

DEVICE AND METHOD FOR DETECTING THE POSITION OF A LASER BEAM

Description

Field of the invention

5 The present invention relates to the field of additive manufacturing and, more specifically, a device and a method for detecting the position of a laser beam.

Prior art

10 Nowadays, additive manufacturing is considered as an industrial production technology. In this respect, additive manufacturing is used in numerous industrial sectors such as the aeronautic or medical sectors, which belong to demanding fields. Thus, it is necessary to produce parts of very high quality for the final client. Consequently, any drift in the manufacturing method must be identified rapidly. In addition, the final client is often interested in the manufacturing history of the part,
15 which makes it possible to ensure traceability of the manufacturing method.

20 In the prior art, the method for depositing material under concentrated energy is based on the principle of depositing metal powders in the molten state on a solid substrate.

25 Indeed, the initial principle consists in using a tool for sending metal powder in solid form, with a defined particle size, typically of the order of 45 to 90 μm , into a power beam such as a laser beam or an electron beam. On traversing the laser beam, the powder is heated and melts, and immediately reaches the substrate in the molten state to form a layer. The tool being displaced, it is thus possible to create metal beads on the substrate. The layers are next superimposed in such a way as to create volume parts. Metal powder is the basis of any construction carried out using additive manufacturing by means of this method and, consequently, proper management of the powder jet and the tool enabling its shaping, that is to say the nozzle, is indispensable.

30 The powder, of very fine particle size, is sent in the form of a jet composed: of a transport gas (called carrier gas), and particles of metal powder. This jet makes it possible to carry the powder up to the laser beam. The flow rate of gas is expressed in litres/minutes and the flow rate of powder in grammes/minutes.
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The powder jet comes from a powder distributor and travels in a tube up to the depositing tool, as near as possible to the laser beam, into which it is injected. The mechanical element through which the powder jet exits is called a nozzle. The metal powder is deposited on the substrate, several millimetres distant from the nozzle. The latter has the role of guiding in a properly managed manner the powder jet comprising the carrier gas in order that said powder jet reaches the laser beam in an optimal manner. The nozzle is composed of several mechanical parts, of which concentric cones, which have the aim of guiding the powder. The guiding of the powder jet depends on two cones: the outer cone and the intermediate cone.

The powder is thus directed into the laser beam by a jet of annular conical shape. It is as though "focused" in the laser beam, which must lie at the centre of this conical jet.

However, it is difficult to manage the position of the laser beam correctly in space in so far as the laser beam is immaterial.

Solutions exist making it possible to carry out the detection of the position of the laser beam. However, these solutions are only valid for low power laser beams.

It proves necessary to propose a detection device and method that overcomes the aforementioned drawbacks. Notably, it proves necessary to propose a device and a method for detecting the position of the laser beam which make it possible to obtain the position of the laser beam with respect to a known position and to do so for high powers of laser beam.

Summary of the invention

According to a first aspect, the object of the invention relates to a device for detecting the position of a laser beam with a determined diameter and emitted by a laser of an additive manufacturing machine, said detection device comprising an upper part comprising a scanning zone (108) of the laser beam, said scanning zone comprising at the centre thereof a circular hole of diameter essentially equal to the diameter of the laser beam and with a determined position;

the detection device comprising a lower part, the lower part comprising at least one sensor for capturing a part of the energy transmitted by the laser beam;

such that when the laser beam scans the scanning zone according to a plurality of positions, the sensor captures a part of the energy transmitted by the laser beam for

each position, the part of the transmitted energy being maximum when the laser beam is aligned with the circular hole.

5 In a preferred manner, the scanning zone is situated below a circular central opening in an upper surface of the upper part.

In a preferred manner, the lower part comprises a graphite martyr plate to absorb the remaining part of the energy transmitted by the laser beam.

10 In a preferred manner, the sensor comprises one photodiode.

In a preferred manner, the sensor comprises three photodiodes.

15 In a preferred manner, the upper part comprises a first and a second element.

In a preferred manner, the first element comprises vents.

In a preferred manner, the second element comprises the circular hole.

20 In a preferred manner, the first and the second element are configured such that the reflections of the laser beam between the first and the second element are infinite to dissipate the energy of the laser beam.

25 According to a second aspect, the object of the invention relates to a method for detecting the position of a laser beam emitted by a laser of an additive manufacturing machine comprising the following steps:

- emission of a laser beam with a determined diameter;
- scanning of the laser beam over an entire determined scanning zone comprising a circular hole of diameter essentially equal to the diameter of the laser beam and with a determined position, said scanning comprising a plurality of positions of the laser beam;
- detection of a part of the energy transmitted by the laser beam for each position of the laser beam during the scanning;
- emission of an electrical signal corresponding to the quantity of energy detected for each position of the laser beam during the scanning;
- determination of the maximum electrical signal value;

- search for the time t corresponding to the position of the manufacturing head for the maximum electrical signal value;
- determination of the position of the laser beam.

5 Brief description of the drawings

The aim, objects and characteristics of the invention will become clearer on reading the description that follows made with reference to the drawings in which:

- figure 1 shows according to an exploded view a deposition nozzle according to the prior art,
- 10 - figure 2 shows according to a sectional view and schematically the deposition nozzle of figure 1, in the absence of the nozzle body and in the presence of the carrier gas and the secondary gas,
- figure 3 shows according to a perspective view the device for detecting the laser beam, according to an embodiment of the invention,
- 15 - figure 4 shows according to a perspective view the upper part of the device for detecting the laser beam according to figure 3,
- figure 5 shows the first element of the device for detecting the laser beam according to figure 4,
- figure 6 shows the second element of the device for detecting the laser beam
- 20 according to figure 4,
- figure 7 shows according to a partial sectional view the device for detecting the laser beam according to figure 4,
- figure 8 shows schematically and according to a sectional view the device for detecting the laser beam according to an embodiment of the invention,
- 25 - figure 9a shows schematically a cone centring device, according to an embodiment of the invention,
- figure 9b shows an image of underneath the deposition nozzle,
- figure 9c shows a diagram of the image of figure 9b,
- figure 10a shows according to a perspective view the cone centring device
- 30 according to an embodiment of the invention,
- figure 10b shows according to a partial sectional view the cone centring device according to figure 10a,
- figure 11 represents according to a perspective view a powder jet analysis system according to an embodiment of the invention,

- figure 12 represents according to another perspective view a powder jet analysis system in the absence of the weighing device, according to an embodiment of the invention,
- 5 - figure 13 represents schematically according to a perspective view a separating element and the deposition nozzle containing four portions, according to an embodiment of the invention,
- figure 14 represents according to a perspective view a separating element containing six portions, according to another embodiment of the invention,
- 10 - figure 15 represents according to a sectional view a separation device according to an embodiment of the invention,
- figure 16 shows according to a perspective view the separation device of figure 5,
- figure 17 shows schematically a sectional view of a separation device according to an embodiment of the invention,
- 15 - figure 18 shows according to a perspective view an opening system according to an embodiment of the invention,
- figure 19 shows according to an exploded view a part of the opening system according to an embodiment of the invention,
- figure 20 shows according to a partial sectional view the interaction between the valves and the opening device according to an embodiment of the invention,
- 20 - figure 21 shows according to a perspective view a funnel according to an embodiment of the invention,
- figure 22 shows according to a perspective view a suction device according to an embodiment of the invention,
- 25 - figures 23a, 23b and 23c represent according to a front view a separating element comprising two portions and located respectively at three different heights according to an embodiment of the invention.

30 Detailed description of an embodiment

The present invention relates to the DED (Directed Energy Deposition) method, an additive manufacturing method which notably consists in constructing a dense part on a substrate, layer after layer, by the fusion of metal powders injected through a laser beam. This method is applied by means of a machine comprising a nozzle 10 or deposition nozzle. Figure 1 shows an exploded view of a nozzle 10 comprising a nozzle body 12, a first cone or inner cone 14, a second cone or intermediate cone 16

and a third cone or outer cone 18. The first cone 14, the second cone 16 and the third cone 18 are made of copper and are arranged in a concentric manner.

5 A laser beam 15 is emitted by a laser. An optic fibre makes it possible to transport the laser beam up to an optical head (not shown) on which is fixed the nozzle 10. Next, the laser beam traverses the nozzle up to the substrate (not shown).

10 As shown in figure 2, schematically, the first cone 14 is traversed by the laser beam 15 and is not visible from the outside of the nozzle 10. The second cone 16 is traversed by a gas 17 called secondary gas such as argon enabling the shaping of the powder jet in order to focus the flow of powder. The end of the second cone is visible from the outside of the nozzle. The third cone 18 makes it possible to bring the powder to the level of the molten bath on the substrate by a carrier gas 21 such as argon.

15 Detection of the laser beam

Figure 3 shows a device 100 for detecting the laser beam 15 which comprises an upper part 102 and a lower part 103. The detection device 100 makes it possible to determine with precision the position of the laser beam with respect to said detection device 100.

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The upper part 102 shown in figure 4 comprises a first element 104 and a second element 106 fixed on a metal plate 99. The first and the second element 104, 106 are made of copper in order to avoid overheating the material during the emission of a laser beam on the detection device 100. Indeed, the copper material is of red colour, just like the laser beam. The copper thus operates as a mirror and absorbs very little energy. Consequently, the copper heats up very little compared to other materials.

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30 As shown in figure 5, the first element 104 is of circular shape with a defined height and comprises a circular central opening 107 in an upper surface 101 of the upper part 102. The first element 104 also comprises notches or vents 110. These notches 110 are each oriented at 45° with respect to the axis of the laser beam. Figure 5 shows two notches 110 intended to improve the cooling of the detection device 100. Indeed, when the laser beam scans the scanning zone or surface 108, described hereafter, of the detection device 100, the nozzle also emits a jet of secondary gas 17. Thanks to the vents 110, the secondary gas 17 can circulate freely between the conical surfaces then escape through the vents 110. The detection device 100 is then cooled

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by convection. The defined angle of 45° (degrees) makes it possible to avoid that reflections of the laser beam come out of the detection device 100 to damage the environment of said detection device 100.

5 The second element 106 is shown in figure 6 and comprises a circular shape of a defined thickness. At the centre of the second element 106 is found a point shaped surface 108 pierced by a circular opening or calibrated hole 111 of a diameter of around some 800 µm (micrometres) to 50 µm (micrometres). This diameter corresponds approximately to the diameter of the laser beam. The calibrated hole 111
10 is situated at the centre of the circular central opening 107.

The second element 106 also comprises a U-shaped cooling channel of which the inlet 62 and outlet 64 orifices for the cooling fluid, for example water, are visible in figures 4 and 6. Figure 4 also shows the rapid attachment piping connections 66.

15 As shown in the partial sectional view of figure 7, the shapes of the first and the second element 104, 106 are adapted so that the reflections of the laser beam are infinite between the two inner conical surfaces as shown in figure 7 with arrows. Thus, the energy of the laser beam is dissipated as it propagates, and harmful reflections on
20 the nozzle 10 are avoided. The surface 108 or scanning zone is also shown in figure 7.

As shown in figure 3, the detection device 100 also comprises a lower part 103 comprising three compartments 50 each comprising a sensor such as a photodiode 114 (not visible). Only two compartments 50 are shown in figure 3. The lower part 103
25 also comprises a receptacle 52 comprising an absorbing element such as a graphite martyr plate 54 (not visible) in the bottom of the receptacle 52. Thus, the laser beam passes through the calibrated hole 111 and strikes the graphite martyr plate 54. A part of the energy or residual energy is reflected by the graphite martyr plate 54. Figure 8 shows in a schematic diagram and according to a sectional view two photodiodes 114
30 located under the second element 106. The photodiodes 114 are arranged facing the graphite martyr plate 54 to be able to capture or detect or measure the residual energy of the laser beam 15 reflected by the graphite martyr plate 54. The model of each photodiode 114 is for example the PIN-5DPI of the Osi Optoelectronics brand. The photodiodes 114 are used for example in photovoltaic mode. The photodiodes 114
35 may also be used in blocking mode. Each photodiode 114 is coupled within an electronic circuit for example with a transimpedance amplification mounting in order to

amplify the weak current generated and to convert it into a voltage signal more easily readable by a micro-controller.

5 The laser beam 15 scans the scanning zone or surface 108, visible at the centre of the circular central opening 107 around the calibrated hole 111, and the calibrated hole 111 itself, making for example back and forth movements on this surface 108 in such a way as to scan the totality of the surface 108. When the laser beam is positioned exactly above and at the centre of the calibrated hole 111, the energy of the laser beam that reaches the graphite martyr plate is maximum. Thus, the aim of the
10 detection module is to seek the moment where the laser beam 15 and the calibrated hole 111 are perfectly aligned. In so far as the position of the calibrated hole 111 is known, it is possible to deduce therefrom the position of the laser beam 15. The residual energy of the laser beam 15 which is emitted by the graphite martyr plate 54 is measured by the photodiodes 114. When this energy is maximum, this signifies that
15 the laser beam 15 is aligned with the calibrated hole 111.

The device for detecting the laser beam 100 also comprises additional structural means. These additional structural means comprise, for example, a shoulder on the first element 104 enabling a short centring on a base plate 208 shown in figure 10a in
20 order to enable the putting in position of the device for detecting the laser beam 100 in an exact manner and to know the position of the calibrated hole 111 in a precise manner.

The device 100 for detecting the laser beam also comprises fixation means such
25 as spacers with screws and threadings in the base plate 208 to enable the detection device 100 to be maintained in position. The device 100 for detecting the laser beam must be positioned in a very precise manner in order to know the exact position of the calibrated hole 111 in order to deduce therefrom later the position of the laser beam when it is aligned with the calibrated hole 111.

30 During the use of the device 100 for detecting the laser beam 15, the detection method comprises the steps described hereafter. The nozzle 10 emits a laser beam of a power of around, for example, 200 to 300 W (Watts) or preferably 500 to 700 W (Watts) that covers the surface of the pierced point 108 visible through the circular
35 central opening 107 of the upper part 104. Thus, the scanning zone 108 is situated below the circular central opening 107. The laser beam 15 is going to scan the surface

108 while occupying several positions. When the laser beam 15 occupies positions situated outside the calibrated hole, the energy of the laser beam is diffused in the copper through infinite reflections visible by arrows in figure 7. The photodiodes then provide a zero signal. When the laser beam occupies positions situated above the hole in a non-centred manner, the energy of the laser beam is transmitted via the circular hole 111 to the graphite martyr plate 54. The photodiodes 114 capture a quantity of residual energy and then produce a non-zero electrical signal. When the laser beam passes totally above the calibrated hole 111 and is aligned with the calibrated hole 111, all of the energy of the laser beam passes through the calibrated hole 111 and touches the graphite martyr plate 54 which absorbs the major part thereof. The residual energy of the laser beam is measured by the photodiodes 114 then filtered by means of electronic circuits. In this situation, the residual energy captured by the photodiodes is maximum. For all of the positions occupied by the laser beam, an electrical signal having a Gaussian shape is produced. The position of the laser beam aligned with the calibrated hole 111 corresponds to the peak of the Gaussian. Next, the log of machine positions is used. This is a file provided by the additive manufacturing machine and which records the positions of the manufacturing head that emits the laser beam and thus the nozzle in order to know the exact position of said manufacturing head at a time t . This file generates an input around every 15 ms (milliseconds). Thus, the log of positions and the signal obtained by the photodiodes are synchronised or time matched to obtain the X and Y coordinates corresponding to the focal point, that is to say to the centre of the laser beam relative to the position of the device 100 for detecting the laser beam.

25 Thus, the method for detecting the position of the laser beam comprises the following steps for the nozzle 10 being displaced according to positions defined in a frame of reference (0,x,y) above the surface 108 containing the calibrated hole 111:

- emission of a laser beam with a determined power and scanning of the surface 108 that is to say around the calibrated hole 111 and in the calibrated hole 111 such that the energy of the laser beam is dissipated between the first and the second element 104, 106;
- measurement and filtering of the signal obtained by means of photodiodes 114 said signal representing the quantity of luminous energy of the laser that passes through the calibrated hole 111 and which is reflected by the graphite martyr plate 54;

- synchronisation over a time scale or time matching of the filtered electrical signal with the position data of the deposition nozzle 10 or the manufacturing head of the additive manufacturing machine;
- obtaining, in the frame of reference of the deposition nozzle 10 or the manufacturing head, the position for which the focal point of the laser beam is exactly above the calibrated hole and is thus aligned with the calibrated hole 111, that is to say for a maximum filtered electrical signal value.

Thus, the device 100 for detecting the laser beam 15 makes it possible to determine the position of the focal point of the laser beam 15 with a precision of the order of 50 μm (micrometres) for a laser beam power ranging from around 1 to 1000 W (Watts) or even above 1500 W.

Centring and state of the cones

Figure 9a shows schematically, and according to a schematic diagram, a cone centring device 200. The cone centring device 200 comprises a lighting device 202 and a camera 204.

The lighting device 202 illuminates according to the colour red. Indeed, the copper cones of the nozzle being of red colour, this illumination is the most suitable. The lighting device 202 comprises a luminous dome for example of the Effilux brand and for example of 100 mm (millimetres) diameter which comprises a hole on the lower surface of said dome.

The camera 204 is of very high definition and has a black and white sensor. Thus, the camera 204 is for example of Basler acA2440-20gm brand and has for example a resolution of 2448x2048. The focal length is 35 mm (millimetres) for example. The lens chosen is, for example, the Fujinon HF35HA1B.

As shown in figure 10a, the cone centring device 200 also comprises a support 206 for the camera 204.

The cone centring device 200 comprises a base plate 208 made of polycarbonate below which are situated the lighting device 202 and the camera 204. The base plate comprises three piercings or three holes in order to integrate the device 100 for detecting the laser beam, the cone centring device 200 and the powder jet analysis

system described hereafter. As shown in figure 10b, the camera 204 is protected, by a window 56 made of polycarbonate, from dust and residual powder which could be introduced into the cone centring device 200 through the hole at the bottom of the lighting device 202.

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During the use of the cone centring device 200, the centre of the laser beam, such as measured with the device for detecting the laser beam, must be aligned with a known frame of reference of the camera 204, for example the centre of an image taken by the camera 204 as shown in figure 9b.

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All of the calculation steps carried out within the context of the operation of the cone centring device 200 are performed by industrial viewing software. The camera acquires images relative to the end of the nozzle and which correspond to the concentric circles shown in figure 9c.

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The cone centring method 200 firstly comprises a step of calculating the centres associated with the different visible diameters of the outer 18 and intermediate 16 cones shown in figure 9c. Next, the method comprises a step of calculating the offset along the horizontal axis OX and the vertical axis OY of the laser beam as well as that of the different centres of circles corresponding to the cones and calculated in the preceding step.

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If these parameters have correct values compared to determined reference values, the method continues with the following steps. The method thus comprises a step of calculating the inner and outer diameters of the different inner and intermediate cones by the least squares technique. The maximum allowed misalignment around the laser beam is of the order of 50 μm (micrometres). Then, the method comprises a step of detecting and measuring deformation, obstruction, lack of material type defects on the two visible cones by means of image recognition software.

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If a defect is detected by means of image recognition software, the method continues with an intervention of the user to carry out the necessary operation on the nozzle such as the realignment or the cleaning of the cones, or the complete change of the cones if they are damaged.

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If no defect is detected, the method continues with a step of saving the measured data in a database.

Thus, the cone centring method comprises the following steps:

- 5 - placement of the laser beam with a position measured with the module for detecting the laser beam in the defined frame of reference, that is to say the centre of the image taken by the camera
- launching the image acquisition
- detecting the presence of defects on the cones and intervention of the user for a change of cones if necessary
- 10 - measuring the diameters of the outer and intermediate cones
- comparing with reference values and intervention of the user for a change of cones if necessary
- calculating the centres associated with said diameters
- 15 - calculating the offset along the horizontal axis OX and along the vertical axis OY of the cones with respect to the laser beam, that is to say with respect to the centre of the camera
- depending on the results, intervention of the user on the nozzle for a realignment of the cones.

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Thus, the cone centring device 200 makes it possible to verify that the cones are concentric around the laser beam, but also that they are in good condition that is to say round and clean. The cone centring device 200 also makes it possible to retain a history of the state of the cones as manufacturing proceeds.

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Analysis of the powder jet

Figures 11 and 12 show a powder jet analysis system 310 according to the invention. The analysis system 310 comprises a separation device 312, an opening device 314, a weighing device or balance 316 and a suction device 348.

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The analysis system according to the invention is suited to operating with the device 100 for detecting the laser beam and the cone centring device 200.

35 The analysis system 310 according to the invention is also suited to operating with a deposition nozzle integrated in an additive manufacturing machine such as known in the prior art and shown in figures 2 and 13. The deposition nozzle 10 notably

comprises the intermediate cone 16 and the outer cone 18. The powder jet 21 contains metal powder and a carrier gas. The powder jet 21 takes the form of a jet through intermediate 16 and outer 18 cones. In the context of the present invention, the initial or incident powder jet 21 has a diameter at the cone outlet of around 10 mm and a
 5 focal distance from the outlet of the outer cone of around 5 mm.

As shown in figure 13, according to a schematic diagram, the separation device 312 comprises a separating element 326 provided with a circular lateral wall 328 which defines a cylinder. The diameter of the separating element 326 is of the order of
 10 several centimetres. The separating element 326 comprises one or more separation walls 330 which are arranged in a symmetrical manner with respect to the central axis of symmetry of the cylinder. The separation walls 330 thus divide the inner volume of the separating element 326 into a number of portions or honeycombs each having the same volume. In figure 13, the four separation walls 330 divide the volume of the
 15 separating element 326 into four portions of equal volume. The number of separation walls 330 can vary to obtain a number of portions of equal volume comprised between 2 and 10 for example. The presence of a large number of portions of equal volume makes it possible to better verify the homogeneity of the powder jet. The length of a separation wall may be the length of the radius of the separating element or the length
 20 of the diameter of the separating element.

As shown in figure 14, according to another alternative, the separating element 327 may contain six separation walls to obtain six portions of equal volume. The thickness of the separation walls 330 must be as small as possible, and is of the order
 25 of 0.1 mm for example, in order to disrupt as little as possible the flow of the powder jet 21 and to achieve a clear separation of the powder jet.

The separating element 326, 327 may be made of metal to be able to withstand erosion by the powder jet. The separating element 326 may be produced by SLM
 30 (Selective Laser Melting) additive manufacturing using for example a 316L stainless steel or a tool steel of H13 type (X40CrMoV5-1). The diameter of the separating element 326, 327 is around 3 cm (centimetres).

Thus, as shown in figure 13, the initial powder jet 21 that falls on the separating
 35 element 326 is divided through the portions of said separating element. The separating element 326 of figure 13 makes it possible to divide or separate the powder jet into four

portions of powder jet and the separating element 327 of figure 14 makes it possible to divide or separate the powder jet into six portions of powder jet.

5 The separation device 312 comprises means for detecting the quantity of powder in each portion of powder jet. These means comprise on the one hand an expansion chamber 332 described below and a storage chamber 340 described below.

10 Thus, as shown in figure 15, the separation device 312 also comprises a first receptacle or expansion chamber 332 having a cylindrical end. Indeed, the first receptacle 332 is a zone intended to serve as expansion chamber for the carrier gas contained in the powder jet 21 and allows it to escape through a circumferential chicane 336 as shown by the arrows 338 while enabling the powder to flow into the second receptacle 340.

15 The second receptacle or storage chamber 340 shown in figure 15 comprises storage tubes 342 for storing the powder that has flowed. The storage chamber 340 has a linear end 20 enabling the fixation of the opening device described hereafter as shown in figure 16.

20 Figure 16 shows a perspective view of the separation device 312 of figure 15.

The structure formed by the separating element 327, that is to say by the circular lateral wall 328 and the separation walls 330, as well as the expansion chamber 332 form conduits where the portions of powder jet flow, each portion of powder jet flowing in a determined respective conduit 30. The storage tubes 342 form the end of the conduits.

25 Each storage tube 342 comprises a valve 344 to make it possible to open and to close each conduit. The opening and closing movement of the valves 344 is represented in figure 17, according to a schematic diagram, by two-directional arrows 346. Each valve 344 comprises a return spring 60.

The valves 344 operate with an opening device 314.

35 The valve opening device 314 is automated by means of adjustable cams for example as shown in figure 18. Each valve 344 may thus be controlled independently of each other. The number of cams is equal to the number of valves, itself equal to the

number of portions of the separating element 327. Indeed, as shown in figure 19, the opening device 314 comprises six cams 315 mounted in abutment against the shoulder on an axle 317 with heptagonal section, spaced apart by spacers and blocked by an elastic ring 323. The cam 315 situated at the end of the axle 317 comprises a magnet
5 321. The axle 317 is mounted on PTFE (polytetrafluoroethylene) bearings and is driven by a motor with a pulley and belt system having a reduction ratio of two to reduce the speed of rotation as much as possible. The opening device 314 comprises a sensor with flexible blade or with reed effect which is positioned laterally in order to detect the instant where the cam situated at the end of the axle 317 passes in front of the reed
10 sensor. Figure 20 shows a sectional view of the opening device 314 with the valves 344. As shown in figure 20, a funnel 346 described hereafter is associated with a skirt 323 in order to avoid that a quantity of powder is ejected outside of the funnel 346 when the valves close under the effect of the return spring 60. The skirt 323 makes it possible to redirect to the funnel the grains of powder ejected towards the front of the
15 separation device. The length of the analysis system from the separating element 327 up to the funnel is around 20 cm (centimetres).

According to the embodiment of the present invention, the separation device comprises six valves 344.
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As shown in figure 16, the expansion chamber 332 and the storage chamber 340 also form the conduits for guiding the powder to the valves 344. In order to enable the powder to slide in the conduits with a minimum of friction, the material used must be smooth and preferably conductive to avoid phenomena of static electricity. Thus, the
25 assembly formed by the expansion chamber 332, the storage chamber 340 and the valves 344 is produced by stereolithography. This 3D printing technique makes it possible to use a transparent material, TuskXC2700T which has mechanical characteristics similar to ABS (acrylonitrile butadiene styrene) and PBT (polybutylene terephthalate). Indeed, a part made of ABS may be replaced by a part made of Tusk of
30 same geometry in a mechanical system without disrupting the operation of said mechanical system.

The analysis system 310 also comprises a funnel 346 shown in figure 21. Thus, during the opening of the valves 344, the powder can escape towards the funnel 346.
35 The funnel 346 comprises a coaxial pipe 347 at the outlet of the funnel in order to be able to suck up the powder as indicated hereafter. As shown in figure 20, the funnel

346 also comprises maintaining teats 58 for the return springs 60 of the opening device 314 and a reinforcement to stiffen the maintaining teats 58. The funnel 346 also comprises different fixation tabs and tapped holes and the axis passage enabling the positioning of the funnel with respect to the separation device 312 and the valves 344.

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The analysis system 310 also comprises a weighing device or balance 316 shown in figure 11. Thus, the shape of the funnel 346 makes it possible to guide the powder to the balance 316 to determine the weight of powder that has flowed in a determined conduit.

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The analysis system also comprises a suction device 348 shown in figures 11 and 22 and capable of evacuating the powder present on the balance 316, after the measurements. The suction device 348 comprises a one-piece Venturi suction tube shown in figure 22 into which argon is injected to carry out the sucking up of the powder.

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The analysis system may be assembled within a box such as a casing (not shown).

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While in operation, the analysis system 310 is placed in the working enclosure of an additive manufacturing machine according to the prior art. The analysis system 310 must be within range of the nozzle 10, which is movable. More specifically, the nozzle 10 must be situated above the analysis system 310, in a centred manner. Thus, the analysis system 310 is suited to operating with the device for detecting the laser beam 100 and the cone centring device 200 in a manner prior to the operation of said analysis system. Thus, before the start of the analysis of the metal powder jet, the laser beam is situated above the analysis system in a centred manner with the cones also centred. The operation of the analysis system described below then makes it possible to determine if the centring of the cones is satisfactory to obtain a homogeneous powder jet.

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During an analysis, the nozzle 10 is positioned above the analysis system, and above the centre of the separating element 326, as shown in figure 13 which represents a schematic diagram. The initial powder jet 21 coming from the nozzle 10 then penetrates into the analysis system 310 through the upper part of the separating element 326 which has the role of dividing or separating the initial powder jet into a

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finite number of portions of powder jet. The initial powder jet 21 pours out for a determined duration.

5 When the initial powder jet 21 has been divided, each portion of powder jet continues its trajectory in a specific conduit, with determined dimensional characteristics to favour a flow without turbulence. In each conduit, the portion of powder jet covers the expansion chamber 332 in order to allow the gas contained in the powder jet 21 to escape.

10 The quantity of powder is next stopped by the mechanical system of valves 344 to be stored in the storage chamber 340. Below these mechanical valves 344 is found the balance 316 which makes it possible to weigh each portion of powder as shown in figure 11.

15 To initialise the system before the step of weighing on the balance 316, all the valves are opened at the same time for several seconds in the presence of a powder jet. Then, all the valves are closed at the same time. Next, the powder fills the storage tubes for a defined duration of the order of two to five minutes as a function of the adjusted flow rate.

20 The weighing cycle starts with the opening of a first valve 344 which frees the powder which reaches the balance 316 for a weighing. The value is recorded in a database and attached to the conduit, which corresponds to the first zone for sampling the powder jet.

25 A second mechanical valve 344 opens in its turn, and a second weighing is carried out. The value thus recorded corresponds to the sum of the first portion with the second portion. The difference in the two makes it possible to obtain the value specific to the second sampling portion.

30 This cycle is repeated as many times as there are powder separation portions. In the end, each portion of powder has been weighed, and it is thus possible to compare the quantity of powder in each portion of the powder jet. In addition, the sum of each portion makes it possible to obtain the total weight of the quantity of powder sampled during a defined time. The flow rate of powder is then obtained.

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Once the cycle has finished, the powder arranged on the balance is evacuated by the suction device 348.

Figures 23a, 23b and 23c show, according to a schematic diagram, a front view of the flow of the powder jet into a separating element 328 comprising, according to another embodiment, two separation walls in order to separate the initial powder jet into two powder jets. The separating element 328 is situated at different heights z with respect to the flow of the initial powder jet. In figure 23a, the separating element 328 is situated at a distance z_1 from the nozzle 10 which brings about the formation of two portions of powder jet 350, 352. In figure 23b, the separating element 328 is situated at a distance z_2 from the nozzle 10 which brings about the formation of two portions of powder jet 354, 356. In figure 23c, the separating element 328 is situated at a distance z_3 from the nozzle 10 which brings about the formation of two portions of powder jet 358, 360.

Thus, the technical effect of the analysis system 310 according to the invention is notably to enable a characterisation of the powder jet as a function of different heights.

The technical effect of the analysis system 310 according to the invention is also to control the homogeneity of the powder jet in order to validate the correct centring of the cones of the nozzle. The homogeneity measurement is carried out by measuring the quantity of powder that has flowed in each conduit.

Finally, the analysis system 310 also makes it possible to determine the mass flow rate of the powder jet.

The analysis system also comprises an electronic control device (not shown) in order to control the motor making it possible to open the valves 344 and to acquire the data of the balance 316 to perform the calculations of the different weighing operations.

The assembly formed by the device for detecting the laser beam, the cone centring device and the powder jet analysis system is thus placed inside the additive manufacturing machine and only necessitates placing the deposition nozzle above the device for detecting the laser beam to start the process of detecting the laser beam. Next, the cone centring device may be used, thanks to a known distance between the centre of the cone centring device 200 and the calibrated hole 111, then the powder jet analysis system is used in its turn.

Figures 8, 9a, 13, 17 and 23a, 23b and 23c represent schematic diagrams and are simplified compared to the other figures representing the possible embodiments of the invention in question.

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The embodiments described previously are indicated as examples uniquely.

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CLAIMS

1. Device (100) for detecting a position of a laser beam (15) with a determined diameter and emitted by a laser of an additive manufacturing machine, said detection device (100) comprising an upper part (102) comprising a scanning zone (108) of the laser beam (15), said scanning zone (108) being situated below a circular central opening (107) in an upper surface (101) of the upper part (102) and comprising a circular hole (111) at a centre of the upper surface, wherein the circular hole has a diameter essentially equal to the diameter of the laser beam and with a determined position; wherein the upper part (102) further comprises a first (104) and a second (106) element, the second element (106) comprising the circular hole (111), and the first (104) and the second (106) element being configured such that reflections of the laser beam (15) between the first and the second element (104, 106) are infinite to dissipate energy of the laser beam (15),

the detection device (100) comprising a lower part (103), the lower part (103) comprising at least one sensor (114) for capturing a part of an energy transmitted by the laser beam (15) an graphite martyr plate (54) to absorb a remaining part of the energy transmitted by the laser beam (15);

such that when the laser beam (15) scans the scanning zone (108) according to a plurality of positions, the sensor (114) captures a part of the energy transmitted by the laser beam for each position, the part of the transmitted energy being maximum when the laser beam (15) is aligned with the circular hole (111).
2. Detection device according to claim 1, the sensor (114) comprising one photodiode.
3. Detection device according to claim 2, the sensor (114) comprising three photodiodes.
4. Detection device according to any one of the preceding claims, the first element (104) comprising vents (110).
5. Method for detecting a position of a laser beam (15) emitted by a laser of an additive manufacturing machine comprising the following steps performed by a

detection device according to any one of the preceding claims:

- emission of a laser beam (15) with a determined diameter;
- scanning of the laser beam (15) over the scanning zone (108) comprising a circular hole (111) with a diameter essentially equal to the diameter of the laser beam (15) and with a determined position, said scanning comprising a plurality of positions of the laser beam (15);
- detection of a part of the energy transmitted by the laser beam (15) for each position of the laser beam (15) during the scanning;
- emission of an electrical signal corresponding to a quantity of energy detected for each position of the laser beam (15) during the scanning;
- determination of a maximum electrical signal value;
- search for a time t corresponding to the position of a manufacturing head for the maximum electrical signal value;
- determination of the position of the laser beam (15).