

ENERGIZING A COIL OF A SOLENOID OF A DIRECTIONAL CONTROL VALVE

Field of the Invention

The present invention relates to energizing a coil of a solenoid of a directional control valve.

Background of the Invention

Well production fluid control valves in subsea hydrocarbon production control systems are typically operated by hydraulic actuators. The control of the hydraulic fluid to the valve actuator is typically effected by a directional control valve (DCV), which is a small hydraulic valve, operated by the armature of an electrically operated solenoid. Well complex control systems have a substantial number of DCVs, each requiring electrical power, typically derived from a surface power source via an umbilical. In order to minimise the cost of the umbilical, minimising the power consumption of the complex is important. The electrical power supplied to DCVs in current systems is intentionally more than enough to operate the DCVs and hold them in their operational positions, mainly as an insurance that the valve will perform reliably. However this results in a considerable waste of power. This invention minimises this waste and has the added advantage of reducing thermal stress in the control system due to the reduced power consumption.

Known forms of monitoring or testing a solenoid are described in EP-A-2 053 289; US-A-6 917 203; GB-A-2 110 373; US-A-5 153 522; US-A-5 796 201; US-A-6 211 665; US-A-6 326 898; US 2006/0285265; US-A-5 245 501; DE-A-3 624 231; and US-A-5 241 218.

Summary of the Invention

According to the present invention from one aspect, there is provided a method of energizing a coil of a solenoid of a directional control valve, the method comprising energizing the coil with a voltage, controlling said voltage and detecting the current in the coil at which an armature of the solenoid moves between a first position in which the solenoid is operated and a second position in which the solenoid is not operated

and using that current increased by a margin as an operating current for energizing the coil of the solenoid.

According to the present invention from another aspect, there is provided an arrangement for energizing a coil of a solenoid of a directional control valve, the arrangement comprising means for energizing the coil with a voltage, and control means for controlling said voltage and detecting the current in the coil at which an armature of the solenoid moves between a first position in which the solenoid is operated and a second position in which the solenoid is not operated and using that current increased by a margin as an operating current for energizing the coil of the solenoid.

Said voltage could be controlled by: increasing it; detecting when the armature moves from said second to said first position; decreasing the voltage and detecting when the armature moves from said first to said second position; increasing the voltage and detecting when the armature moves from said second to said first position; and decreasing the voltage to a level at which the current through the coil is said operating current. In this case, said voltage could be increased to a maximum voltage after it has been detected that the armature has moved from said second to said first position and before it is decreased.

Preferably, movement of the armature is detected by detecting a perturbation in the current through the coil due to a change in the inductance of the coil due to such movement.

Preferably, said voltage is controlled by pulse width modulation of voltage applied by drive circuitry for the solenoid.

The directional control valve could be a directional control valve of a subsea hydrocarbon production control system. In this case, said voltage could be controlled by processor means in a subsea electronics module of a subsea control module.

Brief Description of the Drawings

Fig. 1a is a block diagram showing items for energizing the coil of a DCV solenoid;

Fig. 1b is a block diagram showing items for energizing the coil of a DCV solenoid in an embodiment of the invention;

Fig. 2 shows voltage and current waveforms occurring in operation of the embodiment; and

Fig. 3 is a schematic view of a subsea hydrocarbon production control system incorporating the invention.

Description of an Embodiment of the Invention

Fig. 1a illustrates an arrangement for the operation and control of a DCV in the production control system of a subsea hydrocarbon well. The well control system may include a number of processors, typically housed in a subsea electronics module (SEM), at least one of which will control all of the DCVs on the well, which are housed, along with the SEM, in a subsea control module (SCM) mounted on a well tree. Typically, a DCV is operated by energizing the coil of its solenoid 1 from a DC power supply switched on by a power driver 2 from a control signal (on/off) from a processor 3.

As shown in Fig. 1b for an embodiment of this invention, the arrangement of Fig. 1a is supplemented with current sensing circuitry in the form of a current sensor 4, there being modified software in the processor 3 which controls the power driver 2 by pulse width modulation (PWM) to provide a variable output to the solenoid coil to replace the simple on/off control of power driver 2 of Fig. 1a. The power driver 2 is typically a simple transistor, but instead of simply turning it off and on to operate the solenoid, the processor produces a pulse width modulation control on a line 5 to provide the variable voltage required for the embodiment of this invention.

Fig. 2 shows how the current in the coil of the DCV solenoid (lower graph) is varied by changing the applied voltage (upper graph) by PWM under the control of the modified software in the processor 3, to achieve optimum power saving for holding the DCV operated by determining a minimum “hold-in” current for that purpose. The mode of operation, controlled by the software in the processor 3, is as follows.

When the DCV is required to operate, the full operating voltage 6 is applied to the solenoid coil, resulting in an exponential rise of current, because of the inductance of the coil up to the maximum 7, as determined by the resistance of the coil. During the rise of current, the solenoid operates the DCV (its solenoid moving from a first position in which the solenoid is not operated to a second position in which the solenoid is operated) resulting in a perturbation 8 in the current, due to the change of inductance of the solenoid coil when its armature moves. When the maximum current 7 is reached and the processor 3 knows that the solenoid has operated, that is from the current perturbation 8 and the current, both of which were sensed by the current sensor 4 of Fig. 1b, the voltage and therefore the current is reduced until the armature moves from the second to the first position and the solenoid ‘drops out’, resulting in another current perturbation 9, which is sensed and fed to the processor which records the value of the current at that point. By adding a small increase or “margin” to the recorded at drop out current, a minimum current required for holding the solenoid operated is established and recorded by the processor 3. This “margin” is established by experimental testing of DCV solenoid characteristics under environmental conditions expected in service and programmed into the processor 3. When the drop out current has been detected by the processor, full voltage is applied again to the solenoid coil, resulting in a current perturbation 10 when the solenoid operates, which is detected by the processor (which is thus assured that the solenoid has operated again), the processor then reducing the current in the solenoid coil to the value previously established as the minimum “hold in” current 11.

Thus, substantial power saving is achieved, since the minimum “hold in” current is typically 70% less than the normal current at full voltage. The use of PWM of voltage as a method of current control is not essential, but generally more power efficient than analogue power control such as simple series transistor circuits with an analogue output from the processor, and is also easier to generate from a processor, since it is inherently digital

Referring to Fig. 3, this shows schematically a subsea hydrocarbon production control system incorporating the invention. In a subsea control module (SCM) 12 there is a subsea electronics module (SEM) 13 and a hydraulic control module (HCM) 14. The SCM 12 is fed by an umbilical 15 from a topside master control station (MCS) 16, e.g. at a surface platform, with electric power, control signals and hydraulic power.

The control signals are processed by the SEM 13 which then controls solenoid operated, hydraulic directional control valves (DCVs) D1 - Dn in the HCM 14 which in turn operate a multiplicity of hydraulic devices such as actuators for controlling a subsea hydrocarbon production well. The subsea control system is located at a well tree, the SCM 12 being connected to the umbilical 15 via a distribution unit 17 which provides the electric power and control signals to the SEM 13 via a cable 18 and hydraulic power to the HCM 14 via a feed 19. The SEM 13 controls the DCVs D1 – Dn in the HCM 14 via a cable 20.

In accordance with the invention, the SEM 13 includes a processor 3 for determining minimum “hold-in” currents for the DCVs D1 – Dn, current sensors 4 and drivers 2 having been omitted for clarity.

Advantages of using the Invention

Power saving with operated solenoids is normally achieved by inserting a resistor in series with the solenoid coil with a pair of contacts shorting the resistor, which are opened by the solenoid when it is energised. Thus the solenoid is energised with full voltage and current and then the current reduced to a level greater than the “drop out” current thus saving power. However, solenoid operated DCVs on subsea wells have to be highly reliable and the inherent problem with using a shorted resistor method of power saving is that a failure of the contact would leave the resistor in the solenoid circuit and there would then be insufficient voltage and current to operate the solenoid initially. Thus, this simple technique is not considered reliable enough to be employed on subsea well DCVs. A method of this invention can use existing hardware with software to effect the function with only a small highly reliable solid state current sensing device addition, and saving typically 70% of the power requirements of the multiplicity of DCVs on a typical well

WHAT IS CLAIMED IS:

1. A method of energizing a coil of a solenoid of a directional control valve, the method comprising energizing the coil with a voltage, controlling said voltage and detecting the current in the coil at which an armature of the solenoid moves between a first position in which the solenoid is operated and a second position in which the solenoid is not operated and using that current increased by a margin as an operating current for energizing the coil of the solenoid.
2. A method according to claim 1, wherein said voltage is controlled by: increasing it; detecting when the armature moves from said second to said first position; decreasing the voltage and detecting when the armature moves from said first to said second position; increasing the voltage and detecting when the armature moves from said second to said first position; and decreasing the voltage to a level at which the current through the coil is said operating current.
3. A method according to claim 2, wherein said voltage is increased to a maximum voltage after it has been detected that the armature has moved from said second to said first position and before it is decreased.
4. A method according to any preceding claim, wherein movement of the armature is detected by detecting a perturbation in the current through the coil due to a change in the inductance of the coil due to such movement.
5. A method according to any preceding claim, wherein said voltage is controlled by pulse width modulation of voltage applied by drive circuitry for the solenoid.
6. A method according to any preceding claim, wherein the directional control valve is a directional control valve of a subsea hydrocarbon production control system.
7. A method according to claim 6, wherein said voltage is controlled by processor means in a subsea electronics module of a subsea control module.

8. An arrangement for energizing a coil of a solenoid of a directional control valve, the arrangement comprising means for energizing the coil with a voltage, and control means for controlling said voltage and detecting the current in the coil at which an armature of the solenoid moves between a first position in which the solenoid is operated and a second position in which the solenoid is not operated and using that current increased by a margin as an operating current for energizing the coil of the solenoid.

9. An arrangement according to claim 8, wherein said control means is adapted to: increase said voltage; detect when the armature moves from said second to said first position; decrease the voltage and detect when the armature moves from said first to said second position; increase the voltage and detect when the armature moves from said second to said first position; and decrease the voltage to a level at which the current through the coil is said operating current.

10. An arrangement according to claim 9, wherein said control means is adapted to increase said voltage to a maximum voltage after it has been detected that the armature has moved from said second to said first position and before it is decreased.

11. An arrangement according to any of claims 8 to 10, wherein said control means is such that movement of the armature is detected by detecting a perturbation in the current through the coil due to a change in the inductance of the coil due to such movement.

12. An arrangement according to claims 8 to 11, wherein the control means is adapted to control said voltage by pulse width modulation of voltage applied by drive circuitry for the solenoid.

13. An arrangement according to any of claims 8 to 12, wherein the directional control valve is a directional control valve of a subsea hydrocarbon production control system.

14. An arrangement according to claim 13, wherein said control means includes processor means in a subsea electronics module of a subsea control module.