

Description

This invention relates to digital FM recording of a signal, such as the digital recording of an FM video signal

5 BACKGROUND

Analog generation of an FM video signal for recording presents various problems, including aging of components, tolerances in the circuitry generating the carrier and the carrier deviation, and pre-emphasis circuitry which vary significantly from the nominal. Digital FM modulating techniques have, heretofore, been cumbersome requiring the use of a substantial amount of circuitry and excessive memory storage. A conventional circuit for digital FM can for example be found in EP-A- 0 068 535.

A feature of the invention is a digital synthesizer technique and system which avoids the disadvantages of analog modulation, without introducing the complexity of typical digital signal processing.

15 SUMMARY

The invention is characterized by the appended claims.

A digital synthesizer generates a sequence of digital output samples representing modulation of a carrier by an input signal. The synthesizer is supplied with digital input samples representing the input signal. A calculator stage, responsive to the digital input samples calculates a sequence of pulse periods defining a pulse duration modulated signal that represents the modulation of the carrier by the input signal. An output sample generating stage operates on the sequence of pulse periods for generating the sequence of digital output samples representing the carrier modulated output signal.

25 BRIEF DESCRIPTION OF THE DRAWING

FIGURES 1a and 1b illustrate exemplary waveforms of a modulating input signal and a corresponding modulated output signal, respectively, including representative digital samples in both signals, derived in accordance with inventive aspects;

FIGURE 2 illustrates a flowchart of an inventive method used to calculate the pulse periods of the FM modulated signal illustrated in FIGURE 1b;

FIGURE 3 illustrates a flowchart for calculating FM output samples from the calculated values of the FM signal pulse periods; and

FIGURE 4 illustrates in block diagram form an FM record system which incorporates an inventive digital FM synthesizer technique.

DESCRIPTION OF THE INVENTION

In an FM modulated system, the FM modulated output signal, $FM(t)$, may be defined as

$$FM(t) = \sin\{2\pi * \text{Freq}(t) * t\} \quad \text{Eq. (1)}$$

, where an instantaneous frequency, $\text{Freq}(t)$, may be defined by

$$\text{Freq}(t) = \text{CAR} + \text{DEV} * M(t) \quad \text{Eq. (2)}$$

, where $M(t)$ is the modulating signal, CAR is the carrier frequency, and DEV is the deviation.

The solid line waveform of FIGURE 1a illustrates the waveform of an exemplary video signal, $V(t)$, such as a luminance signal, that is to be FM modulated onto a carrier prior to recording. The solid line waveform of FIGURE 1b illustrates the resultant FM modulated signal, $FM(t)$.

A digital synthesizing technique according to the invention may be used to generate $FM(t)$ from $V(t)$. The synthesis method interprets the FM signal as a pulse duration modulated signal. That is to say, the FM output signal of FIGURE 1b may be considered as a pulse sequence, 1,2,3, j..., each pulse having a period, $T(j)$, that is determined by the modulating video signal $V(t)$, and by the various FM system parameters such as carrier frequency, CAR, and deviation, DEV. Additionally, the signal may be considered a bipolar one, in the sense that the pulses alternate in polarity.

To ascertain the value of each pulse period $T(j)$ using a closed form equation is possible for only a few simple modulating signals. In general, the modulating video signal $V(t)$ is much too complex for closed form expression.

Advantageously according to an inventive arrangement of a digital synthesizing technique, one need consider only the average frequency, Freq_{AV} , of $FM(t)$ over an interval Δt . Taking Equation (2) into account, the average frequency, Freq_{AV} , may be defined as

$$\text{Freq}_{AV} = \text{CAR} + \text{DEV} * V_{AV} \quad \text{Eq. (3)}$$

, where

$$V_{AV} = \frac{1}{\Delta t} \int_{\Delta t} V(t) dt \quad \text{Eq. (4)}$$

, i.e. V_{AV} is the average value of the modulating video signal $V(t)$ over the interval Δt .

Because the amplitude of the FM modulated output signal, $\text{FM}(t)$, of FIGURE 1b is constant, only the frequency, i.e. the time $T(j)$ between zero crossings, is the variable of importance. For this reason, the smallest time interval, Δt , to consider in evaluating Equations (3) and (4), for any given pulse j , is the corresponding pulse period $T(j)$.

In accordance with an inventive feature, the calculation of the intervals $T(j)$ is greatly simplified by providing discrete time samples, $s(i) = s_1, s_2, s_3, \dots$, of the modulating video signal $V(t)$, having corresponding sampled values $V_1, V_2, V_3, \dots$, as illustrated in FIGURE 1a. The minimum rate, $1/\tau_s$, is determined by the Nyquist criterion in accordance with the highest frequencies of the video signal $V(t)$ that are to be recorded, e.g. 3 megahertz in a VHS system. Advantageously, this rate, which establishes the sampling speed requirements of the analog-to-digital converter, may be significantly lower than the output sample rate of the FM modulated signal that is applied to the digital-to-analog converter.

Note that the number of samples, $K(j)$, that occur within any given output pulse period $T(j)$ varies as the frequency of the FM modulated signal $\text{FM}(t)$ varies. Thus, as illustrated in FIGURES 1a and 1b, the number of samples in the pulse period $T(2)$ is $K(2)=2$, while the number of samples in the interval $T(4)$ is $K(4)=3$.

To calculate a given pulse period $T(j)$ from the sampled values of the modulating video signal $V(t)$, one may use Equations (3) and (4), to equate the reciprocal of the pulse period to twice the average frequency, Freq_{AV} , when averaged over that pulse period, i.e. when averaged over the time $\Delta t=T(j)$. Thus

$$1/T(j) = 2 * \text{Freq}_{AV}(\Delta t = T(j)) \quad \text{Eq. (5)}$$

By having available discrete samples of the modulating signal, the integral expression used in calculating the average modulating signal V_{AV} of Equation (4) may be approximated by a piecewise summation over the interval $T(j)$. When this done, the average modulating signal may be taken as, $V_{AV\Sigma(j)}$, over the interval $T(j)$, resulting in

$$1/T(j) = 2 * [\text{CAR} + \text{DEV} * V_{AV\Sigma(j)}] \quad \text{Eq. (6)}$$

where

$$V_{AV\Sigma(j)} = \frac{\tau_R(j)}{\tau_\Sigma(j)} * V(j-1, K(j)-1) + \frac{1}{\tau_\Sigma(j)} * \sum_{n=1}^{K(j)-1} [\tau_s * V(j, n)] + \frac{\tau_L(j)}{\tau_\Sigma(j)} * V(j, K(j))$$

Equation (7)

, and

$$\tau_\Sigma(j) = \tau_R(j) + \tau_s * [K(j) - 1] + \tau_L(j) \quad \text{Eq. (8)}$$

; where, in accordance with the notations shown in FIGURES 1a and 1b,

$V(j, n)$ = the n -th sampled value within a given pulse period $T(j)$, of the baseband modulating video signal $V(t)$, where n is a counter index, initially set equal to 1;

$K(j)$ = the number of samples in the output pulse period $T(j)$;

$\tau_R(j)$ = the residual time from the first (left-most) zero crossing point of the continuous-time FM modulated output signal $\text{FM}(t)$ of a given pulse period $T(j)$ to the time of the first sampled value, $V(j, n=1)$, of the modulating video signal within that period;

$\tau_L(j)$ = the time from the last sampled value, $V(j, K(j))$, of the modulating video signal within the period $T(j)$ to the second (right-most) zero crossing point of $\text{FM}(t)$ of that period;

τ_s = the sampling period of the baseband modulating video signal $V(t)$.

As an example, take the 4th pulse period $T(j=4)$ of FIGURES 1a and 1b. Four sampled values of video

signal $V(t)$ are needed. Three of the sampled values, $V(4,1)$, $V(4,2)$, and $V(4,3)$, are found in the 4th interval, (K equals 3), and the remaining sampled value is the last sampled value of the previous pulse period, sample $V(3,2)$.

The average value V_{AVZ} of the modulating video signal in the 4th pulse period is computed in accordance with Equation (7):

$$V_{AVZ}(4) = \frac{\tau_R(4)}{\tau_Z(4)} * V(3,2) + \frac{\tau_S}{\tau_Z(4)} * [V(4,1) + V(4,2)] + \frac{\tau_L(4)}{\tau_Z(4)} * V(4,3) \quad \text{Eq.(9)}$$

A difficulty arises when one attempts to use Equations (6), (7) and (8) to calculate a sequence of output pulse periods $T(j)$ of FIGURE 1b, given only the sequence of input samples $s(i)$ of the modulating video signal $V(t)$ in FIGURE 1a. To directly calculate a given pulse period $T(j)$ using these equations requires a priori knowledge of the end point of the period itself and a knowledge of the total number of samples $K(j)$ of $V(t)$ falling within that period.

To overcome this difficulty, an iterative process is used which maintains a running, average period, $t_{avg}(j,h)$, over the first h samples occurring in a given pulse j . Initially h is set to 1 at the beginning of the calculation of a given pulse period $T(j)$, and is then incremented by 1 to include another sample for use in another iteration when a new value of the running average period $t_{avg}(j,h)$ is calculated.

This procedure is repeated until the inclusion of another sampling interval τ_S results in the total time, $t_{sum} + \tau_S$, exceeding the running average period $t_{avg}(j,h)$, where t_{sum} is calculated from the beginning-point zero crossing of the pulse to the time of the current input sample. This indicates that by adding an additional sample interval, the end-point zero crossing of the current pulse period has been exceeded. From this fact, one may conclude that the current value of the running average period, $t_{avg}(j,h)$, equals the pulse period $T(j)$, and that the total number of samples $K(j)$ in the pulse period equals the current value of h .

To calculate the running average period $t_{avg}(j,h)$, consider the fact that Equations (6), (7) and (8), are valid expressions (once certain variables are suitably redefined) for any number of samples h . Thus one obtains

$$\frac{1}{2t_{avg}(j,h)} =$$

Eq.(10)

$$CAR + \frac{DEV}{\tau_R(j) + (h-1)*\tau_S + \tau_L(j,h)} * \left\{ \tau_R(j)*V(j-1,K(j-1)) + \tau_S * \sum_{n=1}^{h-1} V(j,n) + \tau_L(j,h)*V(j,h) \right\}$$

, where

$\tau_R(j)$ = the residual time, if any, that is present from the last zero crossing of the continuous-time output signal to the first output sample point in the current output interval;

$\tau_L(j,h)$ = the remaining time in the current output interval;

h = a counter index number indicating the number of input samples of $V(t)$ found in the current output interval;

In order to simplify notation, introduce the running time variable

$$\tau_{SUM}(j,h-1) = \tau_R(j) + (h-1) * \tau_S \quad \text{Eq.(11)}$$

, used to determine if enough discrete-time has passed to complete a full pulse period $T(j)$, and further introduce the variable

$$V_{AVG}(j,h-1) = \frac{\tau_R(j)*V(j-1,K(j-1)) + \tau_S * \sum_{n=1}^{h-1} V(j,n)}{\tau_{SUM}(j,h-1)} \quad \text{Eq.(12)}$$

The variable $V_{AVG}(j, h-1)$ may be viewed as an average value of the modulating signal $V(t)$, averaged in time from the beginning of the pulse period to a point that ends at sample $h-1$, i.e. averaged in time over the time $\tau_{SUM}(j, h-1)$. This is illustrated in FIGURE 1a, for the 4th pulse period that contains input samples $s7$, $s8$ and $s9$, preceded by the sample $s6$, the last sample of the previous pulse period.

Assume that the iterative process has proceeded to the point where τ_{SUM} and V_{AVG} have been calculated using the samples through sample $h-1=2$, i.e., through the 2nd sample, sample $s8$. Based on Equation (11), the accumulated running time, $\tau_{SUM}(4,2)$, from the beginning of the 4th pulse interval to the 3rd sample $s9$, is equal to $\tau_R(4) + 2\tau_s$. The discrete-time average value $V_{AVG}(4,2)$ of the modulating signal averaged over the accumulated running time is the total of the 3 areas shown in hatching in FIGURE 1a divide by τ_{SUM} . The sample values used in the calculation includes the last sample, $s6$, in the previous pulse period, as well as the first two samples, $s7$ and $s8$, in the current period.

Once V_{AVG} has been calculated, the running average period $t_{avg}(j, h)$ may be obtained in the following manner. Equation (10) may be rewritten as

$$\frac{1}{2t_{avg}(j, h)} = CAR + \frac{DEV}{\tau_{SUM}(j, h-1) + \tau_L(j, h)} * [\tau_{SUM}(j, h-1) * V_{AVG}(j, h-1) + \tau_L(j, h) * V(j, h)] \quad \text{Eq.(13)}$$

The discrete-time average value V_{AVG} was calculated using a rectangular approximation of $V(t)$ between two actual sample points. Other approximations, such as a straight line connection between two sample points, may be used, at the possible expense of having a more complicated calculation algorithm.

It is important to note that a zero crossing of the output signal must occur when $\tau_{SUM} > t_{avg}$. The instantaneous frequency is not known exactly until this condition is met. It is possible however to determine if a zero crossing should occur between two sample times $t=t_1$ and $t = t_1 + \tau_s$ by evaluating t_{avg} at $t=t_1$. For example, in FIGURES 1a and 1b, a zero crossing occurs between samples $s9$ and $s10$. To determine that such a zero crossing has occurred, it is necessary to note that

$$\tau_L(j, h) = t_{avg}(j, h) - \tau_{SUM}(j, h-1) \quad \text{Eq.(14)}$$

, resulting in

$$t_{avg}(j, h) = \frac{.5 + DEV * \{\tau_{SUM}(j, h-1) * [V(j, h) - V_{AVG}(j, h-1)]\}}{CAR + DEV * V(j, h)} \quad \text{Eq.(15)}$$

Thus at any value of h , the values of $\tau_{SUM}(j, h-1)$, $V_{AVG}(j, h-1)$ and $t_{avg}(j, h)$ can be calculated from the sampled input, given that CAR and DEV are known numeric constants. It should be noted that there are no input sample values which can cause $t_{avg}(j, h)$ to be less than $\tau_R(j) + \tau_s$.

After $t_{avg}(j, h)$ is calculated, it is necessary to determine whether or not $t_{avg}(j, h) > \tau_R(j) + (h-1)\tau_s$. If it is greater, then a new value of τ_{SUM} and V_{AVG} is calculated and h is incremented by 1.

If $\tau_{SUM}(j, h-1) + \tau_s > t_{avg}(j, h)$, then it is necessary to store 3 values in an output memory queue. These are $t_{avg}(j, h)=T(j)$, $h=K(j)$ and the residual time $\tau_R(j)$. These values are used in conjunction with a relatively small capacity sine ROM lookup table to calculate discrete-time values of the FM modulated output signal, as will be later described.

To calculate the next pulse period $T(j+1)$, it is necessary to calculate a new value of the residual time, $\tau_R(j+1)$, for the next output pulse, pulse $j+1$. The new value is $\tau_R(j+1)=\tau_{SUM}(j, h-1)+\tau_s-T(j)$. After the new value of $\tau_R(j+1)$ is calculated, h is reset to 1. However, if τ_R is ever 0, for example, if $\tau_R(j+1)=0$ then h is set to 2. After these data updating steps have been performed, the process of evaluating the next running average period $t_{avg}(j+1, h)$ is then initiated.

A flowchart describing the above procedure is given in FIGURE 2. It should be noted that for initialization purposes the first output pulse, pulse $j=1$ of FIGURE 1b, is arbitrarily chosen as a positive pulse and phased relative to the first input sample $s1$ so as to set the first residual time $\tau_R(j=1) = 0$. Any subsequent residual time can then be determined once its preceding pulse period has been calculated.

Discrete-time values, $FM(j, n)$, of the FM modulated output signal, shown in FIGURE 1b, may be calculated for each pulse j , based on the values of $T(j)$, $\tau_R(j)$ and $K(j)$ stored in the output memory queue. The equation for $FM(j, n)$ is

$$FM(j, n) = -SGN(j) * \sin\left\{\frac{\pi}{T(j)} * [\tau_R(j) + (n-1) * \tau_s]\right\} \quad \text{Eq.(16)}$$

for $n=1, 2, \dots, K(j)$, and where $SGN(j)$ is the sign function, i.e. (-1) raised to the j -th power. The change in polarity of alternate output pulses introduced by the sign function is indicative of the quantization of the output signal.

The values of $FM(j, n)$ are then supplied to a digital-to-analog converter for generating the continuous-time FM modulated output signal $FM(t)$ of FIGURE 1b.

It may be advantageous to operate the digital-to-analog converter in the modulator output stage at a faster rate, $1/\tau_{DA}$, than the rate, τ_s , for which input samples $s(i)$ are being generated.

Equation (16) is then modified to the following

$$FM(j,p) = -SGN(j) * \sin\left\{\frac{\pi}{T(j)} * [p * \tau_{DA} + \tau_0(j)]\right\} \quad \text{Eq. (17)}$$

for $p=0,1,2,\dots$. The time $\tau_0(j)$ represents the residual time between the first zero crossing instant of the j -th output pulse and the occurrence of the first computed output sample $FM(j,0)$ in that pulse period. For initialization purposes, the residual time $\tau_0(1)$ of the first pulse is set to 0.

When the counter variable p has been incremented to the point where a new pulse period is being entered, a new value $T(j+1)$ for the next output pulse period is fetched from memory. The counter variable p is reset to 0 before beginning the calculation of a new sequence of output samples in the pulse period $j+1$. Storing in memory of the calculated values $\tau_R(j)$ and $K(j)$ is unnecessary since they are not being used for the calculation of the output samples $FM(j,p)$. A flowchart of the steps taken to calculate the sequence of output samples $FM(j,p)$ is provided in FIGURE 3.

The digital FM synthesizing technique just described, in accordance with various inventive aspects, may be used to record an input signal on a recording medium. For example, this technique may be used to record a luminance, chrominance, or composite video signal on video tape.

The circuit is compatible with all FM record standards (NTSC, PAL and SECAM for VHS or SVHS), with the only restriction being the sampling rate of the A/D and the conversion rate of the D/A. This greatly reduces the parts count external to the IC's in, e.g., a multistandard recorder.

A block diagram of a VCR record system 30, including a digital FM synthesizer 10 embodying the invention, is shown in FIGURE 4. The clock input to the digital part of the system, f_{ck} , is greater than 25 megahertz for PAL in the SVHS standard and is approximately 20 megahertz for PAL in the VHS standard. A low pass filter 11 may be used to eliminate frequencies in the input signal V_{in} above the Nyquist frequency of analog-to-digital converter, A/D 12 (10 megahertz). The A/D could actually operate at approximately 10 megahertz clock frequency, f_1 , for video applications without loss of signal fidelity. Input signal V_{in} may be, illustratively, an analog baseband luminance signal.

A pre-emphasis filter 13 receives the digitized input signal. The filter may be constructed as a standard Infinite Impulse Response or Finite Impulse Response digital filter which approximates the pre-emphasis function for the recording system being used (1.3 microsecond for PAL VHS).

The output of pre-emphasis filter 13 is applied to a clipping circuit 14, which is used to limit the minimum and maximum frequency of the output FM signal. This is easily implemented with a lookup table on the output data from the digital filter section. This assumes that video clamping and AGC are applied to the signal, by circuitry not shown, prior to filtering. Other conventional processing of the signal prior to entering the modulator stage are also omitted from the figure.

A digital FM modulator 15, embodying the invention, receives the digital samples $s(i)$ from the output of clipping circuit 14 and generates digital FM output samples, $FM(j,n)$ or $FM(j,p)$, calculated in accordance with the digital synthesizing techniques described above. The digital FM modulator stage is similar in concept to an IIR filter because it uses a group of time domain samples to calculate the output signal. This implies a fixed delay from the input to the output.

Modulator 15 is arranged in three stages. The first stage 16 receives the digital input samples $s(i)$ and calculates the sequence of output pulse periods $T(j)$ and the associated sequences for the residual times $\tau_R(j)$ and the sample counts $K(j)$. The second stage 17, a memory stage, stores the values of $T(j)$, $\tau_R(j)$ and $K(j)$. These values are then fetched by the last stage 18, the FM modulator stage, to generate the sequence of digital FM modulated output samples $FM(j,n)$.

Memory stage 17 functions as a first-in-first-out, FIFO, queue. The queue prevents the output calculator in FM modulator stage 18 from running out of values of $T(j)$, $\tau_R(j)$ and $K(j)$ when the current output frequency is higher than the next, i.e. during a maximum white to maximum black transition. If modulator stage 18 calculates the output samples as samples $FM(j,p)$, in accordance with the algorithm of the flowchart of FIGURE 3, then memory stage 17 need store only the values of $T(j)$.

A digital-to-analog converter, D/A 19, operating at an output clock rate f_2 , converts the FM output samples from modulator stage 18 into an analog signal $FM(t)$. The FM signal is then sent to the VCR record electronics stage 20 for recording the signal on magnetic tape.

If the modulator stage operates at an output rate that is higher than the input sampling rate f_1 , e.g. at the D/A conversion rate f_2 , then the output rate must exceed $2 * (CAR + f_{max} + DEV/2)$, where f_{max} is the maximum frequency of the input modulating signal. There need be no direct relationship between the input sampling rate f_2 and the FM output conversion rate. This permits the use of an existing clock that is available in the VCR, e.g. of a clock operating at $4F_{sc} = 17.734476$ megahertz, when processing a PAL video signal.

Because the input sampling rate and the output conversion rate need not be directly related, the calculations of the pulse periods $T(j)$ may be performed at a comparatively low frequency (6-7 megahertz) while the output converter runs at a high frequency (4 times the input rate). This has two advantages. The more complex

stage which calculates the pulse periods may be implemented with higher resolution in order to preserve signal accuracy and fidelity. The output sine table, adders and D/A's do not require as much accuracy due to the over-sampling of the sine function. This reduces the complexity of the hardware required to implement the modulator.

- 5 The arrangements described above advantageously minimize calculation time, minimize the required memory space, and minimize the required analog bandwidth. Close tolerances are maintained on the carrier and deviation, to within the tolerances of the various clocks used by the system. Low input sampling rates and output D/A conversion rates are used, typically digital video rates. No external analog adjustments are required, resulting in minimal drift with aging, according to the clock drifts. Few unit-to-unit variations in pre-emphasis are found, and record format changes under software control is made possible.
- 10

Claims

- 15 1. Digital frequency synthesizer for generating a sequence of digital output samples representing frequency modulation of a carrier by an input signal, characterized in comprising:
means (12, 13, 14) for supplying digital input samples $s(i)$ of said input signal (V_{in}); means (16) responsive to said digital input samples for calculating a sequence of pulse periods defining a pulse duration modulated signal $T(j)$ that represents frequency modulation of a carrier by said input signal; and output sample means (17, 18) operating on said sequence of pulse periods for generating said sequence of digital output samples representing a carrier frequency modulated output signal corresponding to said pulse duration modulated signal.
- 20
2. Synthesizer of claim 1 further comprising means including record electronics (20), responsive to said digital output samples (FM), for recording a signal on a recording medium representative of said output signal.
- 25
3. Synthesizer of claim 2 wherein said recording medium is a video tape.
4. Synthesizer of claim 3 wherein said input signal comprises a luminance signal.
- 30
5. Synthesizer according to claim 1 wherein said output sample means generates a sequence of digital output samples that defines a sequence of output pulses having pulse widths corresponding to said sequence of pulse periods.
- 35
6. Synthesizer according to claim 5 wherein said sequence of output pulses is a sequence of pulses which alternate in polarity.
7. Synthesizer according to claim 1 wherein said digital output samples represents an FM carrier modulated output signal.
- 40
8. Synthesizer according to claim 7 wherein said sequence of output pulses is a sequence of pulses which alternate in polarity.
9. Synthesizer of claim 1 including a digital-to-analog converter (19) receiving said digital output samples (FM) for generating said carrier modulated output signal as an analog output signal.
- 45
10. Synthesizer of claim 9 including record electronics for recording said analog output signal on a recording medium.
11. Synthesizer of claim 10 wherein said recording medium is a video tape.
- 50
12. Synthesizer of claim 11 wherein said input signal comprises a luminance signal.
13. Synthesizer of claim 9 wherein said input signal (V_{in}) is an analog signal and said supplying means (12, 13, 14) comprises an analog-to-digital converter (12) receiving said analog input signal for supplying said digital input samples at an output thereof.
- 55
14. Synthesizer of claim 13 wherein the sampling rate of said analog-to-digital converter (12) is different than the sampling rate of said digital-to-analog converter (19).



stage which calculates the pulse periods may be implemented with higher resolution in order to preserve signal accuracy and fidelity. The output sine table, adders and D/A's do not require as much accuracy due to the over-sampling of the sine function. This reduces the complexity of the hardware required to implement the modulator.

- 5 The arrangements described above advantageously minimize calculation time, minimize the required memory space, and minimize the required analog bandwidth. Close tolerances are maintained on the carrier and deviation, to within the tolerances of the various clocks used by the system. Low input sampling rates and output D/A conversion rates are used, typically digital video rates. No external analog adjustments are required, resulting in minimal drift with aging, according to the clock drifts. Few unit-to-unit variations in pre-emphasis are found, and record format changes under software control is made possible.
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Claims

- 15 1. Digital frequency synthesizer for generating a sequence of digital output samples representing frequency modulation of a carrier by an input signal, characterized in comprising:
means (12, 13, 14) for supplying digital input samples $s(i)$ of said input signal (V_{in}); means (16) responsive to said digital input samples for calculating a sequence of pulse periods defining a pulse duration modulated signal $T(j)$ that represents frequency modulation of a carrier by said input signal; and output sample
20 means (17, 18) operating on said sequence of pulse periods for generating said sequence of digital output samples representing a carrier frequency modulated output signal corresponding to said pulse duration modulated signal.
- 25 2. Synthesizer of claim 1 further comprising means including record electronics (20), responsive to said digital output samples (FM), for recording a signal on a recording medium representative of said output signal.
3. Synthesizer of claim 2 wherein said recording medium is a video tape.
4. Synthesizer of claim 3 wherein said input signal comprises a luminance signal.
- 30 5. Synthesizer according to claim 1 wherein said output sample means generates a sequence of digital output samples that defines a sequence of output pulses having pulse widths corresponding to said sequence of pulse periods.
- 35 6. Synthesizer according to claim 5 wherein said sequence of output pulses is a sequence of pulses which alternate in polarity.
7. Synthesizer according to claim 1 wherein said digital output samples represents an FM carrier modulated output signal.
- 40 8. Synthesizer according to claim 7 wherein said sequence of output pulses is a sequence of pulses which alternate in polarity.
9. Synthesizer of claim 1 including a digital-to-analog converter (19) receiving said digital output samples (FM) for generating said carrier modulated output signal as an analog output signal.
- 45 10. Synthesizer of claim 9 including record electronics for recording said analog output signal on a recording medium.
11. Synthesizer of claim 10 wherein said recording medium is a video tape.
- 50 12. Synthesizer of claim 11 wherein said input signal comprises a luminance signal.
13. Synthesizer of claim 9 wherein said input signal (V_{in}) is an analog signal and said supplying means (12, 13, 14) comprises an analog-to-digital converter (12) receiving said analog input signal for supplying said digital input samples at an output thereof.
- 55 14. Synthesizer of claim 13 wherein the sampling rate of said analog-to-digital converter (12) is different than the sampling rate of said digital-to-analog converter (19).



15. Synthesizer of claim 13 wherein sampling rate of said analog-to-digital converter is slower than the sampling rate of said digital-to-analog converter.

16. Synthesizer according to claim 1 including means (17) for storing said sequence of pulse periods in a memory, said output sample means (17, 18) fetching said stored sequence from said memory as needed, so as to calculate the values of said digital output samples.

17. Synthesizer according to claim 1 wherein said calculating means calculates said sequence of pulse periods $T(j)$, $j=1, 2, 3, \dots$ that defines a sequence of pulses of said pulse duration modulated signal representing FM modulation of a carrier by said input signal, in accordance with the equation:

$$1/T(j) = 2 * [CAR + DEV * V_{AV\Sigma(j)}]$$

where

$$V_{AV\Sigma(j)} = \frac{\tau_R(j)}{\tau_\Sigma(j)} * V(j-1, K(j-1)) + \frac{1}{\tau_\Sigma(j)} * \sum_{n=1}^{K(j)-1} [\tau_s * V(j, n)] + \frac{\tau_L(j)}{\tau_\Sigma(j)} * V(j, K(j))$$

, and

$$\tau_\Sigma(j) = \tau_R(j) + \tau_s * [K(j) - 1] + \tau_L(j).$$

; where,

CAR = the FM carrier frequency;

DEV = the FM deviation;

$V(j, n)$ = the n -th one of said input samples within a given pulse period $T(j)$, where n is a counter index, initially set equal to 1;

$K(j)$ = the number of said input samples in the pulse period $T(j)$;

$\tau_R(j)$ = the residual time from the first zero crossing point of said pulse duration modulated signal of a given pulse period $T(j)$ to the time of the first one, $V(j, n=1)$, of said input samples within that period;

$\tau_L(j)$ = the time from the last one, $V(j, K(j))$, of said input samples within the period $T(j)$ to the second zero crossing point of said pulse duration modulated signal within that period; and

τ_s = the sampling period associated with said input samples.

18. Synthesizer according to claim 17 wherein said output sample means generates said sequence of digital output samples, $FM(j, n)$ in accordance with the equation:

$$FM(j, n) = -SGN(j) * \sin\left\{\frac{\pi}{T(j)} * [\tau_R(j) + (n - 1) * \tau_s]\right\}$$

19. Synthesizer according to claim 18 including means (17) for storing in a memory said sequence of pulse periods $T(j)$, a sequence of corresponding values $\tau_R(j)$ and a sequence of corresponding values $K(j)$, said output sample means fetching the three stored sequences from said memory as needed, so as to calculate the values of said digital output samples.

20. Synthesizer according to claim 1 wherein said output sampling means operates on said sequence of pulse periods $T(j)$, $j=1, 2, 3, \dots$, that defines a sequence of pulses of said pulse duration modulated signal representing FM modulation of a carrier by said input signal, to generate said sequence of digital output samples, $FM(j, p)$, in accordance with the equation:

$$FM(j, p) = -SGN(j) * \sin\left\{\frac{\pi}{T(j)} * [p * \tau_{DA} + \tau_0(j)]\right\}$$

, $p=0, 1, 2, \dots$, where

τ_{DA} = the sample interval between successive ones of said digital output samples, and

$\tau_0(j)$ = the residual time between the first zero crossing instant of the j -th pulse and the occurrence of the first computed output sample $FM(j, 0)$ in that pulse period.

21. Synthesizer according to claim 20 wherein the interval τ_{DA} is shorter than the sampling period associated with said input samples.



Patentansprüche

1. Digitaler Frequenzsynthesizer zur Erzeugung einer Sequenz von digitalen Ausgangsabtastwerten, welche die Frequenzmodulation eines Trägers durch ein Eingangssignal darstellen, dadurch gekennzeichnet, daß er folgendes umfaßt:
 5 Mittel (12, 13, 14) zur Lieferung von digitalen Eingangsabtastwerten $s(i)$ des Eingangssignals (V_{in}); Mittel (16) die auf die digitalen Eingangsabtastwerte zur Berechnung einer Sequenz von Impulsperioden ansprechen, welche ein impulsdauermoduliertes Signal $T(j)$ definiert, das die Frequenzmodulation eines Trägers durch das Eingangssignal darstellt; und Ausgangsabtastmittel (17, 18), welche die Sequenz von Impulsperioden zur Erzeugung der Sequenz von digitalen Ausgangsabtastwerten bearbeiten, welche ein trägerfrequenzmoduliertes Ausgangssignal darstellen, das dem impulsdauermodulierten Signal entspricht.
2. Synthesizer nach Anspruch 1, welcher ferner ein Mittel umfaßt, das eine Aufzeichnungselektronik (20) enthält, die auf die digitalen Ausgangsabtastwerte (FM) anspricht, zur Aufzeichnung eines Signals auf einem Aufzeichnungsmedium, welches das Ausgangssignal darstellt.
- 15 3. Synthesizer nach Anspruch 2, worin das Aufzeichnungsmedium ein Videoband ist.
4. Synthesizer nach Anspruch 3, worin das Eingangssignal ein Luminanzsignal umfaßt.
- 20 5. Synthesizer nach Anspruch 1, worin das Ausgangsabtastmittel eine Sequenz von digitalen Ausgangsabtastwerten erzeugt, die eine Sequenz von Ausgangsimpulsen mit Impulsbreiten definiert, welche der Sequenz von Impulsperioden entsprechen.
6. Synthesizer nach Anspruch 5, worin die Sequenz von Ausgangsimpulsen eine Sequenz von Impulsen ist, die in der Polarität wechseln.
- 25 7. Synthesizer nach Anspruch 1, worin die digitalen Ausgangsabtastwerte ein FM-trägermoduliertes Ausgangssignal darstellen.
- 30 8. Synthesizer nach Anspruch 7, worin die Sequenz von Ausgangsimpulsen eine Sequenz von Impulsen ist, die in der Polarität wechseln.
9. Synthesizer nach Anspruch 1, enthaltend einen Digital/Analog-Wandler (19), der die digitalen Ausgangsabtastwerte (FM) zur Erzeugung des trägermodulierten Ausgangssignals als analoges Ausgangssignal empfängt.
- 35 10. Synthesizer nach Anspruch 9, enthaltend eine Aufzeichnungselektronik zur Aufzeichnung des analogen Ausgangssignals auf einem Aufzeichnungsmedium.
11. Synthesizer nach Anspruch 10, worin das Aufzeichnungsmedium ein Videoband ist.
- 40 12. Synthesizer nach Anspruch 11, worin das Eingangssignal ein Luminanzsignal umfaßt.
13. Synthesizer nach Anspruch 9, worin das Eingangssignal (V_{in}) ein analoges Signal ist und das Zuleitungsmittel (12, 13, 14) einen Analog/Digital-Wandler (12) umfaßt, der das analoge Eingangssignal empfängt, um die digitalen Eingangsabtastwerte zu einem Ausgang zu leiten.
- 45 14. Synthesizer nach Anspruch 13, worin sich die Abtastgeschwindigkeit des Analog/Digital-Wandlers (12) von der Abtastgeschwindigkeit des Digital/Analog-Wandlers (19) unterscheidet.
- 50 15. Synthesizer nach Anspruch 13, worin die Abtastgeschwindigkeit des Analog/Digital-Wandlers langsamer als die Abtastgeschwindigkeit des Digital/Analog-Wandlers (19) ist.
16. Synthesizer nach Anspruch 1, enthaltend Mittel (17) zum Speichern der Sequenz von Impulsperioden in einem Speicher, wobei das Ausgangsabtastmittel (17, 18) die gespeicherte Sequenz nach Bedarf aus dem Speicher holt, um die Werte der digitalen Ausgangsabtastwerte zu berechnen.
- 55 17. Synthesizer nach Anspruch 1, worin das Berechnungsmittel die Sequenz von Impulsperioden $T(j)$, $j=1, 2, 3, \dots$, die eine Sequenz von Impulsen des impulsdauermodulierten Signals definiert, welches die FM-Mo-



dulation eines Trägers durch das Eingangssignal darstellt, nach folgender Gleichung berechnet:

$$1/T(j) = 2 * [CAR + DEV * V_{AV\Sigma}(j)]$$

wobei

$$V_{AV\Sigma}(j) = \frac{\tau_R(j)}{\tau\Sigma(j)} * V(j-1, K(j-1)) + \frac{1}{\tau\Sigma(j)} * \sum_{n=1}^{K(j)-1} [\tau_S * V(j, n)] + \frac{\tau_L(j)}{\tau\Sigma(j)} * V(j, K(j))$$

und

$$\tau\Sigma(j) = \tau_R(j) + \tau_S * [K(j) - 1] + \tau_L(j)$$

;wobei

CAR = die FM-Trägerfrequenz;

DEV = die FM-Abweichung;

$V(j, n)$ = der n. der Eingangsabstastwerte innerhalb einer bestimmten Impulsperiode $T(j)$, wobei n ein Zählindex ist, der zu Beginn auf gleich 1 eingestellt wird;

$K(j)$ = die Anzahl von Eingangsabstastwerten in der Impulsperiode $T(j)$;

$\tau_R(j)$ = die Restzeit von dem ersten Nulldurchgangspunkt des impulsdauermodulierten Signals einer bestimmten Impulsperiode $T(j)$ zu dem Zeitpunkt des ersten $V(j, n=1)$ der Eingangsabstastwerte in dieser Periode;

$\tau_L(j)$ = die Zeit von dem letzten $V(j, K(j))$ der Eingangsabstastwerte in der Periode $T(j)$ zu dem zweiten Nulldurchgangspunkt des impulsdauermodulierten Signals in dieser Periode; und

τ_S = die zu den Eingangsabstastwerten zugehörige Abtastperiode.

18. Synthesizer nach Anspruch 17, worin das Ausgangsabtastmittel die Sequenz von digitalen Ausgangsabtastwerten $FM(j, n)$ nach folgender Gleichung erzeugt:

$$FM(j, n) = -SGN(j) * \sin\left\{\frac{\pi}{T(j)} * [\tau_R(j) + (n-1) * \tau_S]\right\}$$

19. Synthesizer nach Anspruch 18, enthaltend Mittel (17) zum Speichern der Sequenz von Impulsperioden $T(j)$, einer Sequenz von entsprechenden Werten $\tau_R(j)$ und einer Sequenz von entsprechenden Werten $K(j)$ in einem Speicher, wobei das Ausgangsabtastmittel die drei gespeicherten Sequenzen nach Bedarf aus dem Speicher holt, so daß die Werte der digitalen Ausgangsabtastwerte berechnet werden.

20. Synthesizer nach Anspruch 1, worin das Ausgangsabtastmittel die Sequenz von Impulsperioden $T(j)$, $j=1, 2, 3, \dots$, bearbeitet, welche eine Sequenz von Impulsen des impulsdauermodulierten Signals definiert, welches die FM-Modulation eines Trägers durch das Eingangssignal darstellt, um die Sequenz von digitalen Ausgangsabtastwerten $FM(j, p)$ nach der folgenden Gleichung zu erzeugen:

$$FM(j, p) = -SGN(j) * \sin\left\{\frac{\pi}{T(j)} * [p * \tau_{DA} + \tau_0(j)]\right\}$$

$p=0, 1, 2, \dots$, wobei

τ_{DA} = das Abtastintervall zwischen aufeinanderfolgenden der digitalen Ausgangsabtastwerte, und

$\tau_0(j)$ = die Restzeit zwischen dem ersten Nulldurchgangszeitpunkt des j. Impulses und dem Auftreten des ersten berechneten Ausgangsabtastwertes $FM(j, 0)$ in dieser Impulsperiode.

21. Synthesizer nach Anspruch 20, worin das Intervall τ_{DA} kürzer als die Abtastperiode ist, welche zu den Eingangsabtastwerten gehört.

Revendications

1. Synthétiseur numérique de fréquence pour la génération d'une séquence de valeurs d'échantillonnage



numériques de sortie représentant la modulation de fréquence d'un porteur par un signal d'entrée, caractérisé en ce qu'il comprend:

des moyens (12, 13, 14) d'approvisionnement de valeurs d'échantillonnage numériques d'entrée $s(i)$ du signal d'entrée (V_{in}); un moyen (16) sensible à ces valeurs d'échantillonnage numériques d'entrée pour le calcul d'une séquence de périodes d'impulsions définissant un signal $T(j)$ modulé par la largeur d'impulsion, ce signal représentant la modulation de fréquence d'un porteur par le signal d'entrée; et des moyens d'échantillonnage de sortie (17, 18) agissant sur la séquence de périodes d'impulsions pour la génération de la séquence de valeurs d'échantillonnage numériques de sortie, ces valeurs représentant un signal de sortie modulé de fréquence d'un porteur, ce signal correspondant au signal modulé de la largeur d'impulsion.

2. Synthétiseur selon la revendication 1 comprenant en outre des moyens incluant une électronique d'enregistrement (20), sensible aux valeurs d'échantillonnage numériques (FM), pour l'enregistrement d'un signal sur un support d'enregistrement représentant le signal de sortie.
3. Synthétiseur selon la revendication 2, le support d'enregistrement étant une bande vidéo.
4. Synthétiseur selon la revendication 3, le signal d'entrée comprenant un signal de luminance.
5. Synthétiseur selon la revendication 1, les moyens d'échantillonnage de sortie générant une séquence de valeurs d'échantillonnage numériques définissant un train d'impulsions de sortie, ces impulsions ayant des largeurs d'impulsion correspondant à la séquence de périodes d'impulsions.
6. Synthétiseur selon la revendication 5, le train d'impulsions de sortie étant un train d'impulsions alternant en polarité.
7. Synthétiseur selon la revendication 1, les valeurs d'échantillonnage numériques de sortie représentant un signal de sortie modulé du porteur FM.
8. Synthétiseur selon la revendication 7, le train d'impulsions de sortie étant un train d'impulsions alternant en polarité.
9. Synthétiseur selon la revendication 1 incluant un convertisseur numérique/analogique (19), ce convertisseur recevant les valeurs d'échantillonnage numériques de sortie (FM) pour la génération du signal de sortie modulé du porteur comme signal de sortie analogique.
10. Synthétiseur selon la revendication 9, le support d'enregistrement étant une bande vidéo.
11. Synthétiseur selon la revendication 10, le support d'enregistrement étant une bande vidéo.
12. Synthétiseur selon la revendication 11, le signal d'entrée comprenant un signal de luminance.
13. Synthétiseur selon la revendication 9, le signal d'entrée (V_{in}) étant un signal analogique et les moyens d'approvisionnement (12, 13, 14) comprenant un convertisseur analogique/numérique (12) recevant ce signal d'entrée analogique pour guider les valeurs d'échantillonnage numériques d'entrée à une sortie.
14. Synthétiseur selon la revendication 13, la cadence d'impulsions du convertisseur analogique/numérique (12) étant différente de la cadence d'impulsions du convertisseur numérique/analogique (19).
15. Synthétiseur selon la revendication 13, la cadence d'impulsions du convertisseur analogique/numérique étant plus lente que la cadence d'impulsions du convertisseur numérique/analogique.
16. Synthétiseur selon la revendication 1 incluant un moyen (17) de stockage de la séquence de périodes d'impulsions dans une mémoire, les moyens d'échantillonnage de sortie (17, 18) sortant de la mémoire la séquence stockée quand nécessaire, de manière à calculer les valeurs des échantillonnages numériques de sortie.
17. Synthétiseur selon la revendication 1, les moyens de calcul évaluant la séquence de périodes d'impulsions $T(j)$, $j=1, 2, 3, \dots$, cette séquence définissant un train d'impulsions du signal modulé de durée d'impulsion représentant la modulation FM d'un porteur par le signal d'entrée, selon l'équation suivante:



$$1/T(j) = 2 * [CAR + DEV * V_{AV\Sigma}(j)]$$

sachant que

$$V_{AV\Sigma}(j) = \frac{\tau_R(j)}{\tau\Sigma(j)} * V(j-1, K(j-1)) + \frac{1}{\tau\Sigma(j)} * \sum_{n=1}^{K(j)-1} [\tau_S * V(j, n)] +$$

$$+ \frac{\tau_L(j)}{\tau\Sigma(j)} * V(j, K(j))$$

,et

$$\tau\Sigma(j) = \tau_R(j) + \tau_S * [K(j) - 1] + \tau_L(j)$$

; sachant que,

CAR = fréquence du porteur FM.

DEV = déviation de FM

$V(j, n)$ = la n.ième valeur d'échantillonnage pendant une période d'impulsions donnée $T(j)$, de la bande de base de modulation du vidéosignal $V(t)$, n étant un index de comptage, initialement mis égal à 1;

$K(j)$ = le nombre d'échantillonnages dans la période d'impulsions de sortie $T(j)$;

$\tau_R(j)$ = le temps résiduel entre le premier point de passage par zéro (le plus à gauche) du signal de sortie modulé FM $FM(t)$ en temps continu d'une période d'impulsions donnée $T(j)$, et le temps de la première valeur d'échantillonnage, $V(j, n=1)$, du vidéosignal de modulation pendant cette période;

$\tau_L(j)$ = le temps entre la dernière valeur d'échantillonnage, $V(j, K(j))$, du vidéosignal de modulation pendant la période $T(j)$ et le second point de passage par zéro (le plus à droite) du FM(t) de cette période;

τ_S = la période d'échantillonnage de la bande de base de modulation du vidéosignal $V(t)$.

18. Synthétiseur selon la revendication 17, les moyens d'échantillonnage de sortie générant la séquence de valeurs d'échantillonnage numériques de sortie, $FM(j, n)$ selon l'équation suivante:

$$FM(j, n) = - \text{SGN}(j) * \sin\left\{\frac{\pi}{T(j)} * [\tau_R(j) + (n - 1) * \tau_S]\right\}$$

19. Synthétiseur selon la revendication 18 incluant un moyen (17) de stockage dans une mémoire de la séquence de périodes d'impulsions $T(j)$, une séquence de valeurs correspondantes $\tau_R(j)$ et une séquence de valeurs correspondantes $K(j)$, les moyens d'échantillonnage de sortie sortant de la mémoire les trois séquences stockées quand nécessaire, de manière à calculer les valeurs des échantillonnages numériques de sortie.

20. Synthétiseur selon la revendication 1, les moyens d'échantillonnage de sortie agissant sur la séquence de périodes d'impulsions $T(j)$, $j=1, 2, 3, \dots$, cette séquence définissant un train d'impulsions du signal modulé de durée d'impulsion représentant la modulation FM d'un porteur par le signal d'entrée, de manière à générer la séquence de valeurs d'échantillonnage numériques de sortie, $FM(j, p)$, selon l'équation suivante :

$$FM(j, p) = - \text{SGN}(j) * \sin\left\{\frac{\pi}{T(j)} * [p * \tau_{DA} + I]\right\}$$

, $p=0, 1, 2, \dots$, sachant que

τ_{DA} = intervalle d'échantillonnage entre les valeurs d'échantillonnage numériques de sortie se suivant, et

$\tau_0(j)$ = temps résiduel entre le premier instant de passage par zéro de la j.ième impulsion de sortie et l'occurrence d'échantillonnage de sortie calculé le premier, $FM(j, 0)$, dans cette période d'impulsions.

21. Synthétiseur selon la revendication 20, l'intervalle τ_{DA} étant plus court que la période d'échantillonnage associée avec les valeurs d'échantillonnage d'entrée.