

POSITION RECOGNITION METHOD AND POSITION RECOGNITION SYSTEM FOR VEHICLE

[Abstract]

The present invention relates to a position recognition method comprising
5 the steps of: measuring a space in a first direction by means of at least one
measurement device provided in a vehicle; recognizing a first marker by means of
the measurement means; computing first positional information of the vehicle;
acquiring map information; and specifying comprehensive positional information of
the vehicle, wherein the first marker includes a coordinate value of the first marker,
10 the first positional information is a coordinate value of the vehicle computed through
recognition of the first marker, and the step of specifying the comprehensive
positional information combines the first positional information of the vehicle with
the map information.

15 [Figure 5]