



- (51) **International Patent Classification:**
Not classified
- (21) **International Application Number:**
PCT/SG2022/050851
- (22) **International Filing Date:**
23 November 2022 (23.11.2022)
- (25) **Filing Language:** English
- (26) **Publication Language:** English
- (30) **Priority Data:**
10202113273Q 29 November 2021 (29.11.2021) SG
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- (81) **Designated States** (*unless otherwise indicated, for every kind of national protection available*): AE, AG, AL, AM, AO, AT, AU, AZ, BA, BB, BG, BH, BN, BR, BW, BY, BZ,

(54) **Title:** METHOD AND SYSTEM FOR DETECTING A LANE

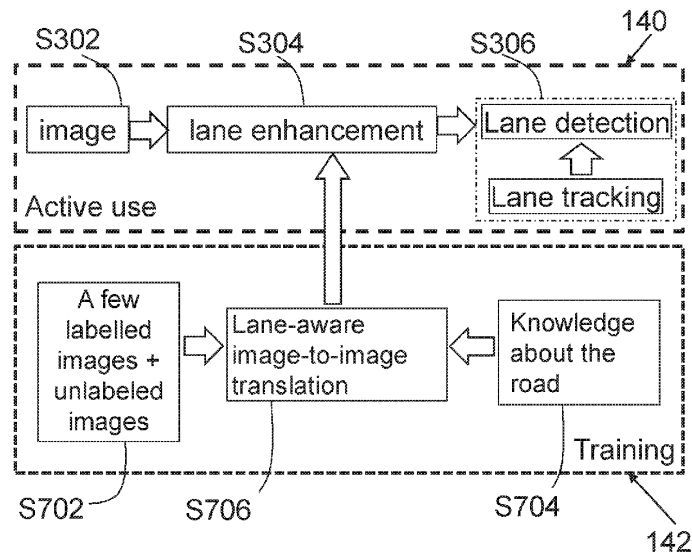


Fig. 7

(57) **Abstract:** Method and system for detecting a lane are provided herein. In an embodiment, the method comprises: receiving one or more source detecting images captured by an image capturing device (102) at step S302, the or each of the source detecting images including a source road region having lane features; generating a translated source image corresponding to each of the one or more source detecting images by using a lane feature enhancement module (122) at step S304, with the lane features of the source road region being enhanced in the translated source image; and detecting the lane from the translated source image at S306; wherein the lane feature enhancement module (122) is trained by a plurality of training images and comprises a generator network, to: identify a road region (136) of a corresponding training image of the plurality of training images, translate the road region (136) of the corresponding training image to a translated road region to minimize a loss function that quantifies a dissimilarity between the road region (136) and the translated

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TJ, TM, TN, TR, TT, TZ, UA, UG, US, UZ, VC, VN, WS,
ZA, ZM, ZW.

(84) Designated States (*unless otherwise indicated, for every kind of regional protection available*): ARIPO (BW, CV, GH, GM, KE, LR, LS, MW, MZ, NA, RW, SD, SL, ST, SZ, TZ, UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, RU, TJ, TM), European (AL, AT, BE, BG, CH, CY, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HR, HU, IE, IS, IT, LT, LU, LV, MC, ME, MK, MT, NL, NO, PL, PT, RO, RS, SE, SI, SK, SM, TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, KM, ML, MR, NE, SN, TD, TG).

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road region to generate the translated source image. A method of training the lane feature enhancement module (122) is also disclosed.