the implant, the guide member configured to move the portion of the implant within the passageway of the housing when the guide member is moved relative to the housing.

20. The apparatus of claim 19, wherein the passageway is nonlinear.

21. The apparatus of claim 19, wherein at least a portion of the guide member is configured to bend to move the portion of the implant within the passageway.

22. The apparatus of claim 19, wherein the implant is an intrauterine device, the portion of the intrauterine device being flexible.

23. The apparatus of claim 19, further comprising:

a manipulator, a portion of the manipulator disposed within the passageway, the manipulator configured to manipulate the portion of the implant when the implant is conveyed to the target location.

24. The apparatus of claim 23, wherein the manipulator is configured to cut the portion of the implant.

25. The apparatus of claim 19, wherein the second end portion of the guide member is movable between an expanded configuration and a collapsed configuration, the second end portion of the guide member configured to retain the portion of the implant when the second end portion of the guide member is in the collapsed configuration.

26. The apparatus of claim 25, further comprising:

a biasing member configured to urge the second end portion of the guide member toward the collapsed configuration.

26. An apparatus, comprising:

a housing defining a housing passageway;

an insertion member having a distal end portion configured to be removably coupled to a first portion of an implant, at least a portion of the insertion member disposed within the housing passageway, the insertion member configured to move relative to the housing;

a manipulator configured to manipulate a second portion of the implant; and

a transfer member, a first portion of the transfer member coupled to the insertion member such that movement of the transfer member relative to the housing results in movement of the insertion member, a second portion of the transfer member configured to actuate the manipulator when the transfer member is moved relative to the housing.

27. The apparatus of claim 26, wherein the implant is an intrauterine device, the second portion of the intrauterine device being a filament.

28. The apparatus of claim 26, wherein the manipulator is configured to move within the housing to sever the second portion of the implant when the manipulator is actuated.

292. The apparatus of claim 26, wherein the transfer member is configured to transfer a force from an actuator to the insertion member to move the insertion member, the transfer member including a coupling portion configured to move relative to the insertion member when the force exceeds a threshold value.

30. The apparatus of claim 26, wherein the transfer member is configured to reciprocate within the housing.

31. The apparatus of claim 26, wherein the insertion member is a first insertion member, the apparatus further comprising:

a second insertion member coupled to the first insertion member, the second insertion member configured to move relative to the first insertion member to decouple the implant from the distal end portion of the first insertion member.

the implant, the guide member configured to move the portion of the implant within the passageway of the housing when the guide member is moved relative to the housing.

20. The apparatus of claim 19, wherein the passageway is nonlinear.

21. The apparatus of claim 19, wherein at least a portion of the guide member is configured to bend to move the portion of the implant within the passageway.

22. The apparatus of claim 19, wherein the implant is an intrauterine device, the portion of the intrauterine device being flexible.

23. The apparatus of claim 19, further comprising:

a manipulator, a portion of the manipulator disposed within the passageway, the manipulator configured to manipulate the portion of the implant when the implant is conveyed to the target location.

24. The apparatus of claim 23, wherein the manipulator is configured to cut the portion of the implant.

25. The apparatus of claim 19, wherein the second end portion of the guide member is movable between an expanded configuration and a collapsed configuration, the second end portion of the guide member configured to retain the portion of the implant when the second end portion of the guide member is in the collapsed configuration.

26. The apparatus of claim 25, further comprising:

a biasing member configured to urge the second end portion of the guide member toward the collapsed configuration.

27. An apparatus, comprising:

a housing defining a housing passageway;

an insertion member having a distal end portion configured to be removably coupled to a first portion of an implant, at least a portion of the insertion member disposed within the housing passageway, the insertion member configured to move relative to the housing;

a manipulator configured to manipulate a second portion of the implant; and

a transfer member, a first portion of the transfer member coupled to the insertion member such that movement of the transfer member relative to the housing results in movement of the insertion member, a second portion of the transfer member configured to actuate the manipulator when the transfer member is moved relative to the housing.

28. The apparatus of claim 26, wherein the implant is an intrauterine device, the second portion of the intrauterine device being a filament.

29. The apparatus of claim 26, wherein the manipulator is configured to move within the housing to sever the second portion of the implant when the manipulator is actuated.

30. The apparatus of claim 26, wherein the transfer member is configured to transfer a force from an actuator to the insertion member to move the insertion member, the transfer member including a coupling portion configured to move relative to the insertion member when the force exceeds a threshold value.

31. The apparatus of claim 26, wherein the transfer member is configured to reciprocate within the housing.

32. The apparatus of claim 26, wherein the insertion member is a first insertion member, the apparatus further comprising:

a second insertion member coupled to the first insertion member, the second insertion member configured to move relative to the first insertion member to decouple the implant from the distal end portion of the first insertion member.