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METHOD AND APPARATUS TO CALIBRATE INTENSITY AND
DETERMINE FRINGE ORDER FOR INTERFEROMETRIC
MEASUREMENT OF SMALL SPACINGS

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BACKGROUND OF THE INVENTION

The rapid increase in the operating speed of computers has led to significant demands on both data storage capacity and access speed. The hard disk drive has been steadily evolving and continues to offer a cost-effective solution to both capacity and speed requirements. Increases in data storage densities and miniaturization of disk drives have enabled even small portable computers to have access to large amounts of on-line disk storage.

In disk drives, head-to-media speeds are such that an air bearing is generated between the head and the disk. At increased speeds the air bearing increases. Thus, without means to counter the tendency to increase the head/media spacing, losses will occur.

Manufacturers of hard disk drives typically measure the flying height of all head/gimble assemblies before assembling them into drives in order to avoid reworking drives after assembly when they do not meet specifications. While head/media spacings in excess of 1 micron can be measured using monochromatic fringe counting techniques, spacings below 1 micron are measured using white light interferometry due to its greater resolution in the range of 250 to 750 nm. Constructive or destructive interference results in the generation of different color fringes which are compared to a Newton's color chart or analyzed by spectrometer. This technique is the current industry standard, however, at spacings of less than 150 nm, the colors wash together and cannot be interpreted with reasonable accuracy.

Various other techniques have been developed for the measurement of small spacings, however, there methods are still incapable of accurately measuring spacing down to contact. One example is U.S. Patent No. 4,593,368 by
5 Fridge et al. This patent describes the use of a computerized spectro-photometer to analyze the color of white light fringes produced at the interface of two surfaces, one of which is transparent, when subject to broad-band illumination. This measuring system and
10 technique has the following disadvantages: 1) At very low spacing (less than $\lambda/5$) no distinct colored fringes are produced. Therefore, at this small spacing, relatively small changes in light intensity as a function of wavelength are measured by the computerized spectro-
15 photometer. Since the measurable change in intensity as a function of wavelength (the color) is greatly reduced at spacings below $\lambda/5$, the signal-to-noise ratio of the measurement greatly decreases for such small spacings. 2) The spectro-photometer employed requires 0.05 seconds to
20 acquire the intensity data for the spectrum of light being used for the measurement. The lengthy time required for data acquisition precludes dynamic measurement of spacing above 10 Hz.

In a method disclosed by Tanaka et al. (U.S. Patent
25 No. 4,630,926) an interferometer is used to dynamically measure head/disk spacing. A xenon light source with a monochrometer produces monochromatic light which is directed over the length of a slider which is inclined such that the spacing between a clear glass disk and the slider
30 varies by more than $\lambda/4$. In such a case where the slider is incident with respect to the disk and the spacing varies by more than $\lambda/4$, at least one maxima and one minima of interferometric fringe intensity occurs. Tanaka et al. teach that at the maximum and minimum (extrema) of fringe
35 intensity, two-beam and multi-beam interferometric theory

yield the same spacing. Therefore, at the extrema, the simpler two-beam theory is used. Tanaka et al. also vary the wavelength of the light being used in order to 1) get fringe extrema and, therefore, spacing measurement at
5 different points along the slider; and 2) verify which order fringe is being detected.

The system of Tanaka et al. is limited in that it cannot measure spacing below $\lambda/4$ of the monochromatic light being used and it is too slow to measure air bearing
10 resonances. Tanaka et al.'s system is clocked at a frequency of 15.8 kHz making it incapable of measuring typical air bearing resonances of 20 kHz or more.

Another method to measure slider/disk spacing is disclosed in Ohkubo et al.'s paper "Accurate Measurement of
15 Gas-lubricated Slider Bearing Separation Using Visible Laser Interferometry" which was distributed as paper 87-Trib-23 by the American Society of Mechanical Engineers. This paper describes the basis of operation for the FM 8801 Laser-Based Flying Height Measuring System which is sold in
20 the U.S.A. by ProQuip, Inc., Santa Clara, California. As described in Ohkubo et al.'s paper, the system uses a HeNe laser source. The beam from the laser goes through a beamsplitter where part of the beam is directed toward a reference photodetector which detects variation in the
25 intensity of the laser source. The remaining part of the laser beam goes through a beam expander then through a lens which focuses the illumination onto the slider/glass disk interface. This illumination causes interference fringes which are focused onto a second measurement photodetector
30 used for measuring intensity of the fringes. The measurement and reference signals from the two photodetectors are sent through amplifiers then into a divider circuit such that the interference signal is normalized to the input laser intensity. From the divider,
35 the signal is sent through an A/D converter to a desk top

computer for processing. The desk top computer digitizes interferometric intensity while the disk changes from a high speed to a low speed.

During the change of disk speed, Ohkubo et al. show flying height to decrease by more than $\lambda/2$. Since the flying height changes, the interferometric intensity varies enough to detect at least one maximum and one minimum fringe intensity. These maximum and minimum fringe intensities are recorded for reference. With the reference maxima and minima of fringe intensity, multi-beam interferometric theory is applied to determine spacing from intensity. However, since for a monochromatic interferometer intensity is a periodic function of spacing, the "fringe order" must be known to finally determine the spacing. This "fringe order" is precisely defined as the interval of spacing from $n/4\lambda$ to $(n-1)/4\lambda$ for $n = 1, 2, 3$. Given an interferometric intensity, and a maximum and minimum fringe intensity for reference, the fringe order n must be determined in order to calculate spacing from the interferometric theory. According to Ohkubo et al.'s paper, the fringe order is determined by landing the slider on the disk by reducing disk speed while monitoring interferometric intensity. The fringe order can be determined by counting the number of times that the interferometric intensity rises to the maximum or falls to the minimum while the spacing is being reduced from the measurement point to the minimum spacing which is assumed to be the fringe order where $n = 1$.

The Ohkubo et al. system has the following disadvantages: 1) the slider must have a design such that the flying height will increase to above $\lambda/2$ simply by changing disk speed; 2) the slider must be landed on the glass disk to determine the fringe order for the spacing calculation; and 3) at the points where the fringe intensity is a minima or maxima, the slope of the

interferometric intensity/spacing curve becomes zero. At these points, the noise in electronic intensity measurement causes a large error in spacing measurement relative to the other spacings which are not directly on the fringe maximum or minimum.

The above-identified disadvantages may cause the following problems: 1) new sliders with a new geometries designed for very low flying height may not fly as high as $\lambda/2$, even at very fast disk speeds, so the Ohkubo et al. technique will not work for such; 2) landing the slider on the disk (required to determine the fringe order) may cause some damage to the air bearing surface of the slider. The possibility for damage to the air bearing surface during test is highly undesirable since many manufacturers test every slider assembly to insure proper flying height; and 3) the relatively high error in spacing measurement at fringe maxima and minima is hidden by "intensity correction" and data "smoothing". These procedures can introduce additional errors into the spacing which is finally calculated.

As magnetic recording technology continues to improve, slider flying heights should continue to decrease to below 100 nm. Also, some manufacturers are beginning to use fluid in the gap to permit smaller spacings. These, too, must be measured. The invention disclosed in this patent is intended to measure such flying heights, statically and dynamically, without having to land the slider on the disk, or have the spacing increase above $\lambda/2$ by only changing disk speed.

The method of intensity calibration and fringe order determination disclosed in this patent can also be applied to other measurements where spacing is decreased to the point of contact, in particular, a micro-hardness tester using a transparent probe could be implemented with interferometric measurement of spacing between the surface

and the probe using this method of interferometric intensity calibration.

SUMMARY OF THE INVENTION

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It is an advantage of the present invention to provide a device for measuring static or dynamic spacing between a transparent article and a reflective surface spacing where the spacing is air or a fluid (down to contact).

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Another advantage is to provide a system for measuring flying height which does not require landing of the slider on the disk to determine fringe order.

15

It is a further advantage of the present invention to provide a flying height tester which uses a calibration procedure to determine maximum and minimum intensity of interference fringes yet is insensitive to changes in illumination intensity or surface reflectivity.

20

It is still another advantage of the present invention to provide a device capable of measurement of disk surface roughness for an entire disk.

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In an exemplary embodiment, the dynamic flying height tester uses a mercury arc lamp light source to provide three distinct wavelengths of light so that three separate interference fringes are generated. Light from the mercury arc lamp is directed substantially normal to the surface of a transparent disk, through the disk and onto the slider on which a magnetic head is mounted. The light reflected from the slider and from the surface of the disk closest to the slider is combined and spectrally analyzed for constructive and destructive interference at each of the three wavelengths. The spectral analysis is accomplished by a detector assembly which includes wavelength discriminating beamsplitters, a filter for each individual wavelength to be measured and a high speed photodetector for each

30

wavelength. The microscope is also connected to a video monitor for visual monitoring of the fringe pattern.

5 A calibration procedure involves measurement of the intensity of all colors while partially unloading the head to determine the maximum and minimum intensity of the fringes for each color being used and to identify the correct fringe orders of the interference patterns. The partial unload for calibration is implemented by rotary head unload which is used to move the head away from the
10 detection assembly by a very small distance, on the order of 0.25 μm . In addition to the demonstrated rotary unload mechanism, any mechanical device which causes the spacing between the head and disk to vary by a quarter wavelength or more can be used to cause the spacing change required
15 for calibration.

Since some parameters such as disk speed or head/disk relative position may be changed after the calibration but prior to the desired measurement, a "follow" trace is made to determine the fringe orders of the measurement trace.
20 The follow trace consists of a spacing measurement which is made during the time any changes occur between the calibration trace and the measurement trace. The follow trace is often required to track the fringe order when changes are made to the head/disk system in between the
25 calibration procedure and the measurement.

Once the calibration trace and follow trace are analyzed, the absolute interferometric intensity reference is known, and the fringe orders for the measurement are known. Therefore, measurement of flying height is
30 accomplished by comparing measured intensity with the theoretical intensity versus spacing relationship. The measurement of spacing can be displayed as spacing versus angular position of the disk or spacing versus time. Also, parameters such as average spacing, maximum spacing,

minimum spacing and others can be calculated from the dynamic spacing data and logged for future reference.

An alternative light source can be a plurality of lasers where each laser emits a different wavelength light, the wavelengths preferably being relatively short to enable measurement of small spacings.

BRIEF DESCRIPTION OF THE DRAWINGS

Understanding of the present invention will be facilitated by consideration of the following detailed description of a preferred embodiment of the present invention, taken in conjunction with the accompanying drawings, in which like reference numerals refer to like parts and in which:

Figure 1 is a diagrammatic view of the flying height testing assembly of the present invention;

Figure 2 is a diagrammatic view of the detector assembly;

Figure 3 is a diagrammatic view of the assembly with an alternate light source;

Figure 4 is a series of plots of spacing versus angle of rotation;

Figure 5 is a plot of spacing versus time;

Figure 6 is an alternate configuration of the testing assembly for measurement of disk surface roughness;

Figure 7 is a diagrammatic view of the apparatus for attaching the head assembly to the load/unload arm;

Figure 8a is a diagrammatic top view of the rotary unload mechanism, Figures 8b and 8c illustrate the load and unload positions, respectively;

Figure 9 is a diagrammatic view of an alternate embodiment in the form of an interferometric surface roughness/surface hardness measurement instrument; and

Figure 10 is a plot of intensity versus spacing.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT

As illustrated in Figure 1, light source 2 is directed through microscope 3 which comprises condensing optics 4, beamsplitter 6 and objective 8. A portion of the incident light split by beamsplitter 6 is directed through glass disk 10 and is internally reflected off the lower surface of the glass disk 10. Another portion of the light is reflected by slider 12. The reflected light is redirected through the objective lens and the beamsplitter 6 into detector assembly 14. The recombination of the light reflected by the lower surface of the disk 10 and the surface of slider 12 results in the generation of interference fringes, with one interference fringe being generated for each individual wavelength of light which has been selected by filters within the assembly. A camera 18 sends a visual image of the fringe patterns to video monitor 22. The photodetectors within the detector assembly 14 convert the fringes' intensity into electrical signals which are then converted to digital data by A/D converter 24. The digital data are then processed at processor 26.

Disk 10 is mounted on spindle 52 which is attached to a variable speed drive capable of achieving speeds in excess of 7200 rpm. In the first embodiment illustrated in Figure 1, the disk 10 is transparent glass or quartz. The slider 12 is attached to rotary load/unload arm 17, which is further illustrated in Figure 8a, by clamping suspension 13, illustrated in Figure 7, onto the end of arm 17 at a given location. Rotary load/unload arm 17 is drive by rotary motor 7. Slider 12 is then positioned under the disk 10 so that light focused by objective 8 passes through disk 10 to be reflected from slider 12 and from the bottom edge 51 of disk 10.

In an alternate embodiment shown in Figure 6, the light source 2' and microscope assembly 3' are positioned relative to the arm and drive so that the slider 12' is between the microscope assembly 3' and disk 10'. Slider 12' is transparent, permitting glide height measurement of an actual magnetic disk 10'. Such a configuration provides measurement of disk surface roughness to identify disk asperities for mapping of asperity heights.

Rotary load/unload arm 17 pivots in such a manner that the slider 12 moves along a line following the light path exiting from objective 8 for at least part of the unload motion. This allows the light to be focused on the same spot on the slider 17 during the calibration procedure, which is described below. The purpose of this movement is to scan at least one fringe maximum and minimum for each color used by increasing the head/disk spacing. Only a small spacing change required, on the order of 0.25 μm , to measure a maximum and minimum intensity for each color fringe to enable calibration. The remainder of the load/unload motion is not critical to measurement functions.

Figure 2 illustrates the elements of detector assembly 14. A first beamsplitter cube 30 reflects light at 436 nm toward absorptive pinhole mirror 29 and 436 nm interference filter 31 to photodetector 32. Beamsplitter cube 30 is a dichroic beamsplitter made from BK7. The entrance face has an anti-reflection coating. The interface is coated for 85-95% reflectance at 435.8 nm and 85-95% transmittance at 546 nm and 580 nm. The portion of light which passes through beamsplitter cube 30 passes through reflective pinhole mirror 33 to beamsplitter cube 34 which reflects light at 546 nm toward 546 nm interference filter 35 and detector 36. Beamsplitter 34 is also dichroic and made from BK7. Its interface coating is 90-100% reflective at 546 nm and 90-100% transmissive at 580 nm. Each of the

interference filters are commercially available filters which transmit light at the chosen wavelength with a bandwidth of 10 nm. The photodetectors are silicon avalanche photodiodes with spectral response in the range of 400-1000 nm. The remaining light continues forward through 580 nm interference filter 37 to photodetector 38. A separate signal is therefore generated for each selected wavelength, and each analog signal generated by photodetectors 32, 36 and 38 is converted to a digital signal by high speed A/D converter 24.

The timing signal by which the sampling rate is controlled is 250 kHz. The timing rate is applied to the A/D converter as a conversion rate control signal. This rapid rate of data conversion enables dynamic measurement of spacing between the head and disk.

In an alternate embodiment, light beams emitted from two or more lasers can be optically combined to generate the illumination projected onto the head/disk interface. Such a configuration is illustrated in Figure 3 in which lasers 41 and 42 each emit at different wavelengths. The beams are expanded by beam expander optics 43 and are combined at beamsplitter 44 to be projected through the microscope objective as above. The detector assembly 45 will have the same number of detectors as lasers, and the appropriate interference filters for the selected lasing wavelengths will be provided.

The accuracy and repeatability of the location of the head 11 with respect to the disk 10 requires that appropriate attachment means are provided to hold the head 11 into place. The suspension 13 must be attached to and removed quickly from the mounting arm 17, and the attachment must be uniform and repeatable. In order to quickly and repeatably grip the suspension 13, the use of a flexible band 48 of polyester film, such as Mylar® or Kapton®, is used, as shown in Figure 7, with a tension

means 49 included to keep the band 48 taut. Since the suspension 13 is somewhat flexible, it may be deformed under uneven or excessive pressure as might be applied by a steel clamp. The flexible band 48 does not deform the suspension 13 and is very thin, as required by the small spacing between the suspension 13 and the disk 10.

The procedure for measuring the spacing between the head 11 and the disk 10 is as follows:

The head 11 is attached to the suspension using the flexible band 48, and the rotary load/unload arm 17 moves the head 11 into the desired location, as in Figure 8b. Light from the light source 2 is projected through the microscope 3 onto the head 11, and the head 11 is then partially unloaded by rotation of arm 17, as illustrated in Figure 8c, so that a calibration trace can be generated. The head unload motion is synchronized with the digitization by the processor 26 such that the digitization will record the intensity of one maximum and one minimum fringe for each individual wavelength tested. The rotary head unload is used so that the slider 12 has only very slight motion while the loading pressure is reduced. The slight motion of the slider 12 is compensated for by moving the microscope assembly 3 by way of x-y translators 5 and 5' in synchronization with the unload motion so that the measurement spot remains at the same point on the slider 12. As previously described, the unload motion required for calibration increases the spacing by a very small amount, on the order of 0.5 μm .

The calibration trace is digitally lowpass filtered to reduce electronic noise. A maximum and minimum intensity for each color in the calibration trace is found by searching through the data collected. The trace is normalized to the maximum and minimum intensity for each color by multiplying a constant and adding a constant offset. In the preferred embodiment, the maximum intensity

for each color is scaled to 1.0 and the minimum intensity for each color is scaled to -1.0.

A look-up table for intensity of each color versus spacing is generated for discrete steps of spacing based on Equation 1 which was derived from multiple beam interferometric theory for a single film.

$$\frac{I_{OUT}}{I_{IN}} = \frac{r^2 + s^2 + 2rs \cos \delta}{1 + r^2 s^2 + 2rs \cos \delta}$$

(1)

where:

10	r	=	Amplitude Reflection Off Glass Disk;
	s	=	Amplitude Reflectance Off Slider;
	n	=	Refractive Index of the Fluid in the Spacing;
	δ	=	$4\pi n H/\lambda$;
15	H	=	Flying Height;
	λ	=	Wavelength of the Illuminating Light; and
	γ	=	Phase Shift on Reflection (Material Dependent)

20

The values of r, s, and δ are determined by ellipsometric measurement of the surfaces using light of the same wavelengths as those being used for the interference measurements of spacing.

25

The ellipsometer measures angles ψ and Δ from which the complex index of refraction $\bar{n} = n - ik$ can be determined. The reflectance for the disk and slider can then be determined from Equation 2:

$$r = \sqrt{\frac{(n_0 - n_1)^2 + k_1^2}{(n_0 + n_1)^2 + k_1^2}}$$

(2)

where $\bar{n}_0$ is the refractive index of the medium immediately above the reflecting surface which has the refractive index $\bar{n}_1$.

5 For the internal glass reflection $\bar{n}_0$ is the index of glass and $\bar{n}_1$ is the index of the fluid in the spacing. For the reflection off the slider, $\bar{n}_0$ is the index of the fluid in the spacing (air or liquid) and $\bar{n}_1$ is the index of the slider.

10 From the ellipsometric measurements, the phase change upon reflection δ can be calculated using Equation 3:

$$\delta = \tan^{-1} \frac{2n_0k_1}{n_0^2 - n_1^2 - k_1^2}$$

(3)

For use in Equation 1, $\delta = \delta_{\text{slider}} - \delta_{\text{glass disk}}$.

15 In the present embodiment, a look-up table is generated using Equations 1, 2 and 3 with intensities for spacings for 0 to 1,000 nm with steps of 1 nm. The theoretic intensity look-up table is normalized to fringe intensity extrema using the same convention as that used for the measured traces, i.e., +1 is maximum, -1 is
20 minimum.

Table 1 illustrates the form of the look-up table for intensity versus spacing:

	SPACING	INTENSITY		
		λ_1	λ_2	λ_3
5	0	-1	-1	-1
	5	-0.8	-0.7	-0.6
	10	-0.6	-0.4	-0.2
10	TABLE 1			

Once the measurements are made and the look-up table is generated, a calculation is made to determine the spacing for the first point in the calibration curve. The calculation of spacing is made as follows:

A "mean square error" is calculated for each discrete step of spacing (H) in the range of interest. Here, steps of spacing from 0 to 1,000 nm in steps of 1 nm are used. These steps conveniently correspond to the values in the theoretical look-up table above. The mean square error (e) is calculated as follows:

$$e(h) = w_1(T_1 - M_1)^2 + w_2(T_2 - M_2)^2 + w_3(T_3 - M_3)^2 \quad (4)$$

where T_x is the theoretical intensity of color x for the spacing H (from the look-up table) and M_x is the measured intensity of color x.

The symbols w_x are used to indicate weighing functions, which help reduce error. While all of the w's can be set to one, accuracy can be improved by choosing the w's such that $w_1 + w_2 + w_3 = \text{some constant}$ and setting each w higher for a color when the signal-to-noise ratio of that color's intensity measurement is higher. Additionally, w_x may be

a function of spacing because, near the maximum or minimum of a given color's intensity, a small amount of electrical noise corresponds to a relatively large change in spacing.

For reference purposes, the "first point" of a trace
5 requires intensity measurements for all three colors, λ_1 , λ_2 and λ_3 . The measured intensity of all colors are stored together and they, as a group, will be referred to as a single point in the intensity trace.

Once (e) has been calculated for each step of spacing,
10 the smallest value of (e) corresponds to a first guess for the initial spacing for the first point in the calibration array. Occasionally, noise in the intensity signal may result in the calculated value being the wrong fringe order. For example, considering only one color, if the
15 normalized intensity is -1, the spacing is given by $n\lambda/2$ where λ is the wavelength of light and n is the fringe order ($n = 0, 1, 2, 3, 4 \dots$). This result comes from a simple model which assumes the disk and slider are made of dielectric materials.

20 The use of two or more colors gives additional information which theoretically indicates the correct fringe order. However, the addition of some noise to the measured signals will occasionally cause this technique to calculate an initial spacing which is significantly
25 incorrect because it is on the wrong fringe order. The principle by which fringe order is determined can be explained by looking at a plot of intensity versus spacing for interference fringes generated for two or more colors. Figure 10 illustrates such a plot for two colors. The
30 intensity function 81 for λ_1 has a different period than that for λ_2 (82). By comparing the normalized measured intensity with the normalized theoretical intensity for both colors the spacing can be determined but there may be some uncertainty as to fringe order. For example, the
35 normalized intensity difference between λ_1 and λ_2 at points

84 and 85 is the same at different orders. This is solved by measuring the intensity continuously while the spacing between the transparent article and the reflective surface is changed (increased) which shows the slope of the
5 respective functions beyond the initial point 84. This enables identification of the correct order.

To determine the correct fringe order, the entire calibration intensity trace is used as follows:

Several different first guesses are made for the
10 spacing for the first point in the calibration trace. The criteria for selection of the first point initial guesses for spacing are that each spacing must have a low value of (e). Additionally, each guess must be at least 100 nm away from all the previously-selected initial guesses for
15 spacing. Once several of the initial guesses are obtained, one of the guesses is correct, but the correct one must be determined.

In order to determine which first guess is correct, a cumulative mean square error for each initial guess is
20 calculated. The cumulative error is calculated by assuming that the spacing does not change by more than 100 nm between each point. The following process is used to calculate the cumulative mean square error for each initial guess of spacing.

25 First, the cumulative error is set to the (e) which corresponds to the initial guess for the spacing at the first point in the calibration trace. Next, the spacing at the second point is calculated by searching through all spacing values within ± 100 nm from the first point. The
30 (e) determined for the second point is added to the cumulative error. The second step is repeated for all remaining points in the calibration trace with the condition that each point must not be more than 100 nm away from the previous point. Once the cumulative error is
35 calculated for each initial guess for spacing of the first

point in the calibration, the spacing with the lowest cumulative error is determined to be the spacing for the first point in the calibration.

5 Analysis of the data taken during calibration has yielded the maximum and minimum intensity for each fringe and the fringe order for the spacing measured during the calibration step.

10 Since operational parameters may change after the after the calibration but before the measurement, the fringe order may change, hence a "follow" trace is recorded while any operation parameters are changed. It is assumed that the first point in the follow trace is within 100 nm of the first point of the calibration trace.

15 The spacing for each point in the follow trace is calculated as follows:

20 Point-by-point, the mean square error is determined for spacings with values from -100 to +100 nm away from the previous point. Note that, since the first point in the follow trace does not have a previous point, the spacing is calculated from the first point in the calibration trace. The spacing with the lowest (e) is determined to be the spacing, and the process is repeated for all points in the trace. By limiting the calculation such that each successive point must be within 100 nm of the previous point, the calculation can never jump to an incorrect fringe order.

30 Once the spacing for the follow trace is calculated, it can be assumed that the spacing for the first point in the measurement trace is within 100 nm of the last point of the follow trace. Since the approximate spacing for the first point of the measurement trace is known, the spacing for the measurement trace is performed using the same procedure used to calculate the spacing for the follow trace.

It should be noted that the 100 nm difference limit is arbitrarily selected and that other values may be used as allowed by the wavelengths of light used for measurement, i.e., the limit should not exceed $\frac{1}{4}$ wavelength.

5 In the preferred embodiment, the flying height tester measures at least 256 points per revolution. A typical test involves storage of data of intensity versus angle for two revolutions. Thus, at least 512 points are taken for each data set. The processor converts intensity versus
10 revolution data into spacing versus revolution and provides an output display in either the form of a video monitor or a printout. Since air bearing thickness is a function of disk speed, testing of the spacing between a given head and disk is preferably performed at a number of disk rotational
15 speeds. Figure 4 illustrates a series of plots of spacing versus angle for two revolutions. Figures 4a, b and c show plots at 3,600 RPM, 900 RPM and 225 RPM, respectively. Figure 4d is a plot of spacing versus disk speed illustrating the principle of increased spacing with
20 increased rotational speed.

Figure 5 is a plot of spacing versus time to show measurement by the system of dynamic variation of head/disk spacing after the head flies over a flaw in the disk.

Interferometric fringe intensity calibration is used
25 to calibrate maximum and minimum intensity of light and dark interferometric fringes. The maximum and minimum fringe intensity is measured at one or more points on the interferometric image while altering interferometric path length by at least $\frac{1}{4}$ of the wavelength of the light being
30 used to produce the interferometric image. By comparison of interferometric intensity to the maximum and minimum intensity, it is possible to obtain spatial measurement with a resolution of a small fraction of the wavelength of light used.

While a number of flying height testers use interference to measure the spacing between the head and media, the system of the present invention utilizes a unique calibration technique in which the head is unloaded
5 in a controlled manner to increase the relative path lengths of the two light rays while monitoring and storing the intensity information in order to utilize interferometric fringe intensity for calibration of the measurement. Thus the need for expensive and difficult
10 control of system components such as light sources, detector drift and disk quality is eliminated. The apparatus of the present invention provides high speed measurement of head/disk spacing simultaneously using multiple wavelengths of light, thus offering a more
15 economical and faster measurement system and technique for dynamic measurement of flying height than systems that are currently available.

Shown in Figure 9 is another use of the intensity calibration method, here used for a micro-hardness
20 tester/surface profiler. In Figure 9, light from source 61 which could be a Mercury arc, a multiple laser, or other multi-wavelength source, goes through beamsplitter 62, then through microscope objective 63, being focused on the interface between transparent probe 64 and the surface to
25 be analyzed 65. The probe is lowered onto the surface using computer-controlled actuator 67 which could use piezo-electric or other means of mechanically moving the probe 64 toward the surface 65. The contact load between the probe 64 and the surface 65 is detected by a load cell
30 66. Light reflected from the surface of the probe 64 which is closest to the sample surface and the surface itself 65 recombines, producing interference effects. Monochromatic images of the interference fringes are projected onto TV cameras 73, 74, and 75 after going through beamsplitters
35 62, 68 and 69, as well as narrow band interference filters

70, 71, and 72. Each TV camera then produces an analog video signal corresponding to the interferometric image for the narrow band of light associated with each interference filter. Note that filters 70, 71, and 72 each transmit a
5 different color of light. The analog video signals are directed into the RGB color frame grabber 76 which is under control of the personal computer 77.

To make a surface roughness and hardness measurement, the computer controlled actuator 67 lowers the probe 64
10 onto the surface 65. During the time that the probe is coming into contact with the surface, the frame grabber 76 continuously acquires images of the three different interference images and the computer processes such images, storing the maximum and minimum intensity of each color at
15 each pixel on each image. Before the probe 64 comes into contact with the surface 65, a minimum and maximum intensity of the fringes for each color will have been detected for each pixel of each image of the fringes. These maximum and minimum fringe intensity values are the
20 normalization intensity values required to determine spacing between the probe 64 and the surface 65. The spacing between the probe 64 and surface 65 is calculated in a manner identical to that described for the Dynamic Flying Height Tester, except the spacing is calculated for
25 a 2-dimensional area rather than a single spot, and the spacing is measured statically, not dynamically. Since the probe 64 shape is known beforehand, the surface profile of the surface 65 can be readily calculated from the spacing between the probe 64 and the surface 65. This surface
30 profile indicates the roughness of the surface.

The surface hardness and other surface properties can be measured by pressing the probe 64 onto the surface 65. The force with which the probe is being pressed onto the surface is measured using load cell 66. The surface
35 profile can continue to be measured interferometrically

while it is being deformed by the probe. The measurement of surface deformation as a function of contact pressure will allow a measurement of surface hardness while causing a minimum amount of damage to the surface.

5 Both the Dynamic Flying Height Tester and the Interferometric Micro-hardness Tester illustrate ways that the Method to calibrate intensity for interferometric measurement of small spacing can be used. The feasibility of the measurement has been demonstrated by the
10 measurements of flying height illustrated herein.

 It will be evident that there are additional embodiments which are not illustrated above but which are clearly within the scope and spirit of the present invention. The above description and drawings are
15 therefore intended to be exemplary only and the scope of the invention is to be limited solely by the appended claims.

This Sheet Has Been Replaced



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CLAIMS

1. An apparatus for determining the spacing between
2 a transparent article and a reflective surface, said
apparatus comprising:
 - 4 a light source for emitting light at a plurality
of wavelengths λ ;
 - 6 a microscope assembly for focusing at least a
first portion of said light along a light path onto a
8 target position between said transparent article and said
reflective surface and for receiving reflected light from
10 said target position, said reflected light being a
combination of light reflected from an interface between
12 said transparent article and said spacing and light
reflected from an interface between said spacing and said
14 reflective surface;
 - a support for maintaining said transparent
16 article at substantially a fixed elevation with respect to
said target position;
 - 18 a movable mounting arm for retaining said
reflective surface and for moving said reflective surface
20 away from said target position substantially along said
light path by at least $\lambda/4$;
 - 22 a detector assembly comprising:
 - 24 a plurality of photodetectors for converting
fringe patterns created by combination of said
reflected light into one electrical signal for each
26 photodetector, one photodetector corresponding to each
of said plurality of wavelengths;
 - 28 at least one beamsplitter for distributing
each of said plurality of wavelengths to its
30 corresponding photodetector;



32 a plurality of filters disposed between said
at least one beamsplitter and said plurality of
34 photodetectors, each filter selectively transmitting
one of said plurality of wavelengths to its
corresponding photodetector; and

36 a processor for receiving each said electrical
signal and generating information therefrom to determine
38 said spacing between said transparent article and said
reflective surface.

2 2. An apparatus as in Claim 1 wherein said processor
is calibrated for each of said plurality of wavelengths by
pivoting said mounting arm to move said reflective surface
4 out of said target position to increase said spacing.

2 3. An apparatus as in Claim 1 wherein said support
comprises a rotatable spindle.

2 4. An apparatus for determining the spacing between
a head assembly and a hard disk, at least one of said head
assembly and said hard disk having a transparent portion,
4 said apparatus comprising:

6 a light source for emitting light at a plurality
of wavelengths λ ;

8 a microscope assembly for focusing a first
portion of said light along a light path onto a target
position and for receiving reflected light from said target
10 position and directing said reflected light along a common
path with a second portion of said light;

12 a support for maintaining said hard disk apart
from said head assembly at an elevation such that at least
14 one of an upper surface and a lower surface of said hard
disk is disposed substantially at said target position;



16 a pivotable mounting arm for releasably retaining
said head assembly and for moving said head assembly into
18 and out of said target position substantially along said
light path by at least $\lambda/4$;

20 a detector assembly comprising:

a plurality of photodetectors for converting
22 fringe patterns created by combination of said
reflected light and said second portion of said light
24 into one electrical signal for each photodetector, one
photodetector corresponding to each of said plurality
26 of wavelengths;

at least one beamsplitter for distributing
28 each of said plurality of wavelengths to its
corresponding photodetector;

30 a plurality of filters disposed between said
at least one beamsplitter and said plurality of
32 photodetectors, each filter selectively transmitting
one of said plurality of wavelengths to its
34 corresponding photodetector; and

a processor for receiving each said electrical
36 signal and generating information therefrom to determine
said spacing between said head assembly and said hard disk.

5. An apparatus as in Claim 1 further comprising a
2 CCD camera and a video monitor for viewing one of said
fringe patterns.

6. An apparatus as in Claim 4 wherein said processor
2 includes an analog to digital converter.

7. An apparatus as in Claim 4 wherein said processor
2 includes a memory for storage of at least each said digital
signal.

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2 8. An apparatus as in Claim 4 wherein said hard disk
is transparent and said first portion of light is reflected
from a slider within said head assembly.

2 9. An apparatus as in Claim 4 wherein said head
assembly has a transparent slider and said hard disk is a
magnetic storage disk.

2 10. An apparatus as in Claim 4 wherein said light
source is a mercury arc lamp.

2 11. An apparatus as in Claim 4 wherein said light
source is a plurality of lasers.

2 12. An apparatus as in Claim 1 wherein said mounting
arm has a thin flexible band under tension for retaining
said head assembly.

2 13. An apparatus as in Claim 12 wherein said thin
flexible band is a thin polyester film.

2 14. An apparatus for determining the spacing between
a magnetic head assembly and a hard disk, said apparatus
comprising:

4 a light source for emitting light at a plurality
of wavelengths;

6 a microscope assembly for focusing at least a
portion of said light along a light path onto a target
8 position, said reflected light being a combination of light
reflected from an upper boundary and a lower boundary of
10 said spacing;

a transparent disk having an upper surface and a
12 lower surface, said transparent disk being mounted on a
spindle for rotation past said magnetic head, said lower
14 surface being said upper boundary;



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16 a pivotal mounting arm for releasably retaining
said magnetic head assembly and for moving said magnetic
18 head assembly into and out of said target position
substantially along said light path, said magnetic head
assembly being said lower boundary;

20 a detector assembly comprising:

22 a plurality of photodetectors for converting
fringe patterns created by said reflected light into
one electrical signal for each photodetector, one
24 photodetector corresponding to each of said plurality
of wavelengths;

26 at least one beamsplitter for directing
light of each of said plurality of wavelengths to its
28 corresponding photodetector;

a plurality of filters disposed between said
30 at least one beamsplitter and said plurality of
photodetectors, each filter selectively transmitting
32 one of said plurality of wavelengths to its
corresponding photodetector; and

34 a processor for receiving each said
electrical signal and generating information therefrom
36 to determine said spacing between said magnetic head
and said hard disk.

15. An apparatus as in Claim 14 wherein said
2 processor is calibrated for each of said plurality of
wavelengths by pivoting said mounting arm to move said
4 magnetic head out of said target position to change said
spacing.

16. An apparatus as in Claim 15 wherein said light
2 source is a mercury arc lamp.



17. A method for measuring spacing between a transparent article and a reflective surface which comprises:

selecting a light source for emitting light having a plurality of wavelengths;

directing said light along a light path toward a target position so that a first portion of said light is reflected by an interface between said spacing and said transparent article and a second portion of said light passes through said transparent article and is reflected by an interface between said spacing and said reflective surface;

receiving light reflected from the two interfaces so that the combination of said first portion with said second portion generates fringe patterns;

optically separating said fringe patterns so that one fringe pattern corresponds to each of said plurality of wavelengths;

converting each separated fringe pattern into an electrical signal;

digitizing each electrical signal;

processing each digitized electrical signal using a processor to determine maximum and minimum light intensity of each of said fringe patterns; and

determining said spacing by comparing correlation between light intensity of each fringe pattern and its corresponding wavelength for each wavelength of said plurality.

18. A method as in Claim 17 further comprising calibrating said processor by moving said reflective surface away from said target position so that said spacing is increased by at least $\lambda/4$ and recording the maximum and minimum light intensity of said fringe patterns for each wavelength when said reflective surface is in motion.



19. A method for calibrating a processor for
2 determining the spacing between a transparent surface and
a reflective surface using an interferometer having a light
4 source emitting at a plurality of wavelengths λ which
comprises:

6 focusing at least a portion of light from said
light source along a light path at said spacing;

8 mounting one of said transparent surface and said
reflective surface on a movable mounting so that said
10 spacing can be increased along said light path;

receiving reflected light from a first interface
12 between said transparent surface and said spacing and from
a second interface between said spacing and said reflective
14 surface;

generating a fringe pattern from said reflected
16 light for each of said plurality of wavelengths λ ;

increasing said spacing by moving said movable
18 mounting; and

recording a maximum and minimum light intensity
20 of said fringe pattern while said movable mounting is in
motion.

20. A method as in Claim 19 which further comprises:
2 generating a look-up table of intensity of each
wavelength λ versus spacing;

4 calculating a mean square error for each of a
selected increment of said spacing by comparing the
6 recorded maximum and minimum light intensity with a
theoretical intensity from said look-up table; and

8 selecting an initial spacing according to said
selected increment having the smallest said mean square
10 error.



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21. A method for measuring a spacing between a head
2 assembly and a hard disk which comprises:

replacing one of said head assembly and said hard
4 disk with a transparent substitute;

rotating a disk comprising one of said hard disk
6 or a substitute disk on a spindle with a slider comprising
one of a substitute head assembly or said head assembly
8 biased toward said disk;

directing light having a plurality of wavelengths
10 along a light path through at least a portion of said
transparent substitute to be focused at a target position
12 between said slider and said disk;

receiving light reflected from a surface of said
14 transparent substitute closest to said target position and
from a surface of said slider or said disk according to
16 which has been replaced by said transparent substitute, so
that the reflected light from each surface is combined to
18 generate fringe patterns;

optically separating said fringe patterns so that
20 one fringe pattern corresponds to each of said plurality of
wavelengths;

22 converting each separated fringe pattern into an
electrical signal;

24 digitizing each electrical signal;

processing each digitized electrical signal using
26 a processor to determine maximum and minimum light
intensity of each of said fringe patterns; and

28 determining said spacing by comparing correlation
between measured light intensity of each fringe pattern and
30 theoretical light intensity at each wavelength of said
plurality.



22. A method as in Claim 21 further comprising
2 calibrating said processor by moving said slider away from
said target position so that said spacing is increased and
4 recording the maximum and minimum light intensity of said
fringe patterns while said slider is in motion.

23. A method as in Claim 22 further comprising
2 utilizing the intensity measurements recorded during the
step of calibrating to determine fringe order.

24. A method as in Claim 23 wherein correct fringe
2 order is assured by requiring a measurement to be within a
fixed range of a previous measurement.

25. A method for simultaneously measuring roughness
2 and hardness of a surface which comprises:
 splitting light having a plurality of wavelengths
4 λ into a first portion and a second portion;
 directing said first portion along a light path
6 toward an interface between a transparent probe and said
surface at a first location of said surface;
8 attaching a load cell to said probe;
 reflecting said first portion from said
10 interface;
 combining the reflected said first portion and
12 said second portion to generate fringe patterns;
 storing maximum and minimum intensity of said
14 fringe patterns for each wavelength λ ;
 calculating spacing using said maximum and
16 minimum intensity;
 moving said probe toward said surface while
18 continuously generating said fringe patterns and storing
their maximum and minimum intensity; and
20 detecting a contact load between said probe and
said surface while said probe deforms said surface.



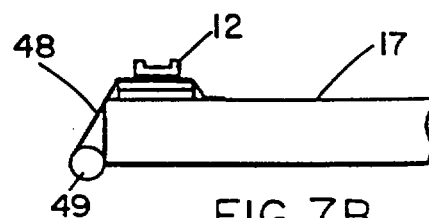
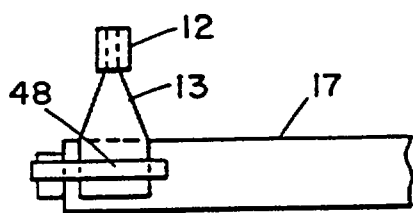
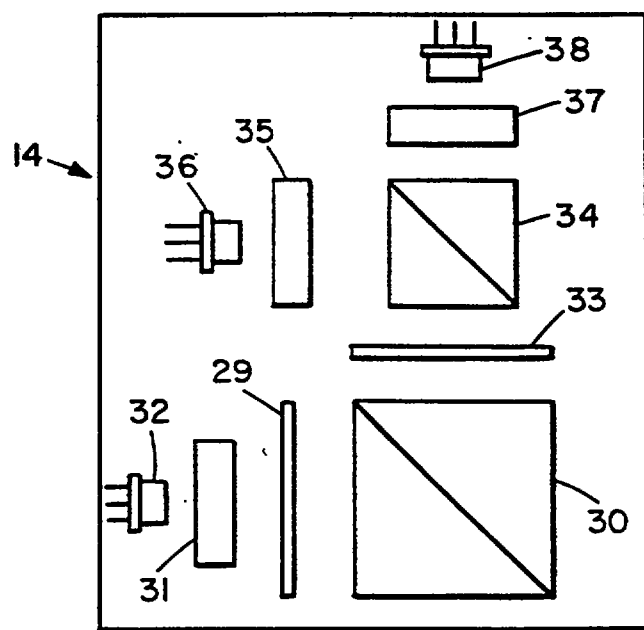
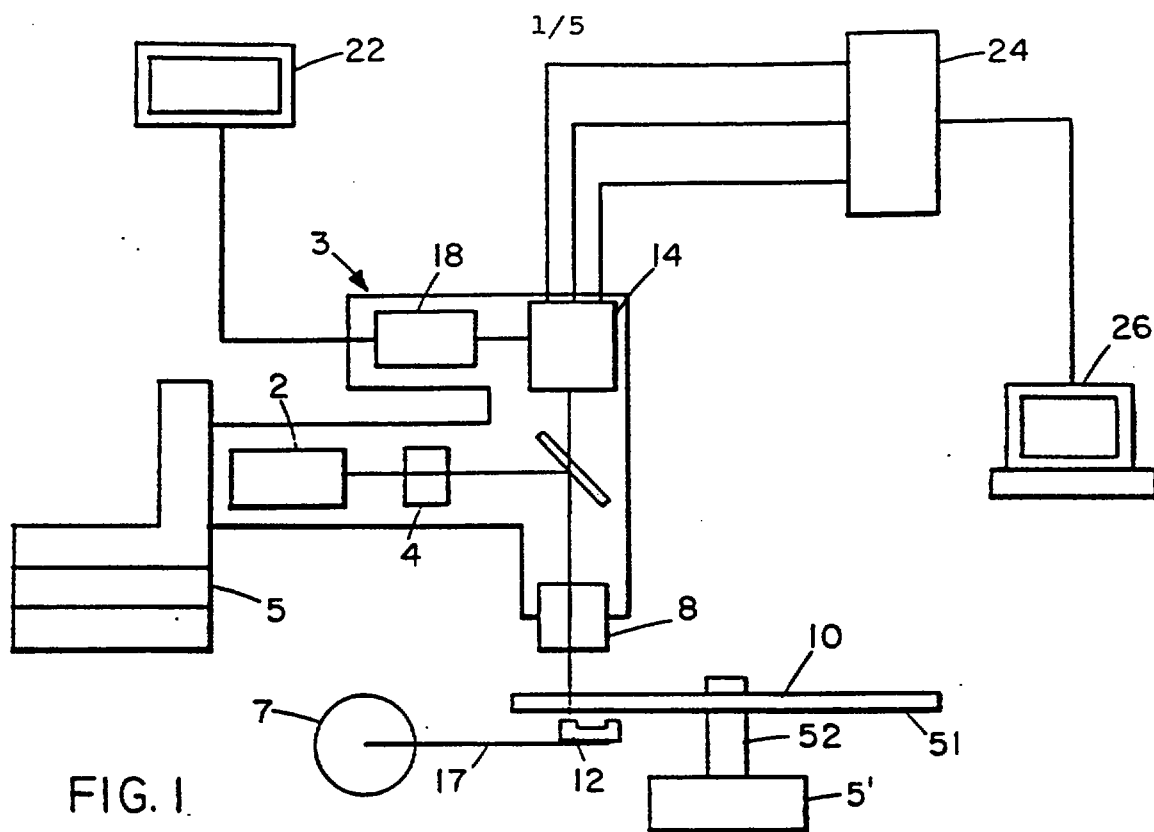
26. A method for determining correct fringe order in
an interferometric system for measurement of spacing
between a transparent article and a reflective surface,
said method which comprises:
selecting a light source for emitting light at a
plurality of wavelengths;
detecting interference fringes generated within
said interferometric system by reflection from said
spacing;
separating each of said interference fringes
according to its wavelength;
generating a theoretical plot of normalized
intensity versus spacing for each said wavelength; and
comparing a measured normalized intensity to said
theoretical plot of normalized intensity while altering
said spacing.

ABSTRACT

TITLE: METHOD AND APPARATUS TO CALIBRATE INTENSITY AND
DETERMINE FRINGE ORDER FOR INTERFEROMETRIC
MEASUREMENT OF SMALL SPACINGS

The apparatus and method for measuring a small spacing down to contact uses an interferometric fringe intensity calibration to calibrate maximum and minimum intensity of two or more monochromatic or quasi-monochromatic interference patterns caused by a spacing between two articles (10, 12), one of which is transparent (10). The intensity calibration is done by measuring maximum and minimum fringe intensity of each color (2) while altering the spacing (51) by at least $1/4$ of the wavelength of the light or other electromagnetic radiation being used. The calibration by changing spacing allows the fringe order to be calculated (26) for each wavelength of the radiation being used. This calibration procedure allows the maximum and minimum intensity of the radiation to be known, as well as the fringe order of the interference patterns to be calculated. With the maximum and minimum intensities and the fringe orders known, the spacing is readily calculated from interferometric theory.

Fig 1



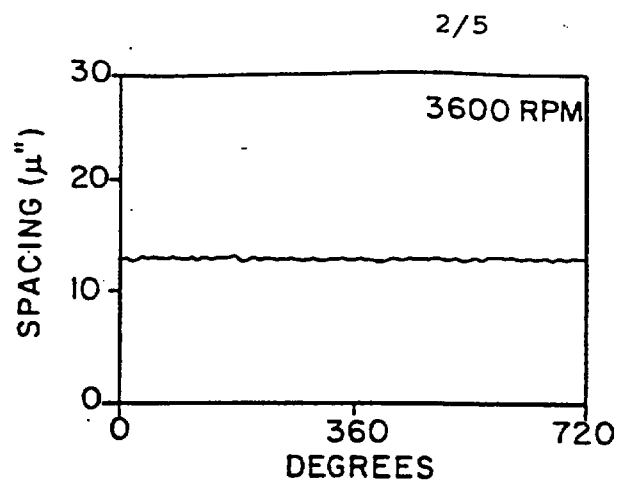


FIG. 4A

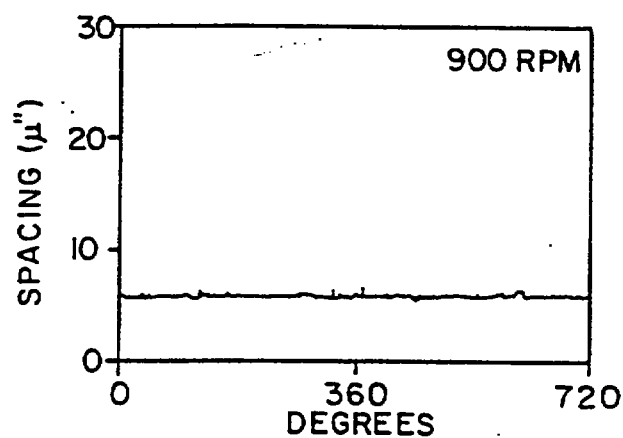


FIG. 4B

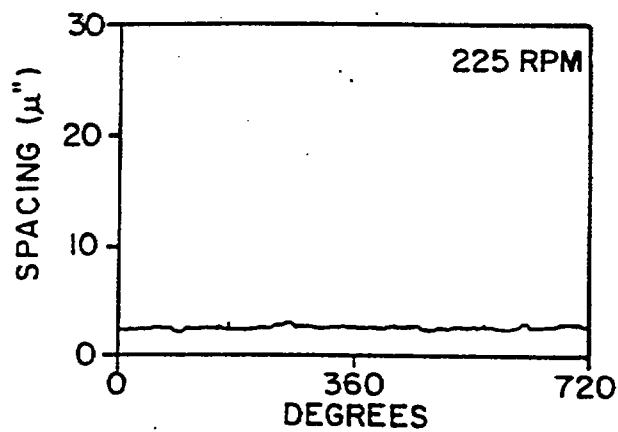


FIG. 4C

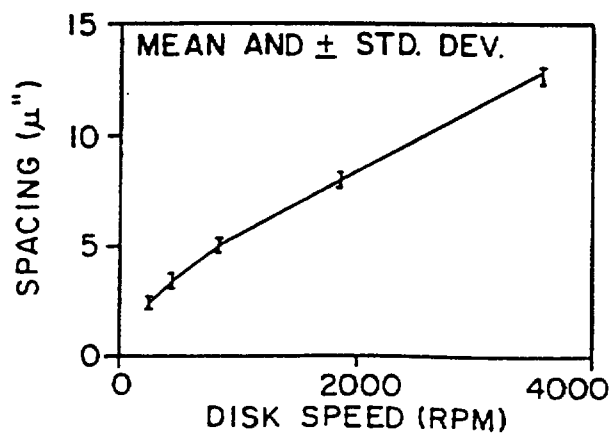


FIG. 4D

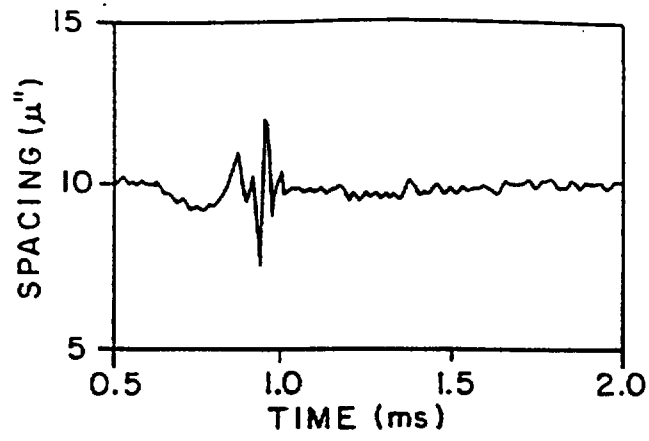


FIG. 5

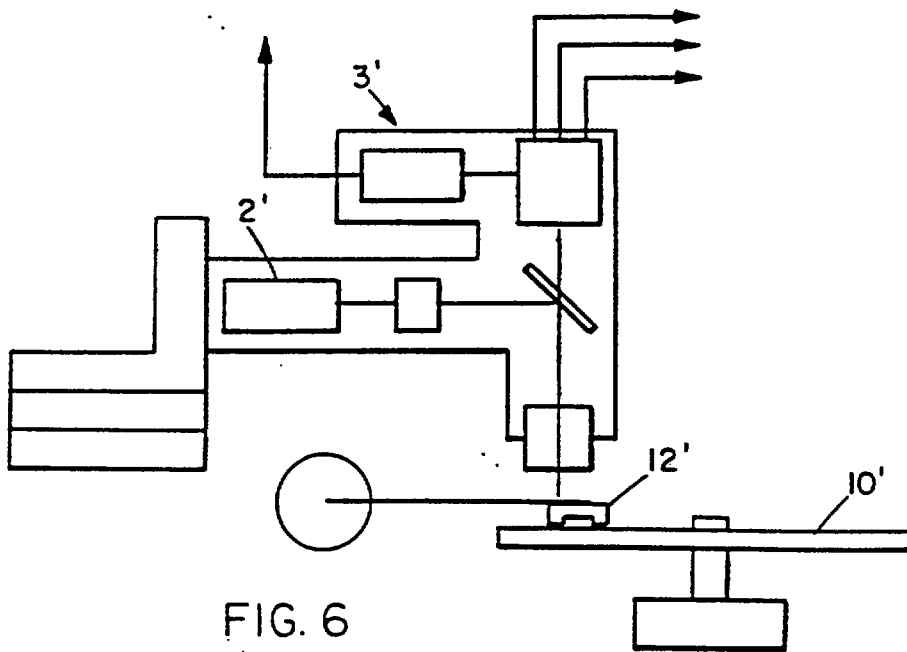


FIG. 6

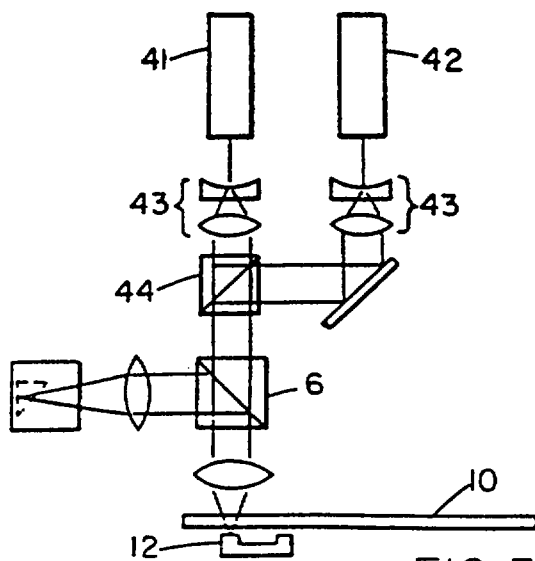


FIG. 3

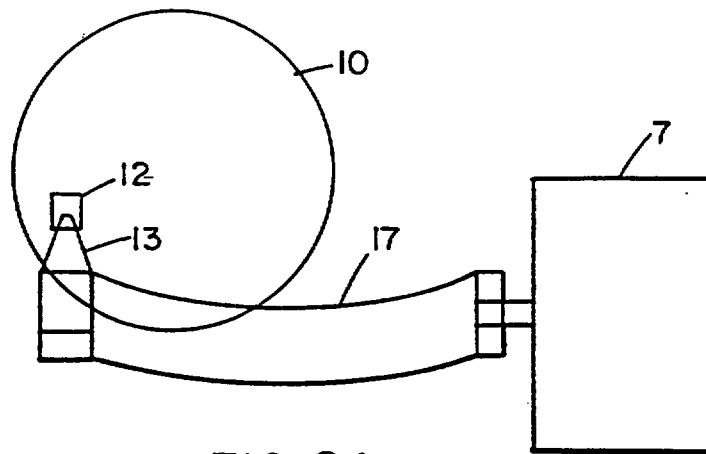


FIG. 8A

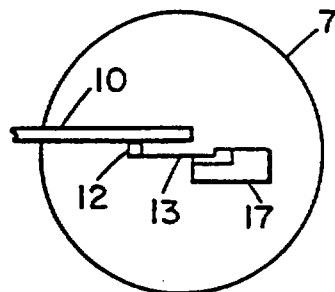


FIG. 8B

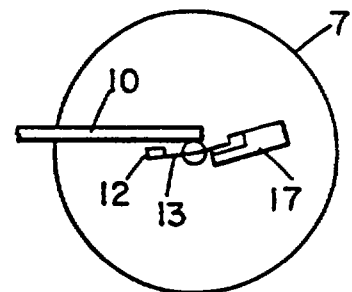


FIG. 8C

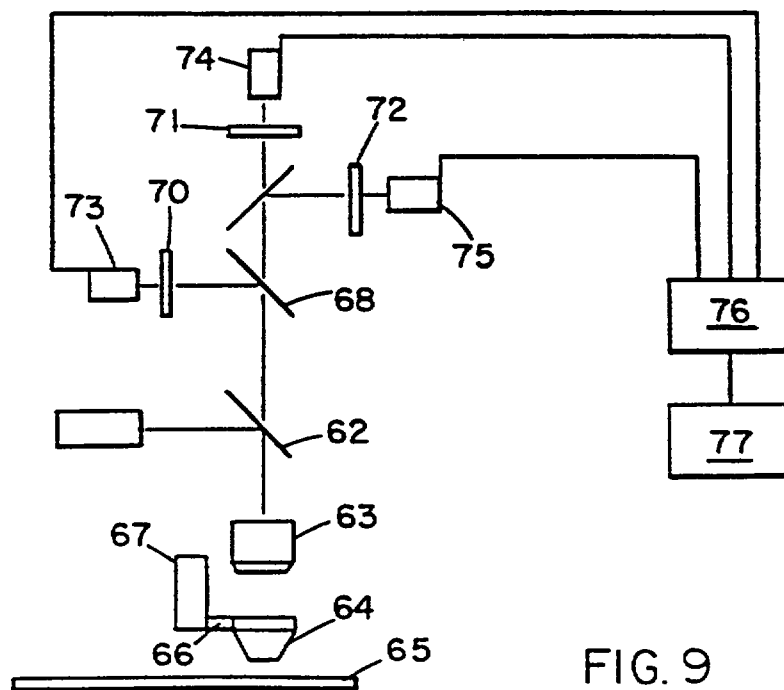


FIG. 9

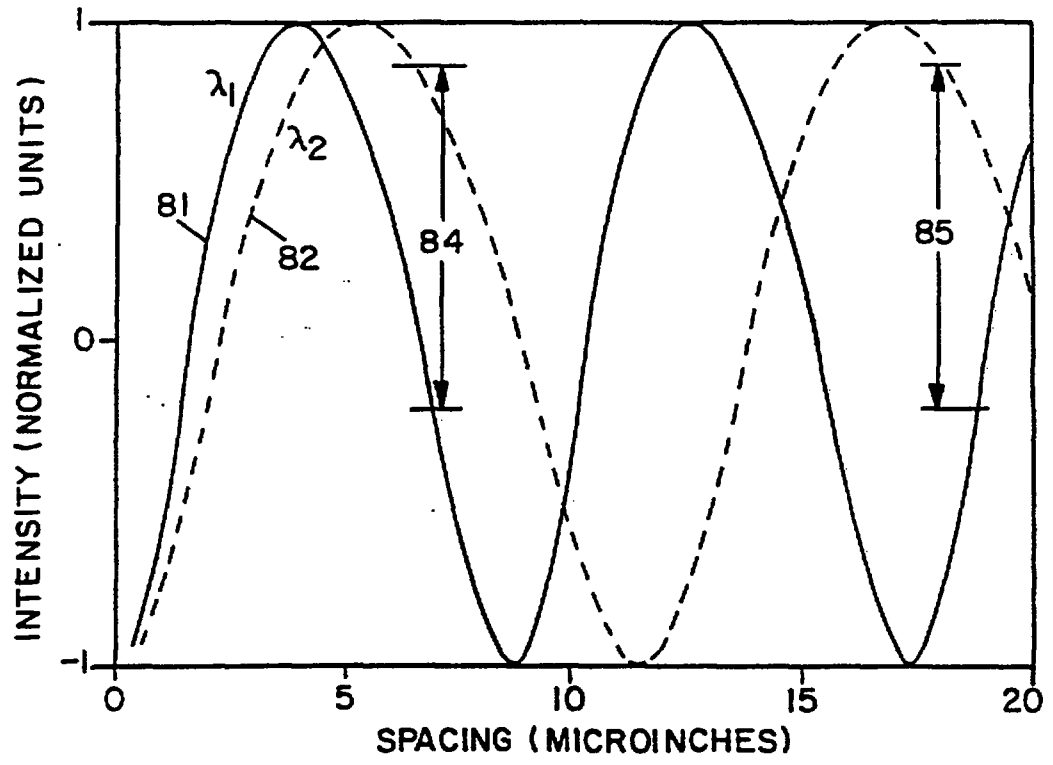


FIG. 10



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AMENDED CLAIMS

REPLACEMENT SHEETS SG

- ☐ Description : paged to paged
☒ Claim(s) : paged 1... to paged 18.
☐ Drawing(s) : paged to paged
☐ Abstract : paged to paged

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1. An apparatus for determining the spacing between a transparent article and a reflective surface, said apparatus comprising:

a light source for emitting light at a plurality of wavelengths λ ;

a microscope assembly for focusing at least a first portion of said light along a light path onto a target position between said transparent article and said reflective surface and for receiving reflected light from said target position, said reflected light being a combination of light reflected from an interface between said transparent article and said spacing and light reflected from an interface between said spacing and said reflective surface;

a support for maintaining said transparent article at substantially a fixed elevation with respect to said target position;

a movable mounting arm for retaining said reflective surface and for moving said reflective surface away from said target position substantially along said light path by at least $\lambda/4$;

a detector assembly comprising:

a plurality of photodetectors for converting fringe patterns created by combination of said reflected light into one electrical signal for each photodetector, one photodetector corresponding to each of said plurality of wavelengths;

at least one beamsplitter for distributing each of said plurality of wavelengths to its corresponding photodetector; and

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a plurality of filters disposed between said at least one beamsplitter and said plurality of photodetectors, each filter selectively transmitting one of said plurality of wavelengths to its corresponding photodetector;

a mounting arm calibration controller for changing said spacing between said transparent article and said reflective surface by moving said moveable mounting arm during a calibration, wherein calibration fringe patterns for each of said plurality of wavelengths are recorded while said controller is moving said mounting arm and changing said spacing; and

a processor for receiving each said electrical signal and generating information therefrom to determine said spacing between said transparent article and said reflective surface.

2. An apparatus as in Claim 1 further comprising a mount for said moveable mounting arm having an axis about which said moveable mounting arm can be rotated, thereby changing said spacing between said transparent article and said reflective surface by a pivoting motion of said moveable mounting arm about said axis.
3. An apparatus as in Claim 1 wherein said support comprises a rotatable spindle.
4. An apparatus for determining the spacing between a head assembly and a hard disk, at least one of said head assembly and said hard disk having a transparent portion, said apparatus comprising:

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a light source for emitting light at a plurality of wavelengths λ ;

a microscope assembly for focusing a first portion of said light along a light path onto a target position and for receiving reflected light from said target position and directing said reflected light along a common path with a second portion of said light;

a support for maintaining said hard disk apart from said head assembly at an elevation such that at least one of an upper surface and a lower surface of said hard disk is disposed substantially at said target position;

a pivotable mounting arm for releasably retaining said head assembly and for moving said head assembly into and out of said target position substantially along said light path by at least $\lambda/4$;

a detector assembly comprising:

a plurality of photodetectors for converting fringe patterns created by combination of said reflected light and said second portion of said light into one electrical signal for each photodetector, one photodetector corresponding to each of said plurality of wavelengths;

at least one beamsplitter for distributing each of said plurality of wavelengths to its corresponding photodetector;

a plurality of filters disposed between said at least one beamsplitter and said plurality of photodetectors, each filter selectively transmitting one of said plurality of wavelengths to its corresponding photodetector;

a mounting arm calibration controller for changing said spacing between said head assembly and said hard disk by pivoting said pivotable mounting arm during a calibration, wherein calibration fringe patterns for each of

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said plurality of wavelengths are recorded while said controller is pivoting said pivotable mounting arm and changing said spacing; and

a processor for receiving each said electrical signal and generating information therefrom to determine said spacing between said head assembly and said hard disk.

5. An apparatus as in Claim 1 further comprising a CCD camera and a video monitor for viewing one of said fringe patterns.
6. An apparatus as in Claim 4 wherein said processor includes an analog to digital converter.
7. An apparatus as in Claim 4 wherein said processor includes a memory for storage of at least each said digital signal.
8. An apparatus as in Claim 4 wherein said hard disk is transparent and said first portion of light is reflected from a slider within said head assembly.
9. An apparatus as in Claim 4 wherein said head assembly has a transparent slider and said hard disk is a magnetic storage disk.
10. An apparatus as in Claim 4 wherein said light source is a mercury arc lamp.
11. An apparatus as in Claim 4 wherein said light source is a plurality of lasers.

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12. An apparatus for determining the spacing between a transparent article and a reflective surface, said apparatus comprising:

a light source for emitting light at a plurality of wavelengths λ ;

a microscope assembly for focusing at least a first portion of said light along a light path onto a target position between said transparent article and said reflective surface and for receiving reflected light from said target position, said reflected light being a combination of light reflected from an interface between said transparent article and said spacing and light reflected from an interface between said spacing and said reflective surface;

a support for maintaining said transparent article at substantially a fixed elevation with respect to said target position;

a movable mounting arm for retaining said reflective surface and for moving said reflective surface away from said target position substantially along said light path by at least $\lambda/4$, wherein said mounting arm has a thin flexible band under tension for retaining said reflective surface;

a detector assembly comprising:

a plurality of photodetectors for converting fringe patterns created by combination of said reflected light into one electrical signal for each photodetector, one photodetector corresponding to each of said plurality of wavelengths;

at least one beamsplitter for distributing each of said plurality of wavelengths to its corresponding Photodetector; and

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a plurality of filters disposed between said at least one beamsplitter and said plurality of photodetectors, each filter selectively transmitting one of said plurality of wavelengths to its corresponding photodetector; and

a processor for receiving each said electrical signal and generating information therefrom to determine said spacing between said transparent article and said reflective surface.

13. An apparatus as in Claim 12 wherein said thin flexible band is a thin polyester film.

14. An apparatus for determining the spacing between a magnetic head assembly and a hard disk, said apparatus comprising:

a light source for emitting light at a plurality of wavelengths;

a microscope assembly for focusing at least a portion of said light along a light path onto a target position, said reflected light being a combination of light reflected from an upper boundary and a lower boundary of said spacing;

a transparent disk having an upper surface and a lower surface, said transparent disk being mounted on a spindle for rotation past said magnetic head, said lower surface being said upper boundary;

a pivotal mounting arm for releasably retaining said magnetic head assembly and for moving said magnetic head assembly into and out of said target position substantially along said light path, said magnetic head assembly being said lower boundary;

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a detector assembly comprising:

a plurality of photodetectors for converting fringe patterns created by said reflected light into one electrical signal for each photodetector, one photodetector corresponding to each of said plurality of wavelengths;

at least one beamsplitter for directing light of each of said plurality of wavelengths to its corresponding photodetector;

a plurality of filters disposed between said at least one beamsplitter and said plurality of photodetectors, each filter selectively transmitting one of said plurality of wavelengths to its corresponding photodetector;

a mounting arm calibration controller for changing said spacing between said magnetic head assembly and said hard disk by pivoting said pivotal mounting arm during a calibration, wherein calibration fringe patterns for each of said plurality of wavelengths are recorded while said controller is pivoting said pivotal mounting arm and changing said spacing; and

a processor for receiving each said electrical signal and generating information therefrom to determine said spacing between said magnetic head and said hard disk.

15. An apparatus as in Claim 14 wherein said processor further comprises a look-up table containing theoretical light intensity as a function of spacing for each of said plurality of wavelengths.
16. An apparatus as in Claim 14 wherein said light source is a mercury arc lamp.



17. A method for measuring spacing between a transparent article and a reflective surface which comprises:

selecting a light source for emitting light having a plurality of wavelengths;

directing said light along a light path toward a target position so that a first portion of said light is reflected by an interface between said spacing and said transparent article and a second portion of said light passes through said transparent article and is reflected by an interface between said spacing and said reflective surface;

receiving light reflected from the two interfaces so that the combination of said first portion with said second portion generates fringe patterns;

optically separating said fringe patterns so that one fringe pattern corresponds to each of said plurality of wavelengths;

converting each separated fringe pattern into an electrical signal;

digitizing each electrical signal;

processing each digitized electrical signal using a processor to determine maximum and minimum light intensity of each of said fringe patterns;

determining said spacing by comparing correlation between light intensity of each fringe pattern and its corresponding wavelength for each wavelength of said plurality; and

calibrating said processor by moving said reflective surface away from said target position so that said spacing is increased by at least $\lambda/4$ and

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recording the maximum and minimum light intensity of said fringe patterns for each wavelength when said reflective surface is in motion.

18. A method for calibrating a processor for determining the spacing between a transparent surface and a reflective surface using an interferometer having a light source emitting at a plurality of wavelengths λ which comprises:

focusing at least a portion of light from said light source along a light path at said spacing;

mounting one of said transparent surface and said reflective surface on a movable mounting so that said spacing can be increased along said light path;

receiving reflected light from a first interface between said transparent surface and said spacing and from a second interface between said spacing and said reflective surface;

generating a fringe pattern from said reflected light for each of said plurality of wavelengths λ ; increasing said spacing by moving said movable mounting; and

recording a maximum and minimum light intensity of said fringe pattern while said movable mounting is in motion.

19. A method as in Claim 18 which further comprises:

generating a look-up table of intensity of each wavelength λ versus spacing;

calculating a mean square error for each of a selected increment of said spacing by comparing the recorded maximum and minimum light intensity with a theoretical intensity from said look-up table; and

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selecting an initial spacing according to said selected increment having the smallest said mean square error.

20. A method for measuring a spacing between a head assembly and a hard disk which comprises:

replacing one of said head assembly and said hard disk with a transparent substitute;

rotating a disk comprising one of said hard disk or a substitute disk on a spindle with a slider comprising one of a substitute head assembly or said head assembly biased toward said disk;

directing light having a plurality of wavelengths along a light path through at least a portion of said transparent substitute to be focused at a target position between said slider and said disk;

receiving light reflected from a surface of said transparent substitute closest to said target position and from a surface of said slider or said disk according to which has been replaced by said transparent substitute, so that the reflected light from each surface is combined to generate fringe patterns;

optically separating said fringe patterns so that one fringe pattern corresponds to each of said plurality of wavelengths;

converting each separated fringe pattern into an electrical signal;

digitizing each electrical signal;

processing each digitized electrical signal using a processor to determine maximum and minimum light intensity of each of said fringe patterns;

determining said spacing by comparing correlation between measured light intensity of each

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fringe pattern and theoretical light intensity at each wavelength of said plurality; and

calibrating said processor by moving said slider away from said target position so that said spacing is increased and recording the maximum and minimum light intensity of said fringe patterns while said slider is in motion.

21. A method as in Claim 20 further comprising utilizing the intensity measurements recorded during the step of calibrating to determine fringe order.
22. A method as in Claim 21 wherein correct fringe order is assured by requiring a measurement to be within a fixed range of a previous measurement.
23. A method for determining correct fringe order in an interferometric system for measurement of spacing between a transparent article and a reflective surface, said method which comprises:
 - selecting a light source for emitting light at a plurality of wavelengths;
 - detecting interference fringes generated within said interferometric system by reflection from said spacing;
 - separating each of said interference fringes according to its wavelength;
 - generating a theoretical plot of normalized intensity versus spacing for each said wavelength; and
 - comparing a measured normalized intensity to said theoretical plot of normalized intensity while altering said spacing.

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24. An interferometric apparatus for measuring the dimensions of a spacing, said apparatus comprising:

a light source for producing light having a first wavelength and a second wavelength;

optics for directing said first and second wavelengths of light to a spacing having a separation distance, said spacing defined by first and second boundaries, such that light reflected from said first and second boundaries produces a first wavelength interference signal and a second wavelength interference signal, said first and second wavelength interference signals having characteristics determined by said separation distance;

a detector for measuring the intensities of said first and second wavelength interference signals; a calibration controller for changing said separation distance while acquiring first and second calibration fringe patterns corresponding to said first and second wavelengths; and

a processor for analyzing said measured intensities of said first and second wavelength interference signals and deriving therefrom said separation distance.

25. An interferometric apparatus as defined in Claim 24 wherein said processor further comprises:

a look-up-table which contains a first set of theoretical interference signal intensity data which corresponds to said first wavelength of light and a second set of theoretical interference signal intensity data which corresponds to said second wavelength of light; and

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a comparator for comparing said measured intensities with said look-up-table theoretical intensities to determine said spacing.

26. An interferometric apparatus as defined in Claim 24 wherein said light source further comprises a mercury arc lamp.
27. An interferometric apparatus as defined in Claim 24 wherein said light source further comprises a laser.
28. An interferometric apparatus as defined in Claim 24 wherein said optics further comprises a microscope assembly.
29. An interferometric apparatus as defined in Claim 24 wherein said detector further comprises a photodetector.
30. A method for determining correct fringe order in an interferometric system for measurement of a small spacing comprising:
 - selecting a light source for emitting light at a plurality of wavelengths;
 - detecting interference fringes generated within said interferometric system by reflection from said spacing;
 - separating each of said interference fringes according to its wavelength;
 - measuring and recording the interference fringe intensity at two or more of said plurality of wavelengths for a range of spacing by altering said spacing;

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generating a theoretical plot of normalized intensity versus spacing for each of said two or more wavelengths; and

comparing said measured intensity to said theoretical plot at said two or more wavelengths to determine the fringe order.

31. A slider positioning apparatus for positioning a slider relative to a first plane corresponding to a surface of a disk comprising:

a slider attached to a suspension near a distal end of said suspension, said suspension having a longitudinal axis; and

a rotary load/unload arm having a rotation axis which is substantially parallel to said first plane about which said rotary load/unload arm rotates, wherein said suspension is mounted to said rotary load/unload arm such that said suspension longitudinal axis forms an angle with said rotary load/unload arm rotation axis and said slider is positioned adjacent said first plane at a separation distance from said first plane, said separation distance increasing as said rotary load/unload arm rotates about said rotation axis in a first direction and decreasing as said rotary load/unload arm rotates about said rotation axis in a second direction which is opposite said first direction.

32. An apparatus as defined in Claim 31 further comprising a rotary drive motor attached to said rotary load/unload arm for rotating said rotary load/unload arm about said rotation axis.

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33. An apparatus as defined in Claim 31 wherein said angle formed between said suspension longitudinal axis and said rotary load/unload arm rotation axis is approximately a 90 degree right angle.
34. An apparatus as defined in Claim 31 wherein said rotary load/unload arm rotation axis intersects said suspension longitudinal axis at a location along said suspension longitudinal axis which is intermediate said distal end of said suspension and a proximate end of said suspension.
35. A method for changing the distance between a surface of a disk and a slider attached to a distal end of a slider suspension having a longitudinal axis, said method comprising the steps of:
- mounting said slider suspension on a rotary load/unload arm having a rotation axis which is substantially parallel to said surface of said disk such that said slider suspension longitudinal axis forms an angle with said rotary load/unload arm rotation axis; and
- rotating said rotary load/unload arm about said rotation axis thereby changing the distance between said surface of said disk and said slider.
36. A method as defined in Claim 35 further comprising the step of mounting said rotary load/unload arm to a rotary motor.
37. A method as defined in Claim 35 wherein said mounting step further comprises making said angle between said suspension longitudinal axis and said rotary load/unload arm rotation axis approximately 90 degrees.

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38. A method as defined in Claim 35 wherein said mounting step further comprises attaching said rotary load/unload arm to said suspension such that said rotary load/unload arm rotation axis intersects said suspension longitudinal axis at a location along said suspension longitudinal axis which is intermediate said distal end of said suspension and a proximate end of said suspension.
39. A slider positioning apparatus for positioning a slider (12) relative to a surface of a disk (10) wherein the slider (12) is attached to a suspension member (13) near a distal end of a longitudinal axis of the suspension member, said apparatus comprising:
- a rotary load/unload arm (17) having a rotation axis which is substantially parallel to said surface of said disk about which said rotary load/unload arm rotates, wherein the suspension member (13) is attached to said rotary load/unload arm (17) such that the suspension member (13) longitudinal axis forms an angle with said rotary load/unload arm (17) rotation axis.
40. An apparatus as defined in Claim 39 further comprising a rotary drive motor (7) attached to said rotary load/unload arm (17) for rotating said rotary load/unload arm (17) about said rotation axis.
41. An apparatus as defined in Claim 39 wherein said angle formed between said suspension member (13) longitudinal axis and said rotary load/unload arm rotation axis is approximately a 90 degree right angle.

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42. An apparatus as defined in Claim 39 wherein said rotary load/unload arm (17) rotation axis intersects said suspension member (13) longitudinal axis at a location along said suspension member (13) longitudinal axis which is intermediate said distal end of said suspension member (13) and a proximate end of said suspension member (13).
43. A slider positioning apparatus for positioning a slider relative to a first plane corresponding to a surface of a disk comprising:
- a slider attached to a suspension near a distal end of said suspension, said suspension having a longitudinal axis; and
 - a rotary load/unload arm having a rotation axis about which said rotary load/unload arm rotates, wherein said suspension is mounted to said rotary load/unload arm such that said rotary load/unload arm rotation axis intersects said suspension longitudinal axis and said slider is positioned adjacent said first plane at a separation distance from said first plane, said separation distance increasing as said rotary load/unload arm rotates about said rotation axis in a first direction and decreasing as said rotary load/unload arm rotates about said rotation axis in a second direction which is opposite said first direction.
44. A method for changing the distance between a surface of a disk and a slider attached to a distal end of a slider suspension having a longitudinal axis, said method comprising the steps of:
- mounting said slider suspension on a rotary load/unload arm having a rotation axis such that said slider suspension longitudinal axis intersects said

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rotary load/unload arm rotation axis; and

rotating said rotary load/unload arm about said rotation axis thereby changing the distance between said surface of said disk and said slider.

45. A slider positioning apparatus for positioning a slider (12) relative to a surface of a disk (10) wherein the slider (12) is attached to a suspension member (13) near a distal end of a longitudinal axis of the suspension member, said apparatus comprising:

a rotary load/unload arm (17) having a rotation axis about which said rotary load/unload arm rotates, wherein the suspension member (13) is attached to said rotary load/unload arm (17) such that the suspension member (13) longitudinal axis intersects said rotary load/unload arm (17) rotation axis.

46. An apparatus for positioning a slider relative to a surface of a disk wherein the slider is attached to a suspension member having a longitudinal axis, said apparatus comprising:

a rotary arm having a rotation axis about which said rotary arm rotates, said rotary arm further comprising a portion configured for attachment of the slider suspension member thereto, wherein said rotary arm rotation axis intersects said slider member longitudinal axis such that rotation of said rotary arm in a first direction about said rotation axis moves said slider away from the surface of the disk and rotation of said rotary arm in a second direction about said rotation axis which is opposite said first direction, moves said slider toward the surface of the disk.

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