

Abstract

ASSISTANCE ROBOT

An assistance robot that assists standing and sitting operations of a care receiver by moving a holding member on a movement path in accordance with a usage state. The control device of the assistance robot includes a path setting section configured to, when a standing operation operation or a sitting operation has been entered as a requested operation, select one of a standing path or a sitting path that corresponds to the requested operation, or one of the standing path or the sitting path that does not correspond to the requested operation, based on a usage state including a current position of the holding member, and set the selected movement path as a reference path.

(FIG. 6)