

ABSTRACT
WHEELED ROLLING ROBOT

The invention relates to a rolling robot (1000) comprising wheels (1010, 1020) articulated about two parallel axes of rotation and a chassis having an essentially planar surface between the two axes of rotation, characterized in that the surface of the chassis exhibits, between the two axes of rotation, a groove (2010, 2020) running parallel to the axes of rotation to allow the robot (1000) to pass over an obstacle that exhibits a corner without that corner striking the chassis between the axes of rotation.

FIG 4