

Abstract

An information acquisition system, for acquiring information about possibility of interference between an external object and at least one of an attachment of a working machine and a suspended cargo suspended by the attachment, the working machine having a support unit and the attachment that is supported by the support unit for suspending the cargo, the system includes a first input acquisition unit that acquires masses of the attachment and the suspended cargo as first input, a second input acquisition unit that acquires information about a posture of the attachment as second input, a position estimation unit that estimates the position of at least one of the attachment and the suspended cargo, based on the first input and the second input, and an information derivation unit that derives information about the possibility of interference between the external object and at least one of the attachment and the suspended cargo, based on the position of at least one of the attachment and the suspended cargo estimated by the position estimation unit.