number of possible states becomes large. For example, with 6 pulses per track with four tracks and a track length $N=16$, then the state is an 83-bit number, which exceeds the maximum length of binary numbers on regular CPUs. It follows that some extra steps have to be made to evaluate the above formula using standard methods with very long integers.

10

Observe also that this approach is equal to arithmetic coding of the track states, when the state probabilities are assumed to be equal.

15

Above, a step-by-step approach has been presented for encoding and decoding pulses information of a track, e.g. the positions, and possibly signs, of pulses of a track. Other embodiments provide another approach, which will be referred to as “split-and-conquer” approach.

20

A pulse information encoder being configured to apply the split-and-conquer approach, divides a track into two track partitions x_1 and x_2 , which could be considered as two vectors, wherein $x = [x_1 \ x_2]$. The basic idea is to encode both vectors x_1 and x_2 separately, and then to combine the two with the formula

25

Formula 3:

$$s(x) = s(x_1) + f(p_1, N_1)s(x_2) + \sum_{k=0}^{p_1-1} f(k, N_1)f(p-k, N-N_1)$$

30

In the above equation, it should be noted that $s(x_1)$ and $s(x_2)$ are the states of vectors x_1 and x_2 , when the number of pulses are already known, that is, when the vectors have, respectively, p_1 and $p_2 = p - p_1$ pulses. To take into account all the states that have 0 to p_1-1 pulses in vector x_1 , we have to add the summation term in the above equation.

35

The above algorithm/formula can be applied to encode the pulses of interlaced tracks by applying the following two pre-processing steps. Firstly, let the vectors $x_{track \ k}$ consists of all samples on track k and merge these vectors by defining $x = [x_{track \ 1}, x_{track \ 2}, x_{track \ 3},$

$x_{track\ 4}]$. Observe that this is merely a re-ordering of samples such that all samples from track 1 are placed in the first group and so on.

Secondly, note that the number of pulses per track is usually a fixed number. It follows that if track 1 always has p_1 pulses, then the number of states on track 1 is $f(k, N_1) = 0$ for all values $k \neq p_1$. This is just another way of saying that there are no states for track 1 which do not have p_1 pulses. Formally, we can then define the number-of-states formula as:

Formula 4:

10

For a complete track $x_{track\ k}$ with p_k pulses, the number of states is ($N = N_{track\ k}$)

$$f(p, N) = \begin{cases} f(p, N) & \text{for } p = p_k \\ 0 & \text{for } p \neq p_k \end{cases}$$

15

Otherwise, for $N > 1$

$$f(p, N) = \sum_{k=0}^p f(k, N_1) f(p-k, N-N_1)$$

And for $N=1$:

20

$$f(p, 1) = \begin{cases} 2 & \text{for } p \geq 1 \\ 1 & \text{for } p = 0 \end{cases}$$

By the re-ordering of samples and using the above definition for the number of states (Formula 4), we can calculate the joint state of all tracks by Formula 3. Note that since the number of states contains mostly zeros, the summation in Formula 3 is zero, when merging the state of tracks. Therefore merging two tracks is identical to Formula 2. Similarly, we can readily show that the merging all four tracks (or five) also gives identical results with both approaches.

30 According to an embodiment, re-ordering can be used as a pre-processing step to the encoder. In another embodiment, the re-ordering can be integrated into the encoder. Similarly, according to an embodiment, re-ordering can be used as a post-processing step to the decoder. In another embodiment, the re-ordering can be integrated into the decoder.

If the number of pulses on a track is not fixed, we can readily modify the number of states formula appropriately, and still use the same encoding algorithm.

Observe that the approach presented in the section “Combining track data” and the above method give equal results if the order of merging tracks is appropriately chosen. Likewise, also the step-by-step and divide-and-conquer approaches give equal results. We can therefore independently choose which approach to use in the decoder and encoder, according to which is more practical to implement or which approach best fits the computational constraints of the platform.

According to an embodiment, a pulse information encoder algorithm is provided, that can be described in pseudo-code by

```
function state = encode(x)
```

```

15   1. if length of x is 1
      a. if x has no pulses
         i. state = 0
         ii. return
      b. else (x has at least one pulse)
20         i. if the pulse(s) in x is positive
            • state = 0
            • return
         ii. else (pulse(s) in x is negative)
            • state = 1
25            • return
         iii. end
      c. end
      2. else (that is, when length of x is > 1)
         a. split x into two vectors x1 and x2 of length N1 and N2 respectively
30         b. determine state of vector x1 by s1 = encode(x1)
         c. determine state of vector x2 by s2 = encode(x2)
         d. let p be the number of pulses in x and p1 the number of pulses in x1
         e. set n0 = 0
         f. for k from 0 to p1-1
35             i. set n0 := n0 + f(k,N1)*f(p-k,N2)
         g. end
         h. calculate state as s := s1 + f(p1,N1)*s2 + n0
         i. return
      3. end

```

Employing such an encoding algorithm, according to an embodiment, the pulse information encoder is configured to divide one of the tracks into a first track partition and into a second track partition. The pulse information encoder is configured to encode a first

substate number associated with the first partition. Furthermore, the pulse information encoder is configured to encode a second substate number associated with the second partition. Moreover, the pulse information encoder is configured to combine the first substate number and the second substate number to obtain the state number.

5

Similarly, according to an embodiment, a the pulse information decoder algorithm is provided that can be described in pseudo-code by:

```

function x = decode(s, p, N)
10   1. if number of pulses p is 0
      a. return vector x full of zeros
      2. else
          a. if len is 1
              i. if s == 0
15                 1. Vector x has p positive pulses at its first position
              ii. else
                  1. Vector x has p negative pulses at its first position
              iii. end
          b. else
20             i. Choose partition lengths N1 and N2
             ii. Set n0 := 0 and p1 := 0
             iii. While n0 + f(p1,N1)*f(p-p1) < s
                  1. set p1 := p1+1
                  2. set n0 := n0 + f(p1,N1)*f(p-p1)
25             iv. end
             v. set s := s - n0 and p2 := p - p1
             vi. set s1 := s / f(p1,N1) and the remainder into s2
             vii. decode first partition x1 = decode(s1, p1, N1)
             viii. decode second partition x2 = decode(s2, p2, N2)
30             ix. merge partitions x1 and x2 in to x
          c. end
      3. end

```

In an embodiment realizing the split-and-conquer approach, a pulse information decoder is
35 configured to generate a first substate number and a second substate number based on the state number. The pulse information decoder is configured to decode a first group of pulse positions of a first partition of one of the tracks based on the first substate number. Moreover, the pulse information decoder is configured to decode a second group of pulse positions of a second partition of the one of the tracks based on the second substate
40 number.

Although some aspects have been described in the context of an apparatus, it is clear that these aspects also represent a description of the corresponding method, where a block or

device corresponds to a method step or a feature of a method step. Analogously, aspects described in the context of a method step also represent a description of a corresponding block or item or feature of a corresponding apparatus.

- 5 Depending on certain implementation requirements, embodiments of the invention can be implemented in hardware or in software. The implementation can be performed using a digital storage medium, for example a floppy disk, a DVD, a CD, a ROM, a PROM, an EPROM, an EEPROM or a FLASH memory, having electronically readable control signals stored thereon, which cooperate (or are capable of cooperating) with a
10 programmable computer system such that the respective method is performed.

Some embodiments according to the invention comprise a data carrier having electronically readable control signals, which are capable of cooperating with a programmable computer system, such that one of the methods described herein is
15 performed.

Generally, embodiments of the present invention can be implemented as a computer program product with a program code, the program code being operative for performing one of the methods when the computer program product runs on a computer. The program
20 code may for example be stored on a machine readable carrier.

Other embodiments comprise the computer program for performing one of the methods described herein, stored on a machine readable carrier or a non-transitory storage medium.

- 25 In other words, an embodiment of the inventive method is, therefore, a computer program having a program code for performing one of the methods described herein, when the computer program runs on a computer.

A further embodiment of the inventive methods is, therefore, a data carrier (or a digital storage medium, or a computer-readable medium) comprising, recorded thereon, the
30 computer program for performing one of the methods described herein.

A further embodiment of the inventive method is, therefore, a data stream or a sequence of signals representing the computer program for performing one of the methods described
35 herein. The data stream or the sequence of signals may for example be configured to be transferred via a data communication connection, for example via the Internet or over a radio channel.

A further embodiment comprises a processing means, for example a computer, or a programmable logic device, configured to or adapted to perform one of the methods described herein.

- 5 A further embodiment comprises a computer having installed thereon the computer program for performing one of the methods described herein.

In some embodiments, a programmable logic device (for example a field programmable gate array) may be used to perform some or all of the functionalities of the methods
10 described herein. In some embodiments, a field programmable gate array may cooperate with a microprocessor in order to perform one of the methods described herein. Generally, the methods are preferably performed by any hardware apparatus.

The above described embodiments are merely illustrative for the principles of the present
15 invention. It is understood that modifications and variations of the arrangements and the details described herein will be apparent to others skilled in the art. It is the intent, therefore, to be limited only by the scope of the impending patent claims and not by the specific details presented by way of description and explanation of the embodiments herein.

20

Claims

1. An apparatus for decoding an encoded audio signal, wherein one or more tracks are associated with the encoded audio signal, each one of the tracks having a plurality of track positions and a plurality of pulses, wherein the apparatus comprises:

5

10

a pulse information decoder (110) for decoding a plurality of pulse positions, wherein each one of the pulse positions indicates one of the track positions of one of the tracks to indicate a position of one of the pulses of the track, and wherein the pulse information decoder (110) is configured to decode the plurality of pulse positions by using a track positions number indicating a total number of the track positions of at least one of the tracks, a total pulses number indicating a total number of the pulses of at least one of the tracks, and one state number; and

15

a signal decoder (120) for decoding the encoded audio signal by generating a synthesized audio signal using the plurality of pulse positions and a plurality of predictive filter coefficients being associated with the encoded audio signal.

2. An apparatus according to claim 1,

20

wherein the pulse information decoder (110) is furthermore adapted to decode a plurality of pulse signs using the track positions number, the total pulses number and the state number, wherein each one of the pulse signs indicates a sign of one of the plurality of pulses, and

25

wherein the signal decoder (120) is adapted to decode the encoded audio signal by generating a synthesized audio signal furthermore using the plurality of pulse signs.

3. An apparatus according to claim 1 or 2, wherein the one or more tracks comprise at least a last track and one or more other tracks, and

30

wherein the pulse information decoder (110) is adapted to generate a first substate number and a second substate number from the state number,

35

wherein the pulse information decoder (110) is configured to decode a first group of the pulse positions based on the first substate number, and

wherein the pulse information decoder (110) is configured to decode a second group of the pulse positions based on the second substate number,

5 wherein the second group of the pulse positions only consists of pulse positions indicating track positions of the last track, and

wherein the first group of the pulse positions only consists of pulse positions indicating track positions of the one or more other tracks.

10 4. An apparatus according to claim 3, wherein the pulse information decoder is configured to generate the first substate number and the second substate number by dividing the state number by $f(p_k, N)$ to obtain an integer part and a remainder as a division result, wherein the integer part is the first substate number and wherein the remainder is the second substate number, wherein p_k indicates for each one of the
15 one or more tracks the number of pulses, and wherein N indicates for each one of the one or more tracks the number of track positions.

5. An apparatus according to one of the preceding claims, wherein the pulse information decoder (110) is adapted to conduct a test comparing the state number
20 or an updated state number with a threshold value.

6. An apparatus according to claim 5, wherein the pulse information decoder (110) is adapted to conduct the test by comparing, whether the state number or an updated state number is greater than, greater than or equal to, smaller than, or smaller than
25 or equal to the threshold value, and wherein the pulse information decoder (110) is furthermore adapted to update the state number or an updated state number depending on the result of the test.

7. An apparatus according to claim 6, wherein the pulse information decoder (110) is
30 configured to compare the state number or the updated state number with the threshold value for each track position of one of the plurality of tracks.

8. An apparatus according to one of claims 1 to 3,

35 wherein the pulse information decoder (110) is configured to divide one of the tracks into a first track partition, comprising at least two track positions of the plurality of track positions, and into a second track partition, comprising at least two other track positions of the plurality of track positions,

wherein the pulse information decoder (110) is configured to generate a first substate number and a second substate number based on the state number,

5 wherein the pulse information decoder (110) is configured to decode a first group of pulse positions associated with the first track partition based on the first substate number, and

10 wherein the pulse information decoder (110) is configured to decode a second group of pulse positions associated with the second track partition based on the second substate number.

9. An apparatus for encoding an audio signal, comprising:

15 a signal processor (210) for determining a plurality of predictive filter coefficients being associated with the audio signal, for generating a residual signal based on the audio signal and the plurality of predictive filter coefficients; and

20 a pulse information encoder (220) for encoding a plurality of pulse positions relating to one or more tracks, to encode the audio signal, the one or more tracks being associated with the residual signal, each one of the tracks having a plurality of track positions and a plurality of pulses, wherein each one of the pulse positions indicates one of the track positions of one of the tracks to indicate a position of one of the pulses of the track, wherein the pulse information encoder (220) is
25 configured to encode the plurality of pulse positions by generating a state number, such that the pulse positions can be decoded only based on the state number, a track positions number indicating a total number of the track positions of at least one of the tracks, and a total pulses number indicating a total number of the pulses of at least one of the tracks.

30

10. An apparatus for encoding according to claim 9, wherein the pulse information encoder (220) is adapted to encode a plurality of pulse signs, wherein each one of the pulse signs indicates a sign of one of the plurality of pulses, wherein the pulse information encoder (220) is configured to encode the plurality of pulse signs by
35 generating the state number, such that the pulse signs can be decoded only based on the state number, the track positions number indicating a total number of the track positions of at least one of the tracks, and the total pulses number.

11. An apparatus according to claim 9 or 10, wherein the pulse information encoder (220) is configured to add an integer value to an intermediate number for each pulse at a track position for each track position of one of the tracks, to obtain the state number.

5

12. An apparatus according to claim 9 or 10,

10

wherein the pulse information encoder (220) is configured to divide one of the tracks into a first track partition, comprising at least two track positions of the plurality of track positions, and into a second track partition, comprising at least two other track positions of the plurality of track positions,

15

wherein the pulse information encoder (220) is configured to encode a first substate number associated with the first partition,

wherein the pulse information encoder (220) is configured to encode a second substate number associated with the second partition, and

20

wherein the pulse information encoder (220) is configured to combine the first substate number and the second substate number to obtain the state number.

13. Method for decoding an encoded audio signal, wherein one or more tracks are associated with the encoded audio signal, each one of the tracks having a plurality of track positions and a plurality of pulses, wherein the method comprises:

25

decoding a plurality of pulse positions, wherein each one of the pulse positions indicates one of the track positions of one of the tracks to indicate a position of one of the pulses of the track, and wherein the plurality of pulse positions are decoded by using a track positions number indicating a total number of the track positions of at least one of the tracks, a total pulses number indicating a total number of the pulses of at least one of the tracks, and one state number; and

30

decoding the encoded audio signal by generating a synthesized audio signal using the plurality of pulse positions and a plurality of predictive filter coefficients being associated with the encoded audio signal.

35

14. Method for encoding an audio signal, comprising:

determining a plurality of predictive filter coefficients being associated with the audio signal, for generating a residual signal based on the audio signal and the plurality of predictive filter coefficients; and

- 5 encoding a plurality of pulse positions relating to one or more tracks, to encode the audio signal, the one or more tracks being associated with the residual signal, each one of the tracks having a plurality of track positions and a plurality of pulses, wherein each one of the pulse positions indicates one of the track positions of one of the tracks to indicate a position of one of the pulses of the track, wherein the
- 10 plurality of pulse positions are encoded by generating a state number, such that the pulse positions can be decoded only based on the state number, a track positions number indicating a total number of the track positions of at least one of the tracks, and a total pulses number indicating a total number of the pulses of at least one of the tracks.
- 15
15. A computer program implementing the method of claim 13 or 14 when being executed on a computer or signal processor.