

## GRIPPER FOR AN ORDER-PICKING DEVICE, AND METHOD FOR OPERATING THE ORDER-PICKING DEVICE

### Abstract

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The present invention relates to a gripper for a picking device for drug packages and a method for operating the picking device. In known grippers it cannot be determined whether a drug package has been properly moved to the tray table of the gripper. To remedy this, the gripper according to the invention has a tray table (10) extending in a first and a second horizontal direction with an end portion (70) with an arcuate front (71) extending in the second direction, wherein the tray table (10) and the end portion (70) define an upper support surface. The gripper further comprises a transport device (20a, 20b) arranged above the tray table (10) and movable in the first horizontal direction and at least three sensors (73, 73a, 73b) arranged in the end portion (70) below the support surface for determining the presence of a drug package, wherein the sensors are arranged at a distance from one another in the Y-direction and wherein outer sensors (73a) are arranged at a distance in the X-direction from at least one sensor (73b) arranged further inside in the Y-direction, such that the arrangement of the sensors is oriented towards the front (71) extending in an arcuate manner.

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[Fig. 1a]