

ABSTRACT

A prework manipulation or a post-work manipulation for a crane is facilitated. A controller (6) executes a boom raising control in response to a first raising manipulation under a condition that a start mode is set (S201 to S209). The controller (6) executes a jib swing out control in response to a second raising manipulation. The boom raising control includes making the controller (6) cause a second winch to wind up a second rope when a detection value from a jib tension force detector falls below a permissible range (S304). The jib swing out control includes making the controller (6) cause the second winch to wind up the second rope.