

Abstract

5

The invention relates to, amongst other things, a mobile robot (1) comprising a mobile base element (6) and at least one multi-jointed manipulator (10), wherein the robot (1) comprises
10 several telemedical devices (2,3,4,5). The invention also relates to a robot for performing a movement sequence together with a limb of a human with the help of a manipulator (22).

(Fig. 1)