Claims

1. A care robot comprising:

a base; and

a pair of underarm holding sections provided on the base and configured to each hold under both arms of a care receiver;

wherein

the care robot is configured to assist the care receiver to stand up or sit down, and

the pair of underarm holding sections are each configured to be swingable in different directions around a fulcrum provided further away from the care receiver than at least a portion that supports the underarm of the care receiver such that the distance between the pair of underarm holding sections changes.

2. The care robot according to claim 1, wherein

the portion that holds the underarm includes an underarm support section configured to support the underarm of the care receiver from below, and an upright section that raises up from the underarm holding section, and

the pair of underarm holding sections swings such that a pair of the upright sections is expandable to a position further to the outside than a shoulder width of the care receiver.

3. The care robot according to claim 1 or 2, wherein

a pair of grips configured to be held by both hands of the care receiver so as to insert the pair of underarm holding sections under both arms are each provided on the base further away from the care receiver than the pair of underarm holding sections,

such that,

when the pair of underarm holding sections are swung around the fulcrum in an opening direction, an arm-passing region is maintained between the care receiver and the pair of grips.

4. The care robot according to any one of the claims 1 to 3, wherein

an elastic member configured to bias each of the pair of underarm holding sections in a closing direction that decreases the distance between the pair of underarm holding sections is provided on the pair of underarm holding sections.

5. The care robot according to claim 4, wherein

an engaging stopping member configured to temporarily stop the pair of underarm holding sections against the biasing force of the elastic member when the underarm holding sections are swung in an opening direction is provided on the pair of underarm holding sections.

6. The care robot according to any one of the claims 1 to 3, wherein

an elastic member configured to bias each of the pair of underarm holding sections in an opening direction that increases the distance between the pair of underarm holding sections is provided on the pair of underarm holding sections.

7. The care robot according to any one of the claims 1 to 6, wherein

a swing pin acting as the fulcrum, and an elongated hole configured to guide the swinging of a guide pin that is inserted into the elongated hole are provided on the underarm holding sections.