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(71) Applicant: CURIUM PTE. LTD. [SG/SG]; 12 Lorong Sarina, #04-01 The Vines, Singapore 416736 (SG).

(72) Inventors: HASNAIN, Ali; 10, Mill Creek, Lorong, Marzuki, #01-02, Singapore 417052 (SG). BUYUKBURC, Kutluhan; 24A Jalan Belangkas, Singapore 369388 (SG). RAVINDRANATH, Pradeep Anand; 222 Jln Eunoss, #04-103, Singapore 415871 (SG).

(74) Agent: SPRUSON & FERGUSON (ASIA) PTE LTD; P.O. Box 1531, Robinson Road Post Office, Singapore 903031 (SG).

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(54) Title: METHOD, SYSTEM AND COMPUTER READABLE MEDIUM FOR CALIBRATION OF COOPERATIVE SENSORS

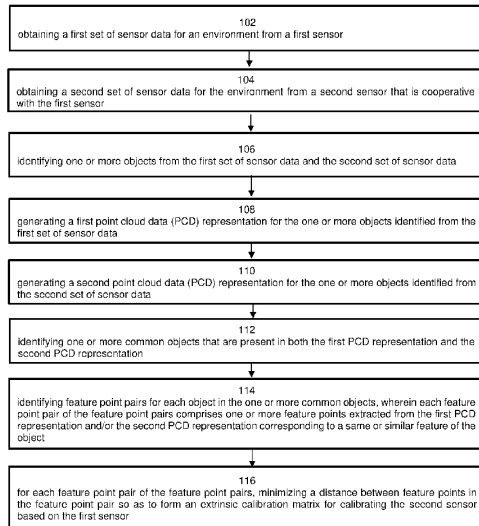


FIG. 1B

(57) Abstract: The present application provides methods, systems and computer readable media for calibration of cooperative sensors. In an embodiment, there is provided a method for calibration of cooperative sensors. The method comprises: obtaining a first set of sensor data for an environment from a first sensor; obtaining a second set of sensor data for the environment from a second sensor that is cooperative with the first sensor; identifying one or more objects from the first set of sensor data and the second set of sensor data; generating a first point cloud data (PCD) representation for the one or more objects identified from the first set of sensor data; generating a second point cloud data (PCD) representation for the one or more objects identified from the second set of sensor data; identifying one or more common objects that are present in both the first PCD representation and the second PCD representation; identifying feature point pairs for each object in the one or more common objects, wherein each feature point pair of the feature point pairs comprises one or more feature points extracted from the first PCD representation and/or the second PCD representation corresponding to a same or similar feature of the object; and for each feature point pair of the feature point pairs, minimizing a distance between feature points in the feature point pair so as to form an extrinsic calibration matrix for calibrating the second sensor based on the first sensor.

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