FRACTURING AND GRAVEL PACKING TOOL WITH MULTI MOVEMENT WASH PIPE VALVE

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FIELD OF THE INVENTION

[0001] The field of this invention relates to gravel packing and fracturing tools used to treat formations and to deposit gravel outside of screens for improved production flow through the screens.

BACKGROUND OF THE INVENTION

[0002] Completions whether in open or cased hole can involve isolation of the producing zone or zones and installing an assembly of screens suspended by an isolation packer. An inner string typically has a crossover tool that is shifted with respect to the packer to allow fracturing fluid pumped down the tubing string to get into the formation with no return path to the surface so that the treating fluid can go into the formation and fracture it or otherwise treat it. This closing of the return path can be done at the crossover or at the surface while leaving the crossover in the circulate position and just closing the annulus at the surface. The crossover tool also can be configured to allow gravel slurry to be pumped down the tubing to exit laterally below the set packer and pack the annular space outside the screens. The carrier fluid can go through the screens and into a wash pipe that is in fluid communication with the crossover tool so that the returning fluid crosses over through the packer into the upper annulus above the set packer.

[0003] Typically these assemblies have a flapper valve, ball valve, ball on seat or other valve device in the wash pipe to prevent fluid loss into the formation during certain operations such as reversing out excess gravel from the tubing string after the gravel packing operation is completed. Some schematic representations of known gravel packing systems are shown schematically in USP 7,128,151 and in more functional detail in USP 6,702,020. Other features of gravel packing systems are found in USP 6,230.801. Other patents and applications focus on the design of the crossover housing where there are erosion issues from moving slurry through ports or against housing walls on the way out such as shown in US Applications 11/586,235 filed October 25, 2006 and application 12/250,065 filed October 13. 2008. Locator tools that use displacement of fluid as a time delay to reduce applied force to a bottom

hole assembly before release to minimize a slingshot effect upon release are disclosed in US Publication 2006/0225878. Also relevant to time delays for ejecting balls off seats to reduce formation shock is USP 6,079,496. Crossover tools that allow a positive pressure to be put on the formation above hydrostatic are shown in US Publication 2002/0195253 Other gravel packing assemblies are found in USP 5,865,251; 6,053,246 and 5,609,204.

[0004] These known systems have design features that are addressed by the present invention. One issue is well swabbing when picking up the inner string. Swabbing is the condition of reducing formation pressure when lifting a tool assembly where other fluid can't get into the space opened up when the string is picked up. As a result the formation experiences a drop in pressure. In the designs that used a flapper valve in the inner string wash pipe this happened all the time or some of the time depending on the design. If the flapper was not retained open with a sleeve then any movement uphole with the inner string while still sealed in the packer bore would swab the well. In designs that had retaining sleeves for the flapper held in position by a shear pin, many systems had the setting of that shear pin at a low enough value to be sure that the sleeve moved when it was needed to move that it was often inadvertently sheared to release the flapper. From that point on a pickup on the inner string would make the well swab. Some of the pickup distances were several feet so that the extent of the swabbing was significant.

[0005] The present invention provides an ability to shift between squeeze, circulate and reverse modes using the packer as a frame of reference where the movements between those positions do not engage the low bottom hole pressure control device or wash pipe valve for operation. In essence the wash pipe valve is held open and it takes a pattern of deliberate steps to get it to close. In essence a pickup force against a stop has to be applied for a finite time to displace fluid from a variable volume cavity through an orifice. It is only after holding a predetermined force for a predetermined time that the wash pipe valve assembly is armed by allowing collets to exit a bore. A pattern of passing through the bore in an opposed direction and then picking up to get the collets against the bore they just passed through in the opposite direction that gets the valve to close. Generally the valve is armed directly prior to gravel packing and closed after gravel packing when pulling the assembly out to prevent fluid losses into the formation while reversing out the gravel.

[0006] The extension ports can be closed with a sleeve that is initially locked open but is unlocked by a shifting tool on the wash pipe as it is being pulled up. The sleeve is then shifted over the ports in the outer extension and locked into position. This insures gravel from the pack does not return back thru the ports, and also restricts subsequent production to enter the production string only through the screens. For the run in position this same sleeve is used to prevent flow out the crossover ports so that a dropped ball can be pressurized to set the packer initially.

[0007] The upper valve assembly that indexes off the packer has the capability of allowing reconfiguration after normal operations between squeezing and circulation while holding the wash pipe valve open. The upper valve assembly also has the capability to isolate the formation against fluid loss when it is closed and the crossover is in the reverse position when supported off the reciprocating set down device. An optional ball seat can be provided in the upper valve assembly so that acid can be delivered though the wash pipe and around the initial ball dropped to set the packer so that as the wash pipe is being lifted out of the well acid can be pumped into the formation adjacent the screen sections as the lower end of the wash pipe moves past them.

[0008] These and other advantages of the present invention will be more apparent to those skilled in the art from a review of the detailed description of the preferred embodiment and the associated drawings that appear below with the understanding that the appended claims define the literal and equivalent scope of the invention.

SUMMARY OF THE INVENTION

[0009] A fracturing and gravel packing tool has features that prevent well swabbing when the tool is picked up with respect to a set isolation packer. An upper or multi-acting circulation valve allows switching between the squeeze and circulation positions without risk of closing the wash pipe valve. A metering device allows a surface indication before the wash pipe valve can be activated. The wash pipe valve can only be closed with multiple movements in opposed direction that occur after a predetermined force is held for a finite time to allow movement that arms the wash pipe valve. The multi-acting circulation valve can prevent fluid loss to the formation when closed and the crossover tool is located in the reverse position. A lockable sleeve initially blocks the gravel exit ports to allow the packer to be set with a

dropped ball. The gravel exit ports are pulled out of the sleeve for later gravel packing. That sleeve is unlocked after gravel packing with a shifting tool on the wash pipe to close the gravel slurry exit ports and lock the sleeve in that position for production through the screens. The multi-acting circulation valve can be optionally configured for a second ball seat that can shift a sleeve to allow acid to be pumped through the wash pipe lower end and around the initial ball that was landed to set the packer. That series of movements also blocks off the return path so that the acid has to go to the wash pipe bottom.

BRIEF DESCRIPTION OF THE DRAWINGS

[0010] FIG. 1 is a system schematic representation to show the major components in the run in position;

[0011] FIG. 2 is the view of FIG. 1 in the packer set position;

[0012] FIG. 3 is the view of FIG. 2 in the squeeze position;

[0013] FIG. 4 is the view of FIG. 3 in the circulate position;

[0014] FIG. 5 is the view of FIG. 4 in the metering position which is also the reverse out position;

[0015] FIG. 6 shows how to arm the wash pipe valve so that a subsequent predetermined movement of the inner string can close the wash pipe valve;

[0016] FIG. 7 is similar to FIG. 5 but the wash pipe valve has been closed and the inner assembly is in position for pulling out of the hole for a production string and the screens below that are not shown;

[0017] FIGS. 8a-j show the run in position of the assembly also shown in FIG. 1;

[0018] FIGS. 9a-b the optional additional ball seat in the multi-acting circulation valve before and after dropping the ball to shift a ball seat to allow acidizing after gravel packing on the way out of the hole;

[0019] FIGS. 10a-c are isometric views of the low bottom hole pressure ball valve assembly that is located near the lower end of the inner string;

[0020] FIGS. 11a-j show the tool in the squeeze position of FIG. 3;

[0021] FIGS. 12a-j show the tool in the circulate position where gravel can be deposited, for example;

[0022] FIGS. 13a-j show the metering position which can arm the low bottom hole pressure ball valve to then close; and

[0023] FIGS. 14a-j show the apparatus in the reverse position with the low bottom hole pressure ball valve open.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT

[0024] Referring to FIG. 1, a wellbore **10** that can be cased or open hole has in it a work string **12** that delivers an outer assembly **14** and an inner assembly **16**. At the top of the outer assembly is the isolation packer **18** which is unset for run in FIG. 1. A plurality of fixed ports **20** allow gravel to exit into the annulus **22** as shown in FIG. 4 in the circulation position. A tubular string **24** continues to a series of screens that are not shown at the lower ends of FIG. 1-7 but are of a type well known in the art. There may also be another packer below the screens to isolate the lower end of the zone to be produced or the zone in question may go to the hole bottom.

[0025] The inner string **16** has a multi-passage or multi-acting circulation valve or ported valve assembly **26** that is located below the packer **18** for run in. Seals **28** are below the multi-acting circulation valve **26** to seal into the packer bore for the squeeze and circulate position shown in FIG. 3. Seals **28** are also below the packer bore during run in to maintain hydrostatic pressure on the formation prior to, and after setting, the packer.

[0026] Gravel exit ports **30** are held closed for run in against sleeve **32** and seals **34** and **36**. Metering dogs **38** are shown initially in bore **40** while the reciprocating set down device **42** and the low bottom hole pressure ball valve assembly **44** are supported below bore **40**. Alternatively, the entire assembly of dogs **38**, reciprocating set down device **42** and low bottom hole pressure ball valve assembly **44** can be out of bore **40** for run in. Valve assembly **44** is locked open for run in. A ball seat **46** receives a ball **48**, as shown in FIG. 2 for setting the packer **18**.

[0027] When the packer **18** has been positioned in the proper location and is ready to be set, the ball **48** is pumped to seat **46** with ports **30** in the closed position, as previously described. The applied pressure translates components on a known packer setting tool and the packer **18** is now set in the FIG. 2 position. Arrows **48** represent the pressure being applied to the known packer setting tool (not shown) to get the packer **18** set.

[0028] In FIG. 3 the string **12** is raised and the collets **50** land on the packer **18**. With weight set down on the string **12** seals **52** and **54** on the multi-acting circulation valve **26** isolates the upper annulus **56** from the annulus **22**. Flow down the

string **12** represented by arrows **58** enters ports **30** and then ports **20** to get to the annulus **22** so that gravel slurry represented by arrows **58** can fill the annulus **22** around the screens (not shown). The multi-acting circulation valve **26** has a j-slot mechanism which will be described below that allows the string **12** to be picked up and set down to get seal **52** past a port so as to open a return flow path that is shown in FIG. 4. It should be noted that picking up the string **12** allows access to the annulus **22** every time to avoid swabbing the formation by connecting it fluidly to the upper annulus **56**. On the other hand, setting down on string **12** while the collets **50** rest on the packer **18** will close off the return path to the upper annulus **56** by virtue of seal **52** going back to the FIG. 3 position. This is accomplished with a j-slot mechanism that will be described below. In the circulation mode of FIG. 4 the return flow through the screens (not shown) is shown by arrows **60**. The positions in FIGS. 3 and 4 can be sequentially obtained with a pickup and set down force using the j-slot assembly mentioned before.

[0029] In FIG. 5 the string **12** has been raised until the metering dogs **38** have landed against a shoulder **62**. A pull of a predetermined force for a predetermined time will displace fluid through an orifice and ultimately allow the dogs **38** to collapse into or past bore **64** as shown in FIG. 6. Also, picking up to the FIG. 5 position lets the reciprocating set down device **42** come out of bore **40** so that it can land on shoulder **66** for selective support. Picking up the reciprocating set down device **42** off shoulder **66** and then setting it down again will allow the reciprocating set down device **42** to re-enter bore **40**.

[0030] Once the valve assembly **44** is pulled past bore **40** as shown in FIG. 6 and returned back into bore **40** it is armed. Re-entering bore **40** then close the valve assembly **44**. The valve assembly can re-enter bore **40** to go to the FIG. 7 position for coming out of the hole. It should be noted that reversing out can be done in the FIG. 5 or FIG. 7 positions. To reverse out in FIG. 5 position it is required that valve **44** be closed to prevent fluid loss down the wash pipe. Valve **44** having been closed can be reopened by moving it through bore **40** and then landing it on shoulder **66**.

[0031] FIGS. 8a-8j represent the tool in the run in position. The major components will be described in an order from top to bottom to better explain how they operate. Thereafter, additional details and optional features will be described followed by the sequential operation that builds on the discussion provided with

FIGS. 1- 7. The work string **12** is shown in FIG. 8a as is the top of the packer setting tool **70** that is a known design. It creates relative movement by retaining the upper sub **72** and pushing down the packer setting sleeve **74** with its own sleeve **76**. The upper sub **72** is held by the setting tool **70** using sleeve **78** that has flexible collets at its lower end supported for the setting by sleeve **80**. After a high enough pressure to set the packer **18** has been applied in passage **82** and into ports **84**, sleeve **80** is pushed up to undermine the fingers at the lower end of sleeve **78** so that the upper sub **72** is released by the setting tool **70**. The initial buildup of pressure in passage **82** communicates through ports **86** in FIG. 8a to move the setting sleeve **76** of the setting tool **70** down against the packer setting sleeve **74** to set the packer **18** by pushing out the seal and slip assembly **88**. It is worth noting that in the preferred embodiment the packer setting tool sets the packer at 4000 PSI through port **86**. The pressure is then released and a pull is delivered to the packer with the work string to make sure the slips have set properly. At that point pressure is applied again. Sleeve **80** will move when 5000 PSI is applied.

[0032] Continuing down on the outside of the packer **18** to FIG. 8e there are gravel slurry outlets **20** also shown in FIG. 1 which are a series of holes in axial rows that can be the same size or progressively larger in a downhole direction and they can be slant cut to be oriented in a downhole direction. These openings **20** have a clear shot into the lower annulus **22** shown in FIG. 1. One skilled in the art would understand that these axial rows of holes could be slots or windows of varying configuration so as to direct the slurry into the lower annulus **22**. Continuing at FIG. 8d and below the string **24** continues to the screens that are not shown.

[0033] Referring now to FIGS. 8b-d the multi-acting circulation valve **26** will now be described. The top of the multi-acting circulation valve **26** is at **90** and rests on the packer upper sub **72** for run in. Spring loaded collets **50** shown extended in the squeeze position of FIG. 3, are held against the upper mandrel **94** by a spring **92**. Upper mandrel **94** extends down from upper end **90** to a two position j-slot assembly **96**. The j-slot assembly **96** operably connects the assembly of connected sleeves **98** and **100** to mandrel **94**. Sleeve **100** terminates at a lower end **102** in FIG. 8d. Supported by mandrel **94** is ported sleeve **104** that has ports **106** through which flow represented by arrows **60** in FIG. 4 will pass in the circulation mode when seal **52** is lifted above ports **106**. Below ports **106** is an external seal **28** that in the run in

position is below the lower end **110** of the packer upper sub **72** and seen in FIG. 8c. Note also that sleeve **100** moves within sleeve **112** that has ports **30** covered for run in by sleeve **114** and locked by dog **116** in FIG. 8e. Ports **30** need to be covered so that after a ball is dropped onto seat **118** the passage **82** can be pressured up to set the packer **18**.

[0034] A flapper valve **120** is held open by sleeve **122** that is pinned at **124**. When the ball (first shown in corresponding FIG. 9) is landed on seat **118** and pressure in passage **82** is built up, the flapper is allowed to spring closed against seat **126** so that downhole pressure surges that might blow the ball (not shown in this view) off of seat **118** will be stopped.

[0035] Going back to FIGS. 8a-b, when pressure builds on passage **82** it will go through ports **128** and lift sleeve **130**. The lower end of sleeve **130** serves as a rotational lock to the packer body or upper sub **72** during run in so that if the screens get stuck during run in they can be rotated to free them. After the proper placement for the packer **18** is obtained, the rotational lock of item **130** is no longer needed and it is forced up to release by pressure in passage **82** after the ball is dropped. Piston **134** is then pushed down to set the packer **18** and then piston **136** can move to prevent overstressing the packer seal and slip assembly **88** during the setting process. This creates a "soft release" so that the collet can unlatch from the packer top sub. The setting tool **70** is now released from the packer upper sub **72** and the string **12** can be manipulated.

[0036] Coming back to FIGS. 8b-c, with the packer **18** set, the top **90** of the multi-acting circulation valve **26** can be raised up by pulling up on sleeves **98** and **100** to raise mandrel **94** after shoulders **95** and **97** engage, which allows the lower inner string to be raised. Ultimately the collets **50** will spring out at the location where top end **90** is located in FIG. 8b. With mandrel **94** and everything that hangs on it including sleeve **104**, supported off the packer upper sub **72** the assembly of connected sleeves **98** and **100** can be manipulated up and down and in conjunction with j-slot **96** can come to rest at two possible locations after a pickup and a set down force of a finite length. In one of the two positions of the j-slot **96** the seal **52** will be below the ports **106** as shown in FIG. 8c. In the other position of the j-slot **96** the seal **52** will move up above the ports **106**. In essence seal **52** is in the return flow path represented by arrows **60** in FIG. 4 in the circulate mode which happens when seal **52**

is above ports **106** and the squeeze position where the return path to the upper annulus **56** is closed as in FIG. 3 and in the run in position of FIG. 8c.

[0037] It should be noted that every time the assembly of sleeves **98** and **100** is picked up the seal **52** will rise above ports **106** and the formation will be open to the upper annulus **56**. This is significant in that it prevents the formation from swabbing as the inner string **16** is picked up. If there are seals around the inner string **16** when it is raised for any function, the raising of the inner string **16** will reduce pressure in the formation or cause swabbing which is detrimental to the formation. As mentioned before moving up to operate the j-slot **96** or lifting the inner string to the reverse position of FIGS. 5 or 7 will not actuate the valve **44** nor will it swab the formation. The components of the multi-acting circulation valve have now been described; however there is an optional construction where the return path **137** shown above ports **106** in FIG. 8c is different. The purpose of this alternative embodiment is to allow pumping fluid down passage **82** as the inner string **16** is removed and to block paths of least resistance so that fluid pumped down passage **82** will go down to the lower end of the inner string **16** past the open valve **44** for the purpose of treating from within the screens with acid as the lower end of the inner string **16** moves up the formation on the way out of the wellbore.

[0038] First to gain additional perspective, it is worth noting that the return path **138** around the flapper **120** in FIG. 8e starts below the ports **30** and bypasses them as shown by the paths in hidden lines and then continues in the run in position until closed off at seal **52** just below the ports **106** in FIG. 8c. Referring now to FIG. 9a part **112'** has been redesigned and part **140** is added to span between parts **100** that is inside part **140** at the top and part **112'** that surrounds it at the bottom. Note that what is shown in FIGS. 9a-b is well above the ball seat **118** that was used to set the packer **18** and that is shown in FIG. 8e. Even with this optional design for the multi-acting circulation valve **26** it should be stated that the ball **142** is not dropped until after the gravel packing and reversing out steps are done and the inner string **16** is ready to be pulled out. Note that return path **138'**is still there but now it passes through part **112'** at ports **144** and **146** and channel **138'** on the exterior of part **140**. Ports **150** are held closed by seals **152** and **154**. Ports **156** are offset from ports **150** and are isolated by seals **154** and **158**. Ball **142** lands on seat **160** held by dog **162** to part **140**. When ball **142** lands on seat **160** and pressure builds to undermine dogs **162**

so that part **140** can shift down to align ports **150** and **156** between seals **152** and **154** while isolating ports **144** from ports **146** with seal **164**. Now acid pumped down passage **82** cannot go uphole into return path **138'** because seal **164** blocks it. It is fine for the acid to go downhole into passage **138'** as by that time after the gravel packing the flow downhole into path **138'** will simply go to the bottom of the inner string **16** as it is pulled out of the whole, which is the intended purpose anyway which is to acidize as the inner string is pulled out of the hole.

[0039] Referring now to FIGS. 8e-g the inner string **16** continues with metering device top mandrel **166** that continues to the metering device lower mandrel **168** in FIG. 8g. The metering assembly **38** is shown in FIGS. 1-7. It comprises a series of dogs **170** that have internal grooves **172** and **174** near opposed ends. Metering sub **166** has humps **176** and **178** initially offset for run in from grooves **172** and **174** but at the same spacing. Humps **176** and **178** define a series of grooves **180**, **182** and **184**. For run in the dogs **170** are radially retracted into grooves **180** and **182**. When the inner string **16** is picked up, the dogs **170** continue moving up without interference until hitting shoulder **186** in FIG. 8d. Before that point is reached, however, the dogs **170** go into a bigger bore than the run in position of FIG. 8f and that is when spring **188** pushes the dogs **170** down relative to the metering sub **166** to hold the dogs **170** in the radially extended position up on humps **176** and **178** before the travel stop shoulder **186** is engaged by dogs **170**. In order for the metering sub to keep moving up after the dogs **170** shoulder out it has to bring with it lower mandrel **168** and that requires reducing the volume of chamber **190** which is oil filled by driving the oil through orifice **192** and passage **194** to chamber **196**. Piston **198** is biased by spring **200** and allows piston **198** to shift to compensate for thermal effects. It takes time to do this and this serves as a surface signal that if the force is maintained on the inner string **16** that valve **44** will be armed as shown in FIG. 6. If the orifice **192** is plugged, a higher force can be applied than what it normally takes to displace the oil from chamber **190** and a spring loaded safety valve **202** will open to passage **204** as an alternate path to chamber **196**. When enough oil has been displaced, the inner string **16** moves enough to allow the opposed ends of the dogs **170** to pop into grooves **182** and **184** to undermine support for the dogs **170** while letting the inner string **16** advance up. The wash pipe valve **44** is now expanded upon emerging from

bore **40**. It will take lowering it down through bore **40** below shoulder **210** to arm it and raising valve **44** back into bore **40** to close it.

[0040] Pulling the metering sub **166** up after the dogs **170** are undermined brings the collets **257** (shown in FIG. 10c) on valve assembly **44** completely through narrow bore **40** that starts at **210** and ends at **212** in FIG. 8g. The collets **206** will need to go back through bore **40** from **212** to **210** and then the inner string **16** will need to be picked up to get the collets **257** back into bore **40** for the valve **44** to close. The valve will close when the collet **257** is drawn back into bore **40**.

[0041] The reciprocating set down device **42** has an array of flexible fingers **214** that have a raised section **216** with a lower landing shoulder **218**. There is a two position j-slot **220**. In one position when the shoulder **218** is supported, the j-slot **220** allows lower reciprocating set down device mandrel **222** that is part of the inner string **16** to advance until shoulder **224** engages shoulder **226**, which shoulder **226** is now supported because the shoulder **218** has found support. Coincidentally with the shoulders **224** and **226** engaging, hump **228** comes into alignment with shoulder **218** to allow the reciprocating set down device **42** to be held in position off shoulder **218**. This is shown in the metering and the reverse positions of FIGS. 5 and 7. However, picking up the inner string **16** gets hump **228** above shoulder **218** and actuates the two position j-slot **220** so that when weight is again set down the hump **228** will not ride down to the shoulder **218** to support it so that the collet assembly **214**, **216** will simple collapse inwardly if weight is set down on it and shoulder **218** engages a complementary surface such as **212** in FIG. 8g.

[0042] Referring now to FIGS. 8i-j and FIGS. 10 a-b, the operation of the valve assembly **44** will be reviewed. FIGS. 10a-b show how the valve **44** is first rotated to close from the open position at run in and through various other steps shown in FIGS. 1-7. Spring **230** urges the ball **232** into the open position of FIG. 8j. To close the ball **232** the spring **230** has to be compressed using a j-slot mechanism **234**. Mechanism **234** comprises the sleeve **236** with the external track **238**. It has a lower triangularly shaped end that comes to a flat **242**. An operator sleeve **244** has a triangularly shaped upper end **246** that ends in a flat **248**. Sleeve **244** is connected by links **246** and **248** to ball **232** offset from the rotational axis of ball **232** with one of the connecting pins **250** to the ball **232** shown in FIG. 8j above the ball **232**.

[0043] The j-slot mechanism **234** is actuated by engaging shoulder **252** (see FIG. 10c) when pulling up into a reduced bore such as **40** or when going down with set down weight and engaging shoulder **254** with a reduced bore such as **40**. Sleeve **256** defines spaced collet fingers on the outside of which are found shoulders **252** and **256**. FIG. 10c shows one of several openings **258** in sleeve **256** where the collet member **206** is mounted (see also FIG. 8i). Pin **260** on the collet **206** rides in track **238** of member **236** shown in FIG. 10a.

[0044] Run-in position shown in FIG. 1 starts with triangular components **240** and **246** misaligned with 270 degrees of remaining rotation required for alignment and closure of ball **232**. The first pick up of valve **44** into bore **40** advances triangular components **240** and **246** to 180 degrees of misalignment. Unrestrained upward movement of the inner string **16** is possible until the metering position shown in FIG. 5 where it is important to note that valve **44** remains collapsed in bore **40** until the metering time has elapsed. Once metered thru, the inner string **16** continues upward allowing the collet sleeve **256** of valve **44** to expand above bore **40**. Downward movement of inner string **16** allows shoulder **254** to interact with bore **40** resulting in triangular components **240** and **246** to advance to a position of 90 degrees misalignment. At this point typically circulate position shown in FIG. 4 is to be reached and gravel pumped. Upon completing the gravel pumping procedure inner string **16** will be pulled upward. Valve **44** will enter bore **40** to produce another rotation of **236** allowing triangular components **240** and **246** to align and ball **232** to close. To reiterate, each alternating interaction of shoulder **252** and **254** with respective shoulders of bore **40** produces a 90 degree rotation of j-slot sleeve **236**. Successive interactions of the same shoulder, be it shoulder **252** or shoulder **254**, by entering and exiting bore **40** without passing completely thru do not produce additional 90 degree rotations of j-slot sleeve **236**. Of course the ball **232** can be opened after being closed as described above by pushing shoulder 254 back down through bore **40** get the flats **242** and **248** misaligned at which time the spring **230** rotates the ball **232** back to the open position.

[0045] When the inner string **16** is pulled out the sleeve **114** will be unlocked, shifted and locked in its shifted position. Referring to FIG. 8j a series of shifting collets **252** have an uphole shifting shoulder **255** and a downhole shifting shoulder **257**. When the inner string **16** comes uphole the shoulder **255** will grab shoulder **258**

of sleeve **260** shown in FIG. 8e and carry sleeve **260** off of trapped collet **116** thus releasing sleeve **114** to move uphole. Sleeve **260** will be carried up by the inner string **16** until it bumps collet finger **266** at which point the sleeve **114** moves in tandem with the inner string **16** until collet fingers **266** engage groove **268**. At this point the collet fingers **266** deflect sufficiently to allow sleeve **260** to pass under collet finger **266**. Sleeve **260** stops when it contacts shoulder **262**, locking sleeve **114** in place. Since sleeve **114** is attached to ported sleeve **20** whose top end **264** is not restrained and is free to move up sleeves **114** and **20** will move in tandem with sleeve **260** until collets **266** land in groove **269** to allow sleeve **260** to go over collets **266** and shoulder **255** to release from sleeve **260** as the inner string **16** comes out of the hole. This locks sleeve 114 in the closed position. At this time sleeve **114** will block ports **20** from the annulus **22** so that a production string can go into the packer **18** to produce through the screens (not shown) and through the packer **18** to the surface. The above described movements can be reversed to open ports **20**. To do that the inner string **16** is lowered so that shoulder **257** engages shoulder **270** on sleeve **260** to pull sleeve **260** off of collets **266**. Sleeve **114** and with it the sleeve with ports **20** will get pushed down until collets **116** go into groove **272** so that sleeve **260** can go over them and shoulder **257**can release from sleeve **260** leaving the sleeve **114** locked in the same position it was in for run in as shown in FIG. 8e. Sleeve **114** is lockable at its opposed end positions.

[0046] Referring now to FIGS. 11a-j, the squeeze position is shown. Comparing FIG. 11 to FIG. 8 it can be seen that there are several differences. As seen in FIG. 11e, the ball **48** has landed on seat **118** breaking shear pin **124** as the shifting of seat **118** allows the flapper **120** to close. The packer **18** has been set with pressure against the landed ball **48**. With the packer **18** set the work string **12** picks up the inner string assembly **16** as shown in FIG. 11a such that the multi-acting circulation valve **26** as shown in FIG. 11c now has its collets **50** sitting on the packer upper sub **72** where formerly during run in the top **90** of the multi-acting circulation valve **26** sat during run in as shown in FIG. 8b. With the weight set down on the inner assembly **16** the seal **52** is below ports **106** so that a return path **138** is closed. This isolates the upper annulus **56** (see FIG. 3) from the screens (not shown) at the formation. As mentioned before the j-slot **96** allows for alternative positioning of seal **52** below ports **106** for the squeeze position and for assumption of the circulation position of

seal **52** being above ports **106** on alternate pickup and set down forces of the inner string **16**. The position in FIG. 11d can be quickly obtained if there is fluid loss into the formation so that the upper annulus **56** can quickly be closed. This can be done without having to operate the low bottom hole pressure ball valve **44** which means that subsequent uphole movements will not swab the formation as those uphole movements are made with flow communication to the upper annulus **56** while fluid loss to the formation can be dealt with in the multi-acting circulation valve **26** being in the closed position by setting down with the j-slot **96** into the reverse position.

[0047] It should also be noted that the internal gravel exit ports **30** are now well above the sliding sleeve **114** that initially blocked them to allow the packer **18** to be set. This is shown in FIGS. 11d-e. As shown in FIG. 3 and FIG. 11f, the metering dogs **170** of the metering device **38** are in bore **40** as is the reciprocating set down device assembly **42** shown in FIG. 11i. The low bottom hole pressure ball valve **44** is below bore **40** and will stay there when shifting between the squeeze and circulate positions of FIGS. 3 and 4.

[0048] FIG. 12 is similar to FIG. 11 with the main difference being that the j-slot **96** puts sleeves **98** and **100** in a different position after picking up and setting down weight on the inner string **16** so that the seal **52** is above the ports **106** opening a return path **138** through the ports **106** to the upper annulus **56**. This is shown in FIG. 12c-d. The established circulation path is down the inner string **16** through passage **82** and out ports **30** and then ports **20** to the outer annulus **22** followed by going through the screens (not shown) and then back up the inner string **16** to passage **138** and through ports **106** and into the upper annulus **56**. It should also be noted that the squeeze position of FIG. 11 can be returned to from the FIG. 12 circulation position by simply picking up the inner string **16** and setting it down again using j-slot **96** with the multi-acting circulation valve **26** supported off the packer upper sub **72** at collets **50**. This is significant for several reasons. First the same landing position on the packer upper sub **72** is used for circulation and squeezing as opposed to past designs that required landing at axially discrete locations for those two positions causing some doubt in deep wells if the proper location has been landed on by a locating collet. Switching between circulate and squeeze also poses no danger of closing the low bottom hole pressure ball valve **44** so that there is no risk of swabbing in future picking up of the inner string **16**. In prior designs the uncertainty of attaining the

correct locations mainly for the reverse step at times caused inadvertent release of the wash pipe valve to the closed position because the shear mechanism holding it open was normally set low enough that surface personnel could easily shear it inadvertently. What then happened with past designs is that subsequent picking up of the inner string swabbed the well. Apart from this advantage, even when in the circulation configuration of FIG. 12 for the multi-acting circulation valve **26**, the squeeze position of multi-acting circulation valve **26** can be quickly resumed to reposition seal **52** with respect to ports **106** to prevent fluid losses, when in the reverse position, to the formation with no risk of operating the low bottom hole pressure ball valve **44**.

[0049] It is worth noting that when the string **12** is picked up the multi-acting circulation valve **26** continues to rest on the packer sub **72** until shoulders **95** and **97** come into contact. It is during that initial movement that brings shoulders **95** and **97** together that seal **52** moves past ports **106**. This is a very short distance preferably under a few inches. When this happens the upper annulus **56** is in fluid communication with the lower annulus **22** before the inner string **16** picks up housing **134** of the multi-acting circulation valve **26** and the equipment it supports including the metering assembly **38**, the reciprocating set down device **42** and the low bottom hole pressure ball valve assembly **44**. This initial movement of the sleeves **98** and **100** without housing **134** and the equipment it supports moving at all is a lost motion feature to expose the upper annulus **56** to the lower annulus **22** before the bulk of the inner string **16** moves when shoulders **95** and **97** engage. In essence when the totality of the inner string assembly **16** begins to move, the upper annulus **56** is already communicating with the lower annulus **22** to prevent swabbing. The j-slot assembly **96** and the connected sleeves **98** and **100** are capable of being operated to switch between the squeeze and circulate positions without lifting the inner string **16** below the multi-acting circulation valve **26** and its housing **134**. In that way it is always easy to know which of those two positions the assembly is in while at the same time having an assurance of opening up the upper annulus **56** before moving the lower portion of the inner string **16** and having the further advantage of quickly closing off the upper annulus **56** if there is a sudden fluid loss to the lower annulus **22** by at most a short pickup and set down if the multi-acting circulation valve **26** was in the circulate position at the time of the onset of the fluid loss. This is to be contrasted with

prior designs that inevitably have to move the entire inner string assembly to assume the squeeze, circulate and reverse positions forcing movement of several feet before a port is brought into position to communicate the upper annulus to the lower annulus and in the meantime the well can be swabbed during that long movement of the entire inner string with respect to the packer bore.

[0050] In FIG. 13 the inner string **16** has been picked up to get the gravel exit ports **30** out of the packer upper sub **72** as shown in FIG. 13e. The travel limit of the string **16** is reached when the metering dogs **170** shoulder out at shoulder **186** as shown in FIG. 13f-g and get support from humps **176** and **178**. At this time the reciprocating set down device **42** shown in FIG. 13i is out of bore **40** so that when weight is set down on the inner string **16** after getting to the FIG. 13 position and as shown in FIG. 13i, the travel stop **224** will land on shoulder **226** which will put hump **228** behind shoulder **218** and trap shoulder **218** to shoulder **219** on the outer string **24** supported by the packer **18**. As stated before, the reciprocating set down device **42** has a j-slot assembly **220** shown in FIG. 13h that will allow it to collapse past shoulder **219** simply by picking up off of shoulder **219** and setting right back down again. By executing the metering operation and displacing enough hydraulic fluid from reservoir **190** shown in FIG. 13g the low bottom hole pressure ball valve **44** is pulled through bore **40** that is now located below FIG. 13j. Pulling valve **44** once through bore **40** turns its j-slot **234** 90 degrees but flats **242** and **248** in FIGS. 10a-b are still offset. Going back down all the way through bore **40** will result in another 90 degree rotation of the j-slot **234** with the flats **242** and **248** still being out of alignment and the valve **44** is still open. However, picking up the inner string **16** to get valve **44** through bore **40** a third time will align the flats **242** and **248** to close the valve **44**. Valve **44** can be reopened with a set down back through bore **40** enough to offset the flats **242** and **248** so that spring **230** can power the valve to open again.

[0051] The only difference between FIGS. 13 and 14 is in FIG. 13i compared to FIG. 14i. The difference is that in FIG. 14i weight has been set down after lifting high enough to get dogs **170** up to shoulder **186** and setting down again without metering though, which means without lifting valve **44** through bore **40** all the way. FIG. 14f shows the dogs **170** after setting down and away from their stop shoulder 186. FIG. 14i shows the hump **228** backing the shoulder **218** of the reciprocating set down device **42** onto shoulder **219** of the outer string **24**. Note also that the ports **30**

are above the packer upper sub **72**. The inner string **16** is sealed in the packer upper sub **72** at seal **28**.

[0052] While the invention has been described with a certain degree of particularity, it is manifest that many changes may be made in the details of construction and the arrangement of components without departing from the spirit and scope of this disclosure. It is understood that the invention is not limited to the exemplified embodiments set forth herein but is to be limited only by the scope of the attached claims, including the full range of equivalency to which each element thereof is entitled.

We claim:

1. A well treatment method for squeezing and gravel packing, comprising;

running in an outer assembly that comprises a packer, an outer string supported by said packer and leading to at least one screen and further comprising at least one outer exit port between said packer and said screen;

supporting said outer assembly with an inner string assembly for run in where the inner string assembly is in turn supported on a running string and the inner string assembly comprises a crossover tool to selectively allow gravel to pass through the inner string and out toward said outer exit port of said outer assembly with returns coming through said screen and said crossover tool to an upper annulus defined above said packer and around said running string;

setting said packer to isolate a zone in a wellbore for said screen from said upper annulus and define a lower annulus;

defining a squeeze position for forcing fluid into the wellbore through said lower annulus, a circulate position where gravel is deposited in said lower annulus and returns come through said screen and past said packer to said upper annulus and a reverse position where gravel in said inner string above said crossover can be reversed out to the surface, by relative movement of at least a portion of said inner string with respect to said packer;

providing a valve assembly adjacent a lower end of said inner string assembly said valve assembly is open for run in and requires more than a force applied to said valve assembly in a single direction to close said valve assembly.

2. The method of claim **1**, comprising:

moving said valve assembly in two opposed directions before it can close.

3. The method of claim **2**, comprising:

moving said valve assembly in three discrete movements with one of said movements in an opposite direction than the other two movements before it will close.

4. The method of claim **1**, comprising:

pulling said valve assembly through a spaced apart end of a restricted bore in said outer assembly before it can close.

5. The method of claim **1**, comprising:

encountering resistance to an initial movement of said valve assembly as said valve assembly reaches a restricted bore in said outer assembly.

6. The method of claim **5**, comprising:

overcoming said resistance with a force at a first predetermined level applied through said running string to said valve assembly.

7. The method of claim **6**, comprising:

overcoming said resistance with a force at a second predetermined level higher than said first predetermined level if said valve assembly fails to advance through said restricted bore when said first predetermined level of force is applied.

8. The method of claim **4**, comprising:

pushing said valve assembly through said restricted bore after said pulling said valve assembly through the same bore before said valve assembly can close.

9. The method of claim **8**, comprising:

pulling said valve assembly at least in part into said restricted bore after said pushing said valve assembly through said restricted bore before said valve assembly can close.

10. The method of claim **5**, comprising:

creating said resistance hydraulically while still allowing movement of said valve assembly with respect to said outer assembly;

using said resistance as a surface signal that an initial motion of said valve assembly will be completed if a predetermined force continues to be applied.

11. The method of claim **10**, comprising:

providing said hydraulic resistance with movement of said valve assembly displacing fluid from a reservoir through a first restricted path;

using the time delay of said displacing fluid to decide at the surface if the force applied to said valve assembly is to be continued for subsequent closing of said valve assembly.

12. The method of claim **11**, comprising:

providing a second path from said reservoir with a pressure responsive valve in said second path that opens upon application of an elevated force to said valve assembly than previously required to displace fluid through said first restricted path.

13. The method of claim **1**, comprising:

using a ball in a passage of said inner string assembly as a valve member;

biasing said ball toward the open position;

using relative movement of a first and second components of said valve assembly to rotate said ball against said bias.

14. The method of claim **13**, comprising:

linking said second component to said ball in a location on said ball offset from an axis of rotation of said ball so that axial movement of said second component rotates said ball in opposed directions;

using said first component to create axial movement of said second component.

15. The method of claim **14**, comprising:

rotating said first component to induce axial movement of said second component.

16. The method of claim **15**, comprising:

using a collet that engages a restricted bore in said outer assembly in conjunction with a j-slot assembly that connects said collet to said first component to convert axial displacement of said collet to rotational movement of said first component.

17. The method of claim **16**, comprising:

providing facing tapers defining peaks on said first and second components where said peaks are misaligned when said ball is open;

using said collet and j-slot to rotate said first component until said tapers engage and push said second component axially to align said peaks to define the closed position of said ball.

18. The method of claim **17**, comprising:

rotating said first component 270 degrees to close said ball.

19. The method of claim **18**, comprising:

moving said collet completely through a restrictive bore in said outer assembly at least twice in opposed for 180 degree rotation of said first component;

forcing said collet at least into said restricted restrictive bore in said outer assembly after said 180 degree rotation as a third movement to further rotate said first component to open said ball against said bias.

20. The method of claim **19**, comprising:

completing said third movement by moving said collet through and out of said restrictive bore in said outer assembly and then reversing movement back into said restrictive bore to allow said bias to open said ball.

21. The method of claim **5**, comprising:

creating said resistance in part with at least one dog that aligns with a groove in said outer assembly;

supporting said dog in said groove while moving said inner string assembly to displace fluid through a restriction to create a time delay until said dog becomes unsupported whereupon said resistance ends.

22. The method of claim **5**, comprising:

moving a smart collet through a restrictive bore by the time said resistance begins;

setting down weight rather than applying force against said resistance to allow said smart collet to support said inner string assembly off of said restrictive bore to obtain said reverse position.

23. The method of claim **22**, comprising:

picking up and setting down said smart collet from said reverse position to allow said smart collet to reenter said restrictive bore to obtain said squeeze or circulate position.