

ABSTRACT

This position detecting system is provided with: a target object shape extracting part which extracts a target object as a target object shape from a three-dimensional shape in an indoor space, and acquires a position of the target object shape; an identification
5 information acquisition part which acquires, on the basis of data reported from the target object, target object identification information for identifying the target object; and an identification information associating part which associates the target object shape with the target object identification information.