

## **FIGURE, BASE, AND FIGURE SYSTEM**

### **ABSTRACT**

5 [Summary]

[Object] To provide a figure that makes it possible to achieve a wide variety of motions while ensuring aesthetic appearance.

[Solution] A figure system includes a drive unit DU including a plurality of first actuators (servomotors SM), and a figure 2 including a plurality of joints. The joints each have one or  
10 more axial joint mechanisms. Drive force derived from at least one of the first actuators is transmitted to corresponding at least one of the axial joint mechanisms through a wire 4.

[Selected Drawing] FIG. 1

