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(71) Applicant: **UNIVERSAL CITY STUDIOS LLC**
[US/US]; 100 Universal City Plaza, Universal City, California 91608 (US).

(72) Inventors: **JEROMIN, Aaron Chandler**; 1000 Universal Studios Plaza, Orlando, Florida 32819 (US). **LAYFIELD, Christopher David**; 1000 Universal Studios Plaza, Orlando, Florida 32819 (US).

(74) Agent: **POWELL, W. Allen** et al.; P.O. Box 692289, Houston, Texas 77269 (US).

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(54) Title: CALIBRATION SYSTEMS AND METHODS FOR DYNAMIC PROJECTION MAPPING

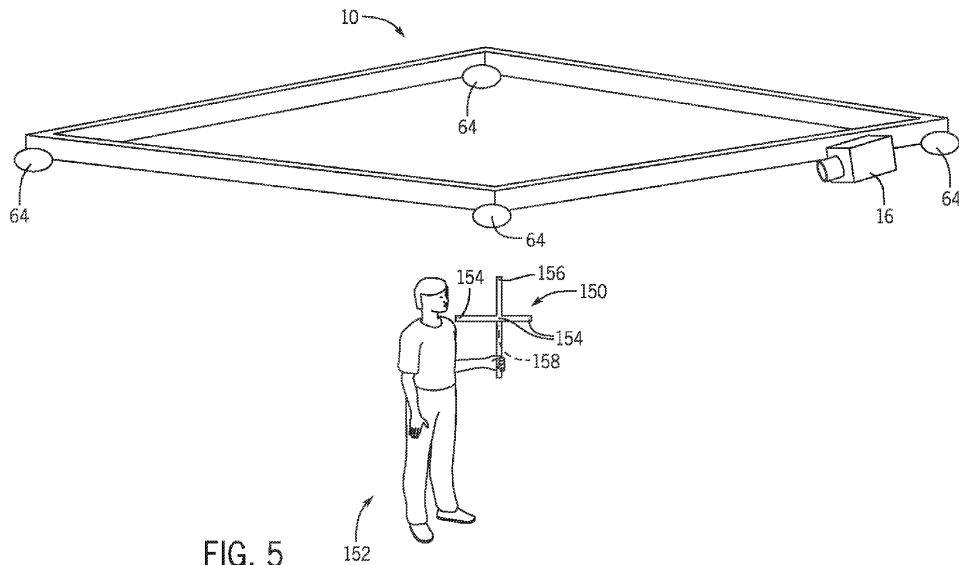


FIG. 5

(57) Abstract: A calibration tool for a dynamic projection mapping system includes a rigid body, a row of at least three light emitters disposed on the rigid body, and an additional light emitter disposed on the rigid body and offset from the row of the at least three light emitters. The calibration tool also includes a sensor disposed on the rigid body and configured to detect projected light.

[Continued on next page]

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