

ABSTRACT

Tracked system with variable geometry

A tracked system (10) with variable geometry
5 comprising: a track (11), which comprises a portion
(11p) having a respective first area (a1), the portion
(11p) being, in use, in contact with the ground or the
road surface; at least one driving wheel (12), which is
coupled to the track (11) and is suited to provide a
10 driving force for the rotation of the track (11); and at
least one driven wheel (13), which is coupled to the
track (11); the tracked system (10) comprises actuator
means (14), which are suited to vary the geometry of
part of the track (11); the actuator means (14)
15 comprising an intervention configuration, in which they
configure the portion (11p) of the track (11) on at
least one second area (a2) which, in use, is in contact
with the ground.

Figure 2