

Abstract

1. Method and device for control.

2.1 It is the object of the present invention to realize a control which enables a correction of various disturbance variables and needs a low memory requirement for correction variables.

2.2 According to the invention, a control actuating signal is determined in a control mode and, during an operating mode, an actuating signal, which is formed by superimposing previously determined correction signals on the control actuating signal, is determined for driving actuating means.

2.3 The invention can be used, for example, for convergence correction.

3. Figure 1.

